# On the geometry of log-concave measures.

Galyna Livshyts

Kent State University

Kent State University, May 4, 2015.

◆□> ◆舂> ◆注> ◆注> □ 注

#### Chapters 2 and 3: Maximal Surface Area Chapter 4: Surface area of polytopes

Chapter 4: Surface area of polytopes Chapter 5: On the Gaussian concentration. Chapter 6: On the Gaussian Brunn-Minkowski inequality

# Chapters 2 and 3: Maximal Surface Area

イロト イヨト イヨト イヨト

= nac

# Classical Isoperimetric Inequality

### Isoperimetric Inequality

Let Q be a set in  $\mathbb{R}^n$ . Denote the boundary of Q by  $\partial Q$ . Let |Q| = 1. Question: How to minimize  $|\partial Q|$  (the surface area of Q)?

医下 不 医下

# Classical Isoperimetric Inequality

## Isoperimetric Inequality

Let Q be a set in  $\mathbb{R}^n$ . Denote the boundary of Q by  $\partial Q$ . Let |Q| = 1. Question: How to minimize  $|\partial Q|$  (the surface area of Q)?

Well-known Answer (Ancient greeks, Jakob Steiner in 1838, Jakob and Johann Bernoulli, Federer in 1969)

 $|\partial Q|$  is minimized when Q is a Euclidean ball.

< 3 >

# Classical Isoperimetric Inequality

## Isoperimetric Inequality

Let Q be a set in  $\mathbb{R}^n$ . Denote the boundary of Q by  $\partial Q$ . Let |Q| = 1. Question: How to minimize  $|\partial Q|$  (the surface area of Q)?

Well-known Answer (Ancient greeks, Jakob Steiner in 1838, Jakob and Johann Bernoulli, Federer in 1969)

 $|\partial Q|$  is minimized when Q is a Euclidean ball.



But if we replace the usual Lebesgue volume measure with another measure, the answer to that question may change!

# Gaussian isoperimetric type inequalities

## Gaussian Measure

The Standard Gaussian Measure  $\gamma_2$  on  $\mathbb{R}^n$  is the probability measure with density

$$\varphi_2(y) = \left(\frac{1}{\sqrt{2\pi}}\right)^n e^{-\frac{|y|^2}{2}}$$

.⊒...>

# Gaussian isoperimetric type inequalities

### Gaussian Measure

The Standard Gaussian Measure  $\gamma_2$  on  $\mathbb{R}^n$  is the probability measure with density

$$\varphi_2(y) = \left(\frac{1}{\sqrt{2\pi}}\right)^n e^{-\frac{|y|^2}{2}}$$

The surface area of a convex body Q with respect to continuous measure  $\gamma$  on  $\mathbb{R}^n$  is defined to be

$$\gamma(\partial Q) = \liminf_{\epsilon \to +0} \frac{\gamma((Q + \epsilon B_2^n) \setminus Q)}{\epsilon}.$$

# Gaussian isoperimetric type inequalities

## Gaussian Measure

The Standard Gaussian Measure  $\gamma_2$  on  $\mathbb{R}^n$  is the probability measure with density

$$\varphi_2(y) = \left(\frac{1}{\sqrt{2\pi}}\right)^n e^{-\frac{|y|^2}{2}}$$

The surface area of a convex body Q with respect to continuous measure  $\gamma$  on  $\mathbb{R}^n$  is defined to be

$$\gamma(\partial Q) = \liminf_{\epsilon \to +0} \frac{\gamma((Q + \epsilon B_2^n) \setminus Q)}{\epsilon}.$$

There is a convenient integral expression for  $\gamma_2(\partial Q)$ :

$$\gamma_2(\partial Q) = \left(\frac{1}{\sqrt{2\pi}}\right)^n \int_{\partial Q} e^{-\frac{|y|^2}{2}} d\sigma(y),$$

where  $d\sigma(y)$  stands for Lebesgue surface measure.

# Gaussian isoperimetric type inequalities

The Gaussian Isoperimetric inequality (Sudakov/Tsirelson and Borell in 1974)

Among all the sets of a fixed Gaussian volume, half-spaces have the smallest Gaussian surface area.

# Gaussian isoperimetric type inequalities

The Gaussian Isoperimetric inequality (Sudakov/Tsirelson and Borell in 1974)

Among all the sets of a fixed Gaussian volume, half-spaces have the smallest Gaussian surface area.



# Gaussian isoperimetric type inequalities

The Gaussian Isoperimetric inequality (Sudakov/Tsirelson and Borell in 1974)

Among all the sets of a fixed Gaussian volume, half-spaces have the smallest Gaussian surface area.



How to ask the reverse question?

# Gaussian isoperimetric type inequalities

The Gaussian Isoperimetric inequality (Sudakov/Tsirelson and Borell in 1974)

Among all the sets of a fixed Gaussian volume, half-spaces have the smallest Gaussian surface area.



### How to ask the reverse question?

By  $\mathcal{K}_n$  we denote the set of all convex bodies in  $\mathbb{R}^n$ . Let Q run over  $\mathcal{K}_n$ . What is the maximal Gaussian surface area of Q?

Gaussian reverse isoperimetric inequalities

• K. Ball in 1993 showed, that for any convex set  $Q \subset \mathbb{R}^n$ ,

 $\gamma_2(\partial Q) \leq Cn^{\frac{1}{4}}.$ 

医下 不良下

Gaussian reverse isoperimetric inequalities

• K. Ball in 1993 showed, that for any convex set  $Q \subset \mathbb{R}^n$ ,

$$\gamma_2(\partial Q) \leq Cn^{\frac{1}{4}}.$$

• F. Nazarov in 2003 showed sharpness of Ball's result by proving

$$0.28n^{\frac{1}{4}} \leq \max_{Q \in \mathcal{K}_n} \gamma_2(\partial Q) \leq 0.64n^{\frac{1}{4}}.$$

Gaussian reverse isoperimetric inequalities

• K. Ball in 1993 showed, that for any convex set  $Q \subset \mathbb{R}^n$ ,

$$\gamma_2(\partial Q) \leq Cn^{\frac{1}{4}}.$$

• F. Nazarov in 2003 showed sharpness of Ball's result by proving

$$0.28n^{\frac{1}{4}} \leq \max_{Q \in \mathcal{K}_n} \gamma_2(\partial Q) \leq 0.64n^{\frac{1}{4}}.$$

• D. Kane in 2010 showed, that for any polynomial level set the Gaussian surface area is bounded by  $\frac{d}{\sqrt{2}}$ , where d is the degree of the polynomial.

.⊒...>

Gaussian reverse isoperimetric inequalities

• K. Ball in 1993 showed, that for any convex set  $Q \subset \mathbb{R}^n$ ,

$$\gamma_2(\partial Q) \leq Cn^{\frac{1}{4}}.$$

• F. Nazarov in 2003 showed sharpness of Ball's result by proving

$$0.28n^{\frac{1}{4}} \leq \max_{Q \in \mathcal{K}_n} \gamma_2(\partial Q) \leq 0.64n^{\frac{1}{4}}.$$

D. Kane in 2010 showed, that for any polynomial level set the Gaussian surface area is bounded by d/√2, where d is the degree of the polynomial. It implied in particular, that for any ellipsoid the Gaussian surface area is bounded by √2 independently of the dimension.

