# On the geometry of log-concave measures. 

Galyna Livshyts

Kent State University

Kent State University,
May 4, 2015.

## Chapters 2 and 3: Maximal Surface Area

## Classical Isoperimetric Inequality

## Isoperimetric Inequality

Let $Q$ be a set in $\mathbb{R}^{n}$. Denote the boundary of $Q$ by $\partial Q$. Let $|Q|=1$. Question: How to minimize $|\partial Q|$ (the surface area of $Q$ )?

## Classical Isoperimetric Inequality

## Isoperimetric Inequality

Let $Q$ be a set in $\mathbb{R}^{n}$. Denote the boundary of $Q$ by $\partial Q$. Let $|Q|=1$. Question: How to minimize $|\partial Q|$ (the surface area of $Q$ )?

Well-known Answer (Ancient greeks, Jakob Steiner in 1838, Jakob and Johann Bernoulli, Federer in 1969)
$|\partial Q|$ is minimized when $Q$ is a Euclidean ball.

## Classical Isoperimetric Inequality

## Isoperimetric Inequality

Let $Q$ be a set in $\mathbb{R}^{n}$. Denote the boundary of $Q$ by $\partial Q$. Let $|Q|=1$. Question: How to minimize $|\partial Q|$ (the surface area of $Q$ )?

Well-known Answer (Ancient greeks, Jakob Steiner in 1838, Jakob and Johann Bernoulli, Federer in 1969)
$|\partial Q|$ is minimized when $Q$ is a Euclidean ball.


But if we replace the usual Lebesgue volume measure with another measure, the answer to that question may change!

## Gaussian isoperimetric type inequalities

## Gaussian Measure

The Standard Gaussian Measure $\gamma_{2}$ on $\mathbb{R}^{n}$ is the probability measure with density

$$
\varphi_{2}(y)=\left(\frac{1}{\sqrt{2 \pi}}\right)^{n} e^{-\frac{|y|^{2}}{2}}
$$

## Gaussian isoperimetric type inequalities

## Gaussian Measure

The Standard Gaussian Measure $\gamma_{2}$ on $\mathbb{R}^{n}$ is the probability measure with density

$$
\varphi_{2}(y)=\left(\frac{1}{\sqrt{2 \pi}}\right)^{n} e^{-\frac{|y|^{2}}{2}}
$$

The surface area of a convex body $Q$ with respect to continuous measure $\gamma$ on $\mathbb{R}^{n}$ is defined to be

$$
\gamma(\partial Q)=\liminf _{\epsilon \rightarrow+0} \frac{\gamma\left(\left(Q+\epsilon B_{2}^{n}\right) \backslash Q\right)}{\epsilon} .
$$

## Gaussian isoperimetric type inequalities

## Gaussian Measure

The Standard Gaussian Measure $\gamma_{2}$ on $\mathbb{R}^{n}$ is the probability measure with density

$$
\varphi_{2}(y)=\left(\frac{1}{\sqrt{2 \pi}}\right)^{n} e^{-\frac{|y|^{2}}{2}}
$$

The surface area of a convex body $Q$ with respect to continuous measure $\gamma$ on $\mathbb{R}^{n}$ is defined to be

$$
\gamma(\partial Q)=\liminf _{\epsilon \rightarrow+0} \frac{\gamma\left(\left(Q+\epsilon B_{2}^{n}\right) \backslash Q\right)}{\epsilon} .
$$

There is a convenient integral expression for $\gamma_{2}(\partial Q)$ :

$$
\gamma_{2}(\partial Q)=\left(\frac{1}{\sqrt{2 \pi}}\right)^{n} \int_{\partial Q} e^{-\frac{|y|^{2}}{2}} d \sigma(y)
$$

where $d \sigma(y)$ stands for Lebesgue surface measure.

## Gaussian isoperimetric type inequalities

The Gaussian Isoperimetric inequality (Sudakov/Tsirelson and Borell in 1974)
Among all the sets of a fixed Gaussian volume, half-spaces have the smallest Gaussian surface area.

## Gaussian isoperimetric type inequalities

The Gaussian Isoperimetric inequality (Sudakov/Tsirelson and Borell in 1974)
Among all the sets of a fixed Gaussian volume, half-spaces have the smallest Gaussian surface area.


## Gaussian isoperimetric type inequalities

The Gaussian Isoperimetric inequality (Sudakov/Tsirelson and Borell in 1974)
Among all the sets of a fixed Gaussian volume, half-spaces have the smallest Gaussian surface area.


How to ask the reverse question?

## Gaussian isoperimetric type inequalities

The Gaussian Isoperimetric inequality (Sudakov/Tsirelson and Borell in 1974)
Among all the sets of a fixed Gaussian volume, half-spaces have the smallest Gaussian surface area.


How to ask the reverse question?

By $\mathcal{K}_{n}$ we denote the set of all convex bodies in $\mathbb{R}^{n}$.
Let $Q$ run over $\mathcal{K}_{n}$. What is the maximal Gaussian surface area of $Q$ ?