Gaussian reverse isoperimetric inequalities

• K. Ball in 1993 showed, that for any convex set  $Q \subset \mathbb{R}^n$ ,

$$\gamma_2(\partial Q) \leq Cn^{\frac{1}{4}}.$$

• F. Nazarov in 2003 showed sharpness of Ball's result by proving

$$0.28n^{\frac{1}{4}} \leq \max_{Q \in \mathcal{K}_n} \gamma_2(\partial Q) \leq 0.64n^{\frac{1}{4}}.$$

D. Kane in 2010 showed, that for any polynomial level set the Gaussian surface area is bounded by d/√2, where d is the degree of the polynomial. It implied in particular, that for any ellipsoid the Gaussian surface area is bounded by √2 independently of the dimension.

Are there any other interesting measures for which it is natural to ask for Isoperimetric type inequalities?

4 E b

#### Chapters 2 and 3: Maximal Surface Area Chapter 4: Surface area of polytopes

Chapter 5: On the Gaussian concentration. Chapter 6: On the Gaussian Brunn-Minkowski inequality

### Log concave measures

### Definition of log concave measures

A Borel measure  $\mu$  on  $\mathbb{R}^n$  is called log concave, if for any compact sets  $A, B \subset \mathbb{R}^n$  and for any  $\lambda \in [0, 1]$ ,

$$\mu(\lambda A + (1-\lambda)B) \ge \mu(A)^{\lambda} \cdot \mu(B)^{1-\lambda}.$$

.⊒ →

#### Chapters 2 and 3: Maximal Surface Area Chapter 4: Surface area of polytopes Chapter 5: On the Gaussian concentration.

Chapter 5: On the Gaussian concentration. Chapter 6: On the Gaussian Brunn-Minkowski inequality

## Log concave measures

### Definition of log concave measures

A Borel measure  $\mu$  on  $\mathbb{R}^n$  is called log concave, if for any compact sets  $A, B \subset \mathbb{R}^n$  and for any  $\lambda \in [0, 1]$ ,

$$\mu(\lambda A + (1-\lambda)B) \ge \mu(A)^{\lambda} \cdot \mu(B)^{1-\lambda}.$$

### Log concave functions

We say, that a function  $f : \mathbb{R}^n \to \mathbb{R}^+$  is log concave, if its domain is a convex set and  $\log(f(x))$  is a concave function.

#### Chapters 2 and 3: Maximal Surface Area Chapter 4: Surface area of polytopes Chapter 5: On the Gaussian concentration.

Chapter 6: On the Gaussian Brunn-Minkowski inequality

## Log concave measures

### Definition of log concave measures

A Borel measure  $\mu$  on  $\mathbb{R}^n$  is called log concave, if for any compact sets  $A, B \subset \mathbb{R}^n$  and for any  $\lambda \in [0, 1]$ ,

$$\mu(\lambda A + (1-\lambda)B) \ge \mu(A)^{\lambda} \cdot \mu(B)^{1-\lambda}.$$

### Log concave functions

We say, that a function  $f : \mathbb{R}^n \to \mathbb{R}^+$  is log concave, if its domain is a convex set and  $\log(f(x))$  is a concave function. In other words, for any  $\lambda \in [0,1]$  and for any  $x, y \in \mathbb{R}^n$ ,

$$f(\lambda x+(1-\lambda)y) \geq f(x)^{\lambda} \cdot f(y)^{1-\lambda}.$$

#### Chapters 2 and 3: Maximal Surface Area

Chapter 4: Surface area of polytopes Chapter 5: On the Gaussian concentration. Chapter 6: On the Gaussian Brunn-Minkowski inequality

# Rotation invariant Log concave measures

★ 문 ► ★ 문 ►

< 4 P ►

э

# Rotation invariant Log concave measures

## Definition

The measure  $\gamma$  on  $\mathbb{R}^n$  is called rotation invariant, if for any rotation T on  $\mathbb{R}^n$  and for any set  $A \subset \mathbb{R}^n$ ,

$$\gamma(TA) = \gamma(A).$$

.⊒...>

# Rotation invariant Log concave measures

## Definition

The measure  $\gamma$  on  $\mathbb{R}^n$  is called rotation invariant, if for any rotation T on  $\mathbb{R}^n$  and for any set  $A \subset \mathbb{R}^n$ ,

$$\gamma(TA) = \gamma(A).$$

If  $\gamma$  has a density f(x), then f depends on the length of x only.

# Rotation invariant Log concave measures

## Definition

The measure  $\gamma$  on  $\mathbb{R}^n$  is called rotation invariant, if for any rotation T on  $\mathbb{R}^n$  and for any set  $A \subset \mathbb{R}^n$ ,

$$\gamma(TA) = \gamma(A).$$

If  $\gamma$  has a density f(x), then f depends on the length of x only.

• We fix a convex function  $\varphi(t): [0,\infty) \to [0,\infty]$ .

# Rotation invariant Log concave measures

### Definition

The measure  $\gamma$  on  $\mathbb{R}^n$  is called rotation invariant, if for any rotation T on  $\mathbb{R}^n$  and for any set  $A \subset \mathbb{R}^n$ ,

$$\gamma(TA) = \gamma(A).$$

If  $\gamma$  has a density f(x), then f depends on the length of x only.

We fix a convex function φ(t): [0,∞) → [0,∞]. We consider a probability measure γ on ℝ<sup>n</sup> with density C<sub>n</sub>e<sup>-φ(|y|)</sup>. This measure is both rotation invariant and log concave.

< ∃ →

# Rotation invariant Log concave measures

### Definition

The measure  $\gamma$  on  $\mathbb{R}^n$  is called rotation invariant, if for any rotation T on  $\mathbb{R}^n$  and for any set  $A \subset \mathbb{R}^n$ ,

$$\gamma(TA) = \gamma(A).$$

If  $\gamma$  has a density f(x), then f depends on the length of x only.

We fix a convex function φ(t): [0,∞) → [0,∞]. We consider a probability measure γ on ℝ<sup>n</sup> with density C<sub>n</sub>e<sup>-φ(|y|)</sup>. This measure is both rotation invariant and log concave.

### Question (generalization of Ball-Nazarov Theorems)

Fix a log concave rotation invariant measure  $\gamma$  on  $\mathbb{R}^n$  with density  $C_n e^{-\varphi(|y|)}$ on  $\mathbb{R}^n$ . Let Q be a convex body in  $\mathbb{R}^n$ . What are the bounds for max $\gamma(\partial Q)$ ?

医下 不正下

Rotation invariant Log concave measures

First example to try: let p > 0, consider probability measure  $\gamma_p$  on  $\mathbb{R}^n$  with density

$$\varphi_p(y) = c_{n,p} e^{-\frac{|y|^p}{p}}.$$

医下 不良下

Rotation invariant Log concave measures

First example to try: let p > 0, consider probability measure  $\gamma_p$  on  $\mathbb{R}^n$  with density

$$\varphi_p(y)=c_{n,p}e^{-\frac{|y|^p}{p}}.$$

## Theorem (G. L., JMAA 2013)

For any positive p

$$c(p)n^{\frac{3}{4}-\frac{1}{p}} \leq \max \gamma_p(\partial Q) \leq C(p)n^{\frac{3}{4}-\frac{1}{p}}$$

where c(p), C(p) depend on p only.

医下 不正下

Rotation invariant Log concave measures

First example to try: let p > 0, consider probability measure  $\gamma_p$  on  $\mathbb{R}^n$  with density

$$\varphi_p(y)=c_{n,p}e^{-\frac{|y|^p}{p}}.$$

## Theorem (G. L., JMAA 2013)

For any positive p

$$c(p)n^{\frac{3}{4}-\frac{1}{p}} \leq \max \gamma_p(\partial Q) \leq C(p)n^{\frac{3}{4}-\frac{1}{p}}$$

where c(p), C(p) depend on p only.

For  $p \ge 1$  the measure  $\gamma_p$  is log concave, but for p < 1 it is not.

医下 不正下

## Theorem (G. L., GAFA seminar notes, 2014)

Fix  $n \ge 2$ . Let  $\gamma$  be log concave rotation invariant measure on  $\mathbb{R}^n$ . Consider a random vector X in  $\mathbb{R}^n$  distributed with respect to  $\gamma$ .

$$\max_{Q \in \mathcal{K}_n} \gamma(\partial Q) = C \frac{\sqrt{n}}{\sqrt{\mathbb{E}|X|} \sqrt[4]{Var|X|}},$$

where  $\mathbb{E}|X|$  and Var|X| denote the expectation and the variance of X correspondingly.

### Theorem (G. L., GAFA seminar notes, 2014)

Fix  $n \ge 2$ . Let  $\gamma$  be log concave rotation invariant measure on  $\mathbb{R}^n$ . Consider a random vector X in  $\mathbb{R}^n$  distributed with respect to  $\gamma$ .

$$\max_{Q \in \mathcal{K}_n} \gamma(\partial Q) = C \frac{\sqrt{n}}{\sqrt{\mathbb{E}|X|} \sqrt[4]{Var|X|}},$$

where  $\mathbb{E}|X|$  and Var|X| denote the expectation and the variance of X correspondingly.

• The above implies results by Ball and Nazarov: if X is a standard Gaussian vector,  $\mathbb{E}|X| \approx \sqrt{n}$  and  $Var|X| \approx 1$ .

## Theorem (G. L., GAFA seminar notes, 2014)

Fix  $n \ge 2$ . Let  $\gamma$  be log concave rotation invariant measure on  $\mathbb{R}^n$ . Consider a random vector X in  $\mathbb{R}^n$  distributed with respect to  $\gamma$ .

$$\max_{Q \in \mathcal{K}_n} \gamma(\partial Q) = C \frac{\sqrt{n}}{\sqrt{\mathbb{E}|X|} \sqrt[4]{Var|X|}},$$

where  $\mathbb{E}|X|$  and Var|X| denote the expectation and the variance of X correspondingly.

- The above implies results by Ball and Nazarov: if X is a standard Gaussian vector,  $\mathbb{E}|X| \approx \sqrt{n}$  and  $Var|X| \approx 1$ .
- The above is also applicable for normalized Lebesgue measure restricted on a unit ball: if X is distributed uniformly in the unit ball,  $\mathbb{E}|X| \approx 1$  and  $Var|X| \approx \frac{1}{n^2}$ .

프 🖌 🔺 프 🕨

### Theorem (G. L., GAFA seminar notes, 2014)

Fix  $n \ge 2$ . Let  $\gamma$  be log concave rotation invariant measure on  $\mathbb{R}^n$ . Consider a random vector X in  $\mathbb{R}^n$  distributed with respect to  $\gamma$ .

$$\max_{Q \in \mathcal{K}_n} \gamma(\partial Q) = C \frac{\sqrt{n}}{\sqrt{\mathbb{E}|X|} \sqrt[4]{Var|X|}},$$

where  $\mathbb{E}|X|$  and Var|X| denote the expectation and the variance of X correspondingly.

- The above implies results by Ball and Nazarov: if X is a standard Gaussian vector,  $\mathbb{E}|X| \approx \sqrt{n}$  and  $Var|X| \approx 1$ .
- The above is also applicable for normalized Lebesgue measure restricted on a unit ball: if X is distributed uniformly in the unit ball,  $\mathbb{E}|X| \approx 1$  and  $Var|X| \approx \frac{1}{n^2}$ . The maximum for the surface area is attained on the unit sphere and is of order *n*.

프 🖌 🔺 프 🛌

# Chapter 4: Gaussian surface area of a polytope with K faces

医下颌 医下颌

э.

Gaussian surface area of a polytope with K faces

Let  $P = \bigcap_{i=1}^{K} \{ \langle x, \theta_i \rangle \leq \rho_i \}$  be a polytope with at most K faces.



돌에 송 돌에 ?

Gaussian surface area of a polytope with K faces

Let  $P = \bigcap_{i=1}^{K} \{ \langle x, \theta_i \rangle \le \rho_i \}$  be a polytope with at most K faces.



Theorem (F. Nazarov)

$$\gamma_2(\partial P) \leq C\sqrt{\log K}$$

for some absolute constant C.

< 臣 > < 臣 > □
Gaussian surface area of a polytope with K faces

Let  $P = \bigcap_{i=1}^{K} \{ \langle x, \theta_i \rangle \leq \rho_i \}$  be a polytope with at most K faces.



Theorem (F. Nazarov)

$$\gamma_2(\partial P) \leq C\sqrt{\log K}$$

for some absolute constant C.

What about log-concave rotation invariant case?

医下颌 医下口

# Surface area of a polytope with K faces with respect to LCRIPM: Upper bound

< ∃⇒

# Surface area of a polytope with K faces with respect to LCRIPM: Upper bound

### Theorem (G.L., 2014)

Fix  $n \ge 2$ . Let  $\gamma$  be log concave rotation invariant measure on  $\mathbb{R}^n$ . Consider a random vector X in  $\mathbb{R}^n$  distributed with respect to  $\gamma$ .

∃ >

# Surface area of a polytope with K faces with respect to LCRIPM: Upper bound

### Theorem (G.L., 2014)

Fix  $n \ge 2$ . Let  $\gamma$  be log concave rotation invariant measure on  $\mathbb{R}^n$ . Consider a random vector X in  $\mathbb{R}^n$  distributed with respect to  $\gamma$ . Fix positive integer  $K \in [2, \exp\left(\sqrt{\frac{c\mathbb{E}|X|}{\sqrt{Var|X|}}}\right)]$ . Let P be a convex polytope in  $\mathbb{R}^n$  with at most K facets.

< ∃ →

# Surface area of a polytope with K faces with respect to LCRIPM: Upper bound

### Theorem (G.L., 2014)

Fix  $n \ge 2$ . Let  $\gamma$  be log concave rotation invariant measure on  $\mathbb{R}^n$ . Consider a random vector X in  $\mathbb{R}^n$  distributed with respect to  $\gamma$ . Fix positive integer  $K \in [2, \exp\left(\sqrt{\frac{c\mathbb{E}|X|}{\sqrt{Var|X|}}}\right)]$ . Let P be a convex polytope in  $\mathbb{R}^n$  with at most K facets. Then

$$\gamma(\partial P) \leq C \frac{\sqrt{n}}{\mathbb{E}|X|} \cdot \sqrt{\log K} \cdot \log \frac{\sqrt{\mathbb{E}|X|}}{\sqrt[4]{Var|X|}\log K},$$

< ∃ →

# Surface area of a polytope with K faces with respect to LCRIPM: Upper bound

### Theorem (G.L., 2014)

Fix  $n \geq 2$ . Let  $\gamma$  be log concave rotation invariant measure on  $\mathbb{R}^n$ . Consider a random vector X in  $\mathbb{R}^n$  distributed with respect to  $\gamma$ . Fix positive integer  $K \in [2, \exp\left(\sqrt{\frac{c\mathbb{E}|X|}{\sqrt{Var|X|}}}\right)]$ . Let P be a convex polytope in  $\mathbb{R}^n$  with at most K facets. Then

$$\gamma(\partial P) \leq C \frac{\sqrt{n}}{\mathbb{E}|X|} \cdot \sqrt{\log K} \cdot \log \frac{\sqrt{\mathbb{E}|X|}}{\sqrt[4]{Var|X|}\log K},$$

where  $\mathbb{E}|X|$  and Var|X| denote the expectation and the variance of X correspondingly, and C and c stand for absolute constants.

4 ∃ > < ∃ >

# Surface area of a polytope with K faces with respect to LCRIPM: Upper bound

### Theorem (G.L., 2014)

Fix  $n \ge 2$ . Let  $\gamma$  be log concave rotation invariant measure on  $\mathbb{R}^n$ . Consider a random vector X in  $\mathbb{R}^n$  distributed with respect to  $\gamma$ . Fix positive integer  $K \in [2, \exp\left(\sqrt{\frac{c\mathbb{E}|X|}{\sqrt{Var|X|}}}\right)]$ . Let P be a convex polytope in  $\mathbb{R}^n$  with at most K facets. Then

$$\gamma(\partial P) \leq C \frac{\sqrt{n}}{\mathbb{E}|X|} \cdot \sqrt{\log K} \cdot \log \frac{\sqrt{\mathbb{E}|X|}}{\sqrt[4]{Var|X|}\log K},$$

where  $\mathbb{E}|X|$  and Var|X| denote the expectation and the variance of X correspondingly, and C and c stand for absolute constants.

#### Corollary

$$\gamma(\partial P) \leq C \frac{\sqrt{n}}{\mathbb{E}|X|} \cdot \sqrt{\log K} \cdot \log n.$$

# Surface area of a polytope with K faces with respect to LCRIPM: Lower bound

< ∃ >

# Surface area of a polytope with K faces with respect to LCRIPM: Lower bound

### Theorem (G.L., 2014)

Fix  $n \ge 2$ . Let  $\gamma$  be log concave rotation invariant measure on  $\mathbb{R}^n$ . Consider a random vector X in  $\mathbb{R}^n$  distributed with respect to  $\gamma$ .

< ∃⇒

# Surface area of a polytope with K faces with respect to LCRIPM: Lower bound

### Theorem (G.L., 2014)

Fix  $n \ge 2$ . Let  $\gamma$  be log concave rotation invariant measure on  $\mathbb{R}^n$ . Consider a random vector X in  $\mathbb{R}^n$  distributed with respect to  $\gamma$ . Fix positive integer  $K \in [2, \exp\left(\sqrt{\frac{c\mathbb{E}|X|}{\sqrt{Var|X|}}}\right)]$ . Then there exists a convex polytope P in  $\mathbb{R}^n$  with at most K facets such that

医下 不正下

# Surface area of a polytope with K faces with respect to LCRIPM: Lower bound

### Theorem (G.L., 2014)

Fix  $n \geq 2$ . Let  $\gamma$  be log concave rotation invariant measure on  $\mathbb{R}^n$ . Consider a random vector X in  $\mathbb{R}^n$  distributed with respect to  $\gamma$ . Fix positive integer  $K \in [2, \exp\left(\sqrt{\frac{c\mathbb{E}|X|}{\sqrt{Var|X|}}}\right)]$ . Then there exists a convex polytope P in  $\mathbb{R}^n$  with at most K facets such that

$$\gamma(\partial P) \ge C' \frac{\sqrt{n}}{\mathbb{E}|X|} \sqrt{\log K},$$

医下 不正下

# Surface area of a polytope with K faces with respect to LCRIPM: Lower bound

### Theorem (G.L., 2014)

Fix  $n \geq 2$ . Let  $\gamma$  be log concave rotation invariant measure on  $\mathbb{R}^n$ . Consider a random vector X in  $\mathbb{R}^n$  distributed with respect to  $\gamma$ . Fix positive integer  $K \in [2, \exp\left(\sqrt{\frac{c\mathbb{E}|X|}{\sqrt{Var|X|}}}\right)]$ . Then there exists a convex polytope P in  $\mathbb{R}^n$  with at most K facets such that

$$\gamma(\partial P) \ge C' \frac{\sqrt{n}}{\mathbb{E}|X|} \sqrt{\log K},$$

where  $\mathbb{E}|X|$  and Var|X| denote the expectation and the variance of X correspondingly, and C and c stand for absolute constants.

★ Ξ ► < Ξ ►</p>

# Surface area of a polytope with K faces with respect to LCRIPM: Lower bound

### Theorem (G.L., 2014)

Fix  $n \ge 2$ . Let  $\gamma$  be log concave rotation invariant measure on  $\mathbb{R}^n$ . Consider a random vector X in  $\mathbb{R}^n$  distributed with respect to  $\gamma$ . Fix positive integer  $K \in [2, \exp\left(\sqrt{\frac{c\mathbb{E}|X|}{\sqrt{Var|X|}}}\right)]$ . Then there exists a convex polytope P in  $\mathbb{R}^n$  with at most K facets such that

$$\gamma(\partial P) \ge C' \frac{\sqrt{n}}{\mathbb{E}|X|} \sqrt{\log K},$$

where  $\mathbb{E}|X|$  and Var|X| denote the expectation and the variance of X correspondingly, and C and c stand for absolute constants.

• In particular, this Theorem shows that the result of Nazarov for the Gaussian case is exact.

・ 同 ト ・ ヨ ト ・ ヨ ト

## Chapter 5: On the Gaussian concentration

イロト イヨト イヨト イヨト

= nar

## On the Gaussian concentration

For a measurable set  $Q \subset \mathbb{R}^n$  we define a function

$$\alpha_Q(h): \mathbb{R}^+ \to \mathbb{R}$$

by

$$\alpha_Q(h) := 1 - \gamma_2(Q + hB_2^n).$$

臣▶ ★ 臣▶

э

### On the Gaussian concentration

For a measurable set  $Q \subset \mathbb{R}^n$  we define a function

$$\alpha_Q(h): \mathbb{R}^+ \to \mathbb{R}$$

by

$$\alpha_Q(h) := 1 - \gamma_2(Q + hB_2^n).$$

It is well known that for every measurable  $Q \subset \mathbb{R}^n$  such that  $\gamma_2(Q) \geq \frac{1}{2}$ ,

$$\alpha_Q(h) \le \frac{1}{2} e^{-\frac{h^2}{2}}.$$
(1)

< ∃⇒

### On the Gaussian concentration

For a measurable set  $Q \subset \mathbb{R}^n$  we define a function

$$\alpha_Q(h): \mathbb{R}^+ \to \mathbb{R}$$

by

$$\alpha_Q(h) := 1 - \gamma_2(Q + hB_2^n).$$

It is well known that for every measurable  $Q \subset \mathbb{R}^n$  such that  $\gamma_2(Q) \geq \frac{1}{2}$ ,

$$\alpha_Q(h) \le \frac{1}{2} e^{-\frac{h^2}{2}}.$$
(1)

医下颌 医下颌

Moreover,

$$\gamma_2(Q+hB_2^n) \ge \gamma_2(H_Q+hB_2^n),\tag{2}$$

where  $H_Q$  is a half space such that  $\gamma_2(Q) = \gamma_2(H_Q)$ .

### On the Gaussian concentration

For a measurable set  $Q \subset \mathbb{R}^n$  we define a function

$$\alpha_Q(h): \mathbb{R}^+ \to \mathbb{R}$$

by

$$\alpha_Q(h) := 1 - \gamma_2(Q + hB_2^n).$$

It is well known that for every measurable  $Q \subset \mathbb{R}^n$  such that  $\gamma_2(Q) \geq \frac{1}{2}$ ,

$$\alpha_Q(h) \le \frac{1}{2} e^{-\frac{h^2}{2}}.$$
(1)

Moreover,

$$\gamma_2(Q+hB_2^n) \ge \gamma_2(H_Q+hB_2^n),\tag{2}$$

where  $H_Q$  is a half space such that  $\gamma_2(Q) = \gamma_2(H_Q)$ .

Theorem (G.L., 2014)

$$\alpha_Q(h) \leq 1 - \gamma_2(Q) - \frac{\sqrt{\pi}\gamma_2(\partial Q)^2}{8\sqrt{n}} \cdot \left(1 - e^{-\frac{\sqrt{n}}{\sqrt{\pi}\gamma_2(\partial Q)}h}\right)$$

## Chapter 6: the Gaussian Brunn-Minkowski inequality

・ロト ・四ト・モン・モン・

= nar

Classical Brunn-Minkowski inequality

★ E ► < E ►</p>

< 4 P ►

э

### Classical Brunn-Minkowski inequality

Recall: the Minkowski sum of the sets K and Q in  $\mathbb{R}^n$  is the set



▶ ★ 国 ▶

## Classical Brunn-Minkowski inequality

Recall: the Minkowski sum of the sets K and Q in  $\mathbb{R}^n$  is the set



The  $\lambda$ -dilate of a set A in  $\mathbb{R}^n$  is the set

 $\lambda A := \{ \lambda a \, | \, a \in A \}.$ 

- < ⊒ >

## Classical Brunn-Minkowski inequality

Recall: the Minkowski sum of the sets K and Q in  $\mathbb{R}^n$  is the set



The  $\lambda$ -dilate of a set A in  $\mathbb{R}^n$  is the set

 $\lambda A := \{ \lambda a \, | \, a \in A \}.$ 

#### Brunn-Minkowski inequality

The classical Brunn-Minkowski inequality states that for any measurable sets  $A, B \subset \mathbb{R}^n$  and for any  $\lambda \in [0, 1]$ ,

$$|\lambda A + (1-\lambda)B|^{\frac{1}{n}} \geq \lambda |A|^{\frac{1}{n}} + (1-\lambda)|B|^{\frac{1}{n}},$$

where  $|\cdot|$  stands for the Lebesgue Measure on  $\mathbb{R}^n$ .

The Brunn-Minkowski inequality and "shadow systems" (highlights of the work done by Colesanti)

The support function of a convex set

Recall, that the support function  $h_Q$  of a convex set  $Q \subset \mathbb{R}^2$  is the function on the unit sphere defined by

$$h_Q(\theta) = \max_{x \in Q} \langle x, \theta \rangle.$$

By homogeneity it extends from the sphere to the whole space. The support function represents the distance from the origin to the support hyperplane of a convex set in a given direction:



The Brunn-Minkowski inequality and "shadow systems" (highlights of the work done by Colesanti)

The support function of a convex set

Recall, that the support function  $h_Q$  of a convex set  $Q \subset \mathbb{R}^2$  is the function on the unit sphere defined by

$$h_Q(\theta) = \max_{x \in Q} \langle x, \theta \rangle.$$

By homogeneity it extends from the sphere to the whole space. The support function represents the distance from the origin to the support hyperplane of a convex set in a given direction:



The Brunn-Minkowski inequality and "shadow systems" (highlights of the work done by Colesanti)

The support function "shadow system"

**∃** →

The Brunn-Minkowski inequality and "shadow systems" (highlights of the work done by Colesanti)

#### The support function "shadow system"

Pick a positive number *a*. Let h(u) be a strictly convex  $C^2$ -smooth function on the circle  $\mathbb{S}^1$ . Consider a function  $\psi(u) \in C^2(\mathbb{S}^1)$ . Let  $s \in [0, a]$ .

The Brunn-Minkowski inequality and "shadow systems" (highlights of the work done by Colesanti)

#### The support function "shadow system"

Pick a positive number *a*. Let h(u) be a strictly convex  $C^2$ -smooth function on the circle  $\mathbb{S}^1$ . Consider a function  $\psi(u) \in C^2(\mathbb{S}^1)$ . Let  $s \in [0, a]$ . Consider a family of sets  $K_s$  in  $\mathbb{R}^2$ , where the support function of each  $K_s$  is  $h_s = h + s\psi$ .

 $\mathbf{K}_{2}(h(u),\psi(u),a):=\{\mathbf{K}_{s}\}_{s=0}^{a}$ 

The Brunn-Minkowski inequality and "shadow systems" (highlights of the work done by Colesanti)

#### The support function "shadow system"

Pick a positive number *a*. Let h(u) be a strictly convex  $C^2$ -smooth function on the circle  $\mathbb{S}^1$ . Consider a function  $\psi(u) \in C^2(\mathbb{S}^1)$ . Let  $s \in [0, a]$ . Consider a family of sets  $K_s$  in  $\mathbb{R}^2$ , where the support function of each  $K_s$  is  $h_s = h + s\psi$ .

 $\mathbf{K}_2(h(u),\psi(u),a):=\{\mathbf{K}_s\}_{s=0}^a$ 



The Brunn-Minkowski inequality and "shadow systems" (highlights of the work done by Colesanti)

#### The support function "shadow system"

Pick a positive number *a*. Let h(u) be a strictly convex  $C^2$ -smooth function on the circle  $\mathbb{S}^1$ . Consider a function  $\psi(u) \in C^2(\mathbb{S}^1)$ . Let  $s \in [0, a]$ . Consider a family of sets  $K_s$  in  $\mathbb{R}^2$ , where the support function of each  $K_s$  is  $h_s = h + s\psi$ .

$$\mathbf{K}_2(h(u),\psi(u),a) := \{\mathbf{K}_s\}_{s=0}^a$$



1 A. Colesanti, From the Brunn-Minkowski inequality to a class of Poincare' type inequalities, Communications in Contemporary Mathematics, 10 n. 5 (2008), 765-772.

## Highlights of the work done by Colesanti

Each couple of sets can be "embedded" into a support function shadow system

< ∃⇒

## Highlights of the work done by Colesanti

#### Each couple of sets can be "embedded" into a support function shadow system

Pick convex sets A and B in  $\mathbb{R}^2$  with the support functions  $h_A(u)$  and  $h_B(u)$ . For  $s \in [0,1]$ , consider the "support function shadow system"  $\{K_s\}$ , where the support function of  $K_s$  is  $h_s = h_A + s(h_B - h_A)$ . This way,  $K_0 = A$  and  $K_1 = B$ .

医下 不良下

## Highlights of the work done by Colesanti

#### Each couple of sets can be "embedded" into a support function shadow system

Pick convex sets A and B in  $\mathbb{R}^2$  with the support functions  $h_A(u)$  and  $h_B(u)$ . For  $s \in [0,1]$ , consider the "support function shadow system"  $\{K_s\}$ , where the support function of  $K_s$  is  $h_s = h_A + s(h_B - h_A)$ . This way,  $K_0 = A$  and  $K_1 = B$ .

The Brunn-Minkowski inequality for convex sets A, B in  $\mathbb{R}^2$ 

$$|\lambda A + (1-\lambda)B|^{\frac{1}{2}} \ge \lambda |A|^{\frac{1}{2}} + (1-\lambda)|B|^{\frac{1}{2}}$$

follows from the fact that the function  $f(s) := |K_s|^{\frac{1}{2}}$  is concave in s on [0,1].

## Highlights of the work done by Colesanti

#### Each couple of sets can be "embedded" into a support function shadow system

Pick convex sets A and B in  $\mathbb{R}^2$  with the support functions  $h_A(u)$  and  $h_B(u)$ . For  $s \in [0,1]$ , consider the "support function shadow system"  $\{K_s\}$ , where the support function of  $K_s$  is  $h_s = h_A + s(h_B - h_A)$ . This way,  $K_0 = A$  and  $K_1 = B$ .

The Brunn-Minkowski inequality for convex sets A, B in  $\mathbb{R}^2$ 

$$|\lambda A + (1-\lambda)B|^{rac{1}{2}} \ge \lambda |A|^{rac{1}{2}} + (1-\lambda)|B|^{rac{1}{2}}$$

follows from the fact that the function  $f(s) := |K_s|^{\frac{1}{2}}$  is concave in s on [0,1].

#### Claim

The Brunn-Minkowski inequality holds true for every pair of convex sets in  $\mathbb{R}^2$  if and only if for every convex smooth function h(u) on  $\mathbb{S}^1$  and for every smooth function  $\psi(u)$  on  $\mathbb{S}^1$ ,

$$f''(0) = \left(|K_s|^{\frac{1}{2}}\right)''|_{s=0} \leq 0.$$

## The Gaussian Brunn-Minkowski inequality

### Can we replace the standard Lebesgue measure with other measures?

돌에 송 돌에 ?

э

## The Gaussian Brunn-Minkowski inequality

#### Can we replace the standard Lebesgue measure with other measures?

Recall: the standard Gaussian Measure  $\gamma_2$  on  $\mathbb{R}^n$  is the measure with density

$$\left(\frac{1}{\sqrt{2\pi}}\right)^n e^{-\frac{|y|^2}{2}}.$$



< ∃⇒
# The Gaussian Brunn-Minkowski inequality

### Can we replace the standard Lebesgue measure with other measures?

Recall: the standard Gaussian Measure  $\gamma_2$  on  $\mathbb{R}^n$  is the measure with density

$$\left(\frac{1}{\sqrt{2\pi}}\right)^n e^{-\frac{|y|^2}{2}}.$$



### Gaussian Brunn-Minkowski inequality

Gardner and Zvavitch conjectured that for the standard Gaussian measure  $\gamma_2$  the inequality analogous to BM holds *under some natural assumptions* on the sets A and B in  $\mathbb{R}^n$ :

$$\gamma_2(\lambda A+(1-\lambda)B)^{rac{1}{n}}\geq \lambda\gamma_2(A)^{rac{1}{n}}+(1-\lambda)\gamma_2(B)^{rac{1}{n}}.$$

# The Gaussian Brunn-Minkowski inequality

Gaussian Brunn-Minkowski inequality

$$\gamma_2(\lambda A + (1-\lambda)B)^{\frac{1}{n}} \ge \lambda \gamma_2(A)^{\frac{1}{n}} + (1-\lambda)\gamma_2(B)^{\frac{1}{n}}$$
(3)

Which assumptions on the sets A and B in  $\mathbb{R}^n$  must be emposed in order for it to hold?

# The Gaussian Brunn-Minkowski inequality

Gaussian Brunn-Minkowski inequality

$$\gamma_2(\lambda A + (1-\lambda)B)^{\frac{1}{n}} \ge \lambda \gamma_2(A)^{\frac{1}{n}} + (1-\lambda)\gamma_2(B)^{\frac{1}{n}}$$
(3)

Which assumptions on the sets A and B in  $\mathbb{R}^n$  must be emposed in order for it to hold?

The inequality (3) is false in the full generality: one may shift the set A away from the origin. The farther the shift, the smaller the right hand side of (3) becomes, while the left hand side stays bounded from below by the fixed quantity  $(1 - \lambda)\gamma_2(B)^{\frac{1}{n}}$ .



< ∃ →

# The Gaussian Brunn-Minkowski inequality

Gaussian Brunn-Minkowski inequality

$$\gamma_2(\lambda A + (1-\lambda)B)^{\frac{1}{n}} \ge \lambda \gamma_2(A)^{\frac{1}{n}} + (1-\lambda)\gamma_2(B)^{\frac{1}{n}}$$
(3)

Which assumptions on the sets A and B in  $\mathbb{R}^n$  must be emposed in order for it to hold?

The inequality (3) is false in the full generality: one may shift the set A away from the origin. The farther the shift, the smaller the right hand side of (3) becomes, while the left hand side stays bounded from below by the fixed quantity  $(1 - \lambda)\gamma_2(B)^{\frac{1}{n}}$ .

That gives a clue on which assumptions must be reinforced.

# Gaussian Brunn Minkowski inequality: questions

### Question 1

Gardner and Zvavitch asked: *Does the Gaussian Brunn-Minkowski inequality hold true for all convex sets A and B containing the origin*?

# Gaussian Brunn Minkowski inequality: questions

### Question 1

Gardner and Zvavitch asked: *Does the Gaussian Brunn-Minkowski inequality hold true for all convex sets A and B containing the origin*?

The answer is **NO** (obtained by Nayar, Tkozh).

# Gaussian Brunn Minkowski inequality: questions

### Question 1

Gardner and Zvavitch asked: *Does the Gaussian Brunn-Minkowski inequality hold true for all convex sets A and B containing the origin*?

The answer is **NO** (obtained by Nayar, Tkozh). Their counterexample looks roughly like this:



# Gaussian Brunn Minkowski inequality: questions

### Question 1

Gardner and Zvavitch asked: *Does the Gaussian Brunn-Minkowski inequality hold true for all convex sets A and B containing the origin*?

The answer is  $\ensuremath{\text{NO}}$  (obtained by Nayar, Tkozh). Their counterexample looks roughly like this:



### Question 2

Gardner, Zvavitch, and Nayar and Tkozh conjectured: *The Gaussian Brunn-Minkowski inequality holds true for all symmetric convex sets A and B.* 

# The approach

### Once again, a support function shadow system

Pick a positive number *a*. Let h(u) be a strictly convex  $C^2$ -smooth function on the circle  $\mathbb{S}^1$ . Consider a function  $\psi(u) \in C^2(\mathbb{S}^1)$ . Let  $s \in [0, a]$ . Consider a family of sets  $K_s$  in  $\mathbb{R}^2$ , where the support function of each  $K_s$  is  $h_s = h + s\psi$ .

 $\mathbf{K}_{2}(h(u),\psi(u),a):=\{\mathbf{K}_{s}\}_{s=0}^{a}$ 

# The approach

#### Once again, a support function shadow system

Pick a positive number *a*. Let h(u) be a strictly convex  $C^2$ -smooth function on the circle  $\mathbb{S}^1$ . Consider a function  $\psi(u) \in C^2(\mathbb{S}^1)$ . Let  $s \in [0, a]$ . Consider a family of sets  $K_s$  in  $\mathbb{R}^2$ , where the support function of each  $K_s$  is  $h_s = h + s\psi$ .

 $\mathbf{K}_{2}(h(u),\psi(u),a):=\{\mathbf{K}_{s}\}_{s=0}^{a}$ 

The Gaussian Brunn-Minkowski inequality for symmetric convex sets would be implied by the fact that  $\gamma_2(K_s)''|_{s=0} \leq 0$  for all such systems when h and  $\psi$  are even.

< ∃ →

# The approach

#### Once again, a support function shadow system

Pick a positive number *a*. Let h(u) be a strictly convex  $C^2$ -smooth function on the circle  $\mathbb{S}^1$ . Consider a function  $\psi(u) \in C^2(\mathbb{S}^1)$ . Let  $s \in [0, a]$ . Consider a family of sets  $K_s$  in  $\mathbb{R}^2$ , where the support function of each  $K_s$  is  $h_s = h + s\psi$ .

 $\mathbf{K}_{2}(h(u),\psi(u),a):=\{\mathbf{K}_{s}\}_{s=0}^{a}$ 

The Gaussian Brunn-Minkowski inequality for symmetric convex sets would be implied by the fact that  $\gamma_2(K_s)''|_{s=0} \leq 0$  for all such systems when h and  $\psi$  are even. We need a formula expressing the standard Gaussian measure of a set in terms of the support function.

# The approach

### Once again, a support function shadow system

Pick a positive number *a*. Let h(u) be a strictly convex  $C^2$ -smooth function on the circle  $\mathbb{S}^1$ . Consider a function  $\psi(u) \in C^2(\mathbb{S}^1)$ . Let  $s \in [0, a]$ . Consider a family of sets  $K_s$  in  $\mathbb{R}^2$ , where the support function of each  $K_s$  is  $h_s = h + s\psi$ .

 $\mathbf{K}_{2}(h(u),\psi(u),a):=\{\mathbf{K}_{s}\}_{s=0}^{a}$ 

The Gaussian Brunn-Minkowski inequality for symmetric convex sets would be implied by the fact that  $\gamma_2(K_s)''|_{s=0} \leq 0$  for all such systems when h and  $\psi$  are even. We need a formula expressing the standard Gaussian measure of a set in terms of the support function.

### Formula for the Gaussian measure via the support function

Let  $\gamma_2$  be the Standard Gaussian measure in  $\mathbb{R}^2$ . Let K be a strictly convex body in  $\mathbb{R}^2$  containing the origin with the support function  $h(u) \in C^2(\mathbb{S}^1)$ . Then

$$\gamma_2(K) = \frac{1}{2\pi} \int_{-\pi}^{\pi} \frac{h^2 + h\ddot{h}}{h^2 + \dot{h}^2} \left( 1 - e^{-\frac{h^2 + \dot{h}^2}{2}} \right) du.$$

Sketch of the proof of the formula

$$\gamma_2(K) = \frac{1}{2\pi} \int_{-\pi}^{\pi} \frac{h^2 + h\ddot{h}}{h^2 + \dot{h}^2} \left( 1 - e^{-\frac{h^2 + \dot{h}^2}{2}} \right) du.$$

Proof.

★ 문 ► ★ 문 ►

< 4 ► >

э

Sketch of the proof of the formula

$$\gamma_2(K) = \frac{1}{2\pi} \int_{-\pi}^{\pi} \frac{h^2 + h\ddot{h}}{h^2 + \dot{h}^2} \left( 1 - e^{-\frac{h^2 + \dot{h}^2}{2}} \right) du.$$

Proof.

• We write

$$\gamma_2(K) = \frac{1}{2\pi} \int_K e^{-\frac{|y|^2}{2}} dy.$$

★ E ► < E ►</p>

< 4 P ►

э

Sketch of the proof of the formula

$$\gamma_2(K) = \frac{1}{2\pi} \int_{-\pi}^{\pi} \frac{h^2 + h\ddot{h}}{h^2 + \dot{h}^2} \left( 1 - e^{-\frac{h^2 + \dot{h}^2}{2}} \right) du.$$

Proof.

We write

$$\gamma_2(K) = \frac{1}{2\pi} \int_K e^{-\frac{|y|^2}{2}} dy.$$

 We make a change of variables X : ∂K × (0,∞) → ℝ<sup>2</sup>, where X(y,t) = yt. The Jacobian of such change is t|y|cos(y, n<sub>y</sub>), where n<sub>y</sub> is the normal vector at y.

Sketch of the proof of the formula

$$\gamma_2(K) = \frac{1}{2\pi} \int_{-\pi}^{\pi} \frac{h^2 + h\ddot{h}}{h^2 + \dot{h}^2} \left( 1 - e^{-\frac{h^2 + \dot{h}^2}{2}} \right) du.$$

Proof.

• We write

$$\gamma_2(K) = \frac{1}{2\pi} \int_K e^{-\frac{|y|^2}{2}} dy.$$

 We make a change of variables X : ∂K × (0,∞) → ℝ<sup>2</sup>, where X(y,t) = yt. The Jacobian of such change is t|y|cos(y, n<sub>y</sub>), where n<sub>y</sub> is the normal vector at y.



# The proof of the formula

$$\gamma_2(K) = \frac{1}{2\pi} \int_{\partial K} \int_0^1 t|y| \cos(y, n_y) e^{-\frac{(t|y|)^2}{2}} dt d\sigma(y)$$

・ロト ・四ト ・ヨト ・ヨトー

Ξ.

## The proof of the formula

$$\gamma_2(K) = \frac{1}{2\pi} \int_{\partial K} \int_0^1 t|y| \cos(y, n_y) e^{-\frac{(t|y|)^2}{2}} dt d\sigma(y)$$

• In the latter integral we make the change of variables via Gauss map, passing the integration from  $\partial K$  to  $\mathbb{S}^1$ . The Jacobian of the Gauss map is the curvature function of K, which in the planar case is  $h + \ddot{h}$ , where h is the support function of K.

## The proof of the formula

$$\gamma_2(K) = \frac{1}{2\pi} \int_{\partial K} \int_0^1 t|y| \cos(y, n_y) e^{-\frac{(t|y|)^2}{2}} dt d\sigma(y)$$

• In the latter integral we make the change of variables via Gauss map, passing the integration from  $\partial K$  to  $\mathbb{S}^1$ . The Jacobian of the Gauss map is the curvature function of K, which in the planar case is  $h + \ddot{h}$ , where h is the support function of K.

$$\gamma_2(K) = \frac{1}{2\pi} \int_{-\pi}^{\pi} h(h+\ddot{h}) \int_0^1 t e^{-\frac{(t|\nabla h|)^2}{2}} dt du.$$

## The proof of the formula

$$\gamma_2(K) = \frac{1}{2\pi} \int_{\partial K} \int_0^1 t |y| \cos(y, n_y) e^{-\frac{(t|y|)^2}{2}} dt d\sigma(y)$$

• In the latter integral we make the change of variables via Gauss map, passing the integration from  $\partial K$  to  $\mathbb{S}^1$ . The Jacobian of the Gauss map is the curvature function of K, which in the planar case is  $h + \ddot{h}$ , where h is the support function of K.

$$\gamma_2(K)=\frac{1}{2\pi}\int_{-\pi}^{\pi}h(h+\ddot{h})\int_0^1te^{-\frac{(t|\nabla h|)^2}{2}}dtdu.$$

• Observation that  $|\nabla h|^2 = h^2 + \dot{h}^2$ , and integration in t leads to the desired conclusion

$$\gamma_2(K) = rac{1}{2\pi} \int_{-\pi}^{\pi} rac{h^2 + h\ddot{h}}{h^2 + \dot{h}^2} \left( 1 - e^{-rac{h^2 + \dot{h}^2}{2}} 
ight) du. \square$$

### The general statement

### The formula for any measure in $\mathbb{R}^n$

Let  $\gamma$  be a measure in  $\mathbb{R}^n$  with density f(x). Let K be a strictly convex body in  $\mathbb{R}^n$  containing the origin with the support function  $h(u) \in C^2(\mathbb{S}^{n-1})$ , where  $u \in \mathbb{S}^{n-1}$ . Let det Q(h(u)) be the curvature function of K. Denote the gradient of h by  $\nabla h$ . Then

$$\gamma(K) = \int_{\mathbb{S}^{n-1}} \frac{h(u) \det Q(h(u))}{|\nabla h(u)|^n} \int_0^{|\nabla h|} t^{n-1} f(t \cdot \frac{\nabla h}{|\nabla h|}) dt du.$$

### The general statement

### The formula for any measure in $\mathbb{R}^n$

Let  $\gamma$  be a measure in  $\mathbb{R}^n$  with density f(x). Let K be a strictly convex body in  $\mathbb{R}^n$  containing the origin with the support function  $h(u) \in C^2(\mathbb{S}^{n-1})$ , where  $u \in \mathbb{S}^{n-1}$ . Let det Q(h(u)) be the curvature function of K. Denote the gradient of h by  $\nabla h$ . Then

$$\gamma(\mathcal{K}) = \int_{\mathbb{S}^{n-1}} \frac{h(u) \det Q(h(u))}{|\nabla h(u)|^n} \int_0^{|\nabla h|} t^{n-1} f(t \cdot \frac{\nabla h}{|\nabla h|}) dt du.$$

This formula might find its use in other questions, such as B-Theorem, S-Theorem, Isoperimetric inequalities etc.

## The neighborhood of the disc

### Once again, a shadow system for h(u) = R

Pick a positive number *a*. Pick a positive number *R*. Consider a function  $\psi(u) \in C^2(\mathbb{S}^1)$ . Let  $s \in [0, a]$ . Consider a family of sets  $K_s$  in  $\mathbb{R}^2$ , where the support function of each  $K_s$  is  $h_s = R + s\psi$ .

 $\mathbf{K}_2(R,\psi(u),a) := \{\mathbf{K}_s\}_{s=0}^a$ 

## The neighborhood of the disc

### Once again, a shadow system for h(u) = R

Pick a positive number *a*. Pick a positive number *R*. Consider a function  $\psi(u) \in C^2(\mathbb{S}^1)$ . Let  $s \in [0, a]$ . Consider a family of sets  $K_s$  in  $\mathbb{R}^2$ , where the support function of each  $K_s$  is  $h_s = R + s\psi$ .

 $\mathbf{K}_2(R,\psi(u),a) := \{\mathbf{K}_s\}_{s=0}^a$ 



< ∃ →

# The neighborhood of the disc

### Once again, a shadow system for h(u) = R

Pick a positive number *a*. Pick a positive number *R*. Consider a function  $\psi(u) \in C^2(\mathbb{S}^1)$ . Let  $s \in [0, a]$ . Consider a family of sets  $K_s$  in  $\mathbb{R}^2$ , where the support function of each  $K_s$  is  $h_s = R + s\psi$ .

 $\mathbf{K}_2(R,\psi(u),a) := \{\mathbf{K}_s\}_{s=0}^a$ 



Gaussian Brunn-Minkovski is true in a neighborhood of any disc

Pick  $R \in (0,\infty)$ . Fix  $\psi \in C^2(\mathbb{S}^1)$ . Then there exists an  $\epsilon = \epsilon(R,\psi)$  such that for every  $K, L \in \mathbf{K}_2(R,\psi,\epsilon)$  and for every  $\lambda \in [0,1]$ ,

$$\gamma_2^{\frac{1}{2}}(\lambda K + (1-\lambda)L) \geq \lambda \gamma_2^{\frac{1}{2}}(K) + (1-\lambda)\gamma_2^{\frac{1}{2}}(L).$$

# Sketch of the proof

ヘロト ヘロト ヘヨト ヘヨト

Ξ.

# Sketch of the proof

• We apply the formula for the Gaussian measure

$$\gamma_2(K) = \frac{1}{2\pi} \int_{-\pi}^{\pi} \frac{h^2 + h\ddot{h}}{h^2 + \dot{h}^2} \left( 1 - e^{-\frac{h^2 + h^2}{2}} \right) du$$

when the support function of the set is  $h = R + s\psi$ 

$$\gamma(s) := \int_{-\pi}^{\pi} \frac{(R+s\psi)^2 + (R+s\psi)s\ddot{\psi}}{(R+s\psi)^2 + (s\dot{\psi})^2} (1 - e^{-\frac{(R+s\psi)^2 + (s\dot{\psi})^2}{2}}) du.$$

## Sketch of the proof

• We apply the formula for the Gaussian measure

$$\gamma_2(K) = \frac{1}{2\pi} \int_{-\pi}^{\pi} \frac{h^2 + h\ddot{h}}{h^2 + \dot{h}^2} \left( 1 - e^{-\frac{h^2 + h^2}{2}} \right) du$$

when the support function of the set is  $h = R + s\psi$ 

$$\gamma(s) := \int_{-\pi}^{\pi} \frac{(R+s\psi)^2 + (R+s\psi)s\ddot{\psi}}{(R+s\psi)^2 + (s\dot{\psi})^2} (1 - e^{-\frac{(R+s\psi)^2 + (s\dot{\psi})^2}{2}}) du.$$

• We differentiate it at zero twice.

## Sketch of the proof

• We apply the formula for the Gaussian measure

$$\gamma_2(K) = \frac{1}{2\pi} \int_{-\pi}^{\pi} \frac{h^2 + h\ddot{h}}{h^2 + \dot{h}^2} \left( 1 - e^{-\frac{h^2 + h^2}{2}} \right) du$$

when the support function of the set is  ${\it h}={\it R}+{\it s}\psi$ 

$$\gamma(s) := \int_{-\pi}^{\pi} \frac{(R+s\psi)^2 + (R+s\psi)s\ddot{\psi}}{(R+s\psi)^2 + (s\dot{\psi})^2} (1 - e^{-\frac{(R+s\psi)^2 + (s\dot{\psi})^2}{2}}) du.$$

• We differentiate it at zero twice. We observe that  $(\sqrt{\gamma(s)})_0'' \leq 0$  whenever

$$2(e^{\frac{R^2}{2}}-1)\int \left[(1-R^2)\psi^2-\dot{\psi}^2\right]-R^2\left(\int\psi\right)^2\leq 0.$$

# Sketch of the proof

We want to prove that

$$2(e^{\frac{R^2}{2}}-1)\int \left[(1-R^2)\psi^2-\dot{\psi}^2\right]-R^2\left(\int\psi\right)^2\leq 0.$$

臣▶ ★臣▶

э

# Sketch of the proof

We want to prove that

$$2(e^{\frac{R^2}{2}}-1)\int \left[(1-R^2)\psi^2-\dot{\psi}^2\right]-R^2\left(\int\psi\right)^2\leq 0.$$

• We apply Poincare inequality.

∢ ≣⇒

# Sketch of the proof

We want to prove that

$$2(e^{\frac{R^2}{2}}-1)\int \left[(1-R^2)\psi^2-\dot{\psi}^2\right]-R^2\left(\int\psi\right)^2\leq 0.$$

- We apply Poincare inequality.
- We arrive to an inequality

$$2(e^{\frac{R^2}{2}}-1)(1-2R^2)-R^2<0,$$

for R > 0

# Sketch of the proof

We want to prove that

$$2(e^{\frac{R^2}{2}}-1)\int \left[(1-R^2)\psi^2-\dot{\psi}^2\right]-R^2\left(\int\psi\right)^2\leq 0.$$

- We apply Poincare inequality.
- We arrive to an inequality

$$2(e^{\frac{R^2}{2}}-1)(1-2R^2)-R^2<0,$$

for R > 0

## Sketch of the proof

We want to prove that

$$2(e^{\frac{R^2}{2}}-1)\int \left[(1-R^2)\psi^2-\dot{\psi}^2\right]-R^2\left(\int\psi\right)^2\leq 0.$$

- We apply Poincare inequality.
- We arrive to an inequality

$$2(e^{\frac{R^2}{2}}-1)(1-2R^2)-R^2<0,$$

for R > 0, which we brutal force.  $\Box$ 



# Thanks for your attention!

・ロト ・四ト ・ヨト ・ヨトー