## Gaussian reverse isoperimetric inequalities

- K. Ball in 1993 showed, that for any convex set $Q \subset \mathbb{R}^{n}$,

$$
\gamma_{2}(\partial Q) \leq C^{\frac{1}{4}} .
$$

## Gaussian reverse isoperimetric inequalities

- K. Ball in 1993 showed, that for any convex set $Q \subset \mathbb{R}^{n}$,

$$
\gamma_{2}(\partial Q) \leq C n^{\frac{1}{4}} .
$$

- F. Nazarov in 2003 showed sharpness of Ball's result by proving

$$
0.28 n^{\frac{1}{4}} \leq \max _{Q \in \mathcal{K}_{n}} \gamma_{2}(\partial Q) \leq 0.64 n^{\frac{1}{4}}
$$

## Gaussian reverse isoperimetric inequalities

- K. Ball in 1993 showed, that for any convex set $Q \subset \mathbb{R}^{n}$,

$$
\gamma_{2}(\partial Q) \leq C n^{\frac{1}{4}} .
$$

- F. Nazarov in 2003 showed sharpness of Ball's result by proving

$$
0.28 n^{\frac{1}{4}} \leq \max _{Q \in \mathcal{K}_{n}} \gamma_{2}(\partial Q) \leq 0.64 n^{\frac{1}{4}}
$$

- D. Kane in 2010 showed, that for any polynomial level set the Gaussian surface area is bounded by $\frac{d}{\sqrt{2}}$, where $d$ is the degree of the polynomial.


## Gaussian reverse isoperimetric inequalities

- K. Ball in 1993 showed, that for any convex set $Q \subset \mathbb{R}^{n}$,

$$
\gamma_{2}(\partial Q) \leq C n^{\frac{1}{4}}
$$

- F. Nazarov in 2003 showed sharpness of Ball's result by proving

$$
0.28 n^{\frac{1}{4}} \leq \max _{Q \in \mathcal{K}_{n}} \gamma_{2}(\partial Q) \leq 0.64 n^{\frac{1}{4}}
$$

- D. Kane in 2010 showed, that for any polynomial level set the Gaussian surface area is bounded by $\frac{d}{\sqrt{2}}$, where $d$ is the degree of the polynomial. It implied in particular, that for any ellipsoid the Gaussian surface area is bounded by $\sqrt{2}$ independently of the dimension.


## Gaussian reverse isoperimetric inequalities

- K. Ball in 1993 showed, that for any convex set $Q \subset \mathbb{R}^{n}$,

$$
\gamma_{2}(\partial Q) \leq C n^{\frac{1}{4}}
$$

- F. Nazarov in 2003 showed sharpness of Ball's result by proving

$$
0.28 n^{\frac{1}{4}} \leq \max _{Q \in \mathcal{K}_{n}} \gamma_{2}(\partial Q) \leq 0.64 n^{\frac{1}{4}}
$$

- D. Kane in 2010 showed, that for any polynomial level set the Gaussian surface area is bounded by $\frac{d}{\sqrt{2}}$, where $d$ is the degree of the polynomial. It implied in particular, that for any ellipsoid the Gaussian surface area is bounded by $\sqrt{2}$ independently of the dimension.

Are there any other interesting measures for which it is natural to ask for Isoperimetric type inequalities?

## Log concave measures

## Definition of log concave measures

A Borel measure $\mu$ on $\mathbb{R}^{n}$ is called log concave, if for any compact sets $A, B \subset \mathbb{R}^{n}$ and for any $\lambda \in[0,1]$,

$$
\mu(\lambda A+(1-\lambda) B) \geq \mu(A)^{\lambda} \cdot \mu(B)^{1-\lambda}
$$

## Log concave measures

## Definition of log concave measures

A Borel measure $\mu$ on $\mathbb{R}^{n}$ is called log concave, if for any compact sets $A, B \subset \mathbb{R}^{n}$ and for any $\lambda \in[0,1]$,

$$
\mu(\lambda A+(1-\lambda) B) \geq \mu(A)^{\lambda} \cdot \mu(B)^{1-\lambda}
$$

## Log concave functions

We say, that a function $f: \mathbb{R}^{n} \rightarrow \mathbb{R}^{+}$is log concave, if its domain is a convex set and $\log (f(x))$ is a concave function.

## Log concave measures

## Definition of log concave measures

A Borel measure $\mu$ on $\mathbb{R}^{n}$ is called log concave, if for any compact sets $A, B \subset \mathbb{R}^{n}$ and for any $\lambda \in[0,1]$,

$$
\mu(\lambda A+(1-\lambda) B) \geq \mu(A)^{\lambda} \cdot \mu(B)^{1-\lambda}
$$

## Log concave functions

We say, that a function $f: \mathbb{R}^{n} \rightarrow \mathbb{R}^{+}$is log concave, if its domain is a convex set and $\log (f(x))$ is a concave function. In other words, for any $\lambda \in[0,1]$ and for any $x, y \in \mathbb{R}^{n}$,

$$
f(\lambda x+(1-\lambda) y) \geq f(x)^{\lambda} \cdot f(y)^{1-\lambda}
$$

## Rotation invariant Log concave measures

## Rotation invariant Log concave measures

## Definition

The measure $\gamma$ on $\mathbb{R}^{n}$ is called rotation invariant, if for any rotation $T$ on $\mathbb{R}^{n}$ and for any set $A \subset \mathbb{R}^{n}$,

$$
\gamma(T A)=\gamma(A)
$$

## Rotation invariant Log concave measures

## Definition

The measure $\gamma$ on $\mathbb{R}^{n}$ is called rotation invariant, if for any rotation $T$ on $\mathbb{R}^{n}$ and for any set $A \subset \mathbb{R}^{n}$,

$$
\gamma(T A)=\gamma(A)
$$

If $\gamma$ has a density $f(x)$, then $f$ depends on the length of $x$ only.

## Rotation invariant Log concave measures

## Definition

The measure $\gamma$ on $\mathbb{R}^{n}$ is called rotation invariant, if for any rotation $T$ on $\mathbb{R}^{n}$ and for any set $A \subset \mathbb{R}^{n}$,

$$
\gamma(T A)=\gamma(A)
$$

If $\gamma$ has a density $f(x)$, then $f$ depends on the length of $x$ only.

- We fix a convex function $\varphi(t):[0, \infty) \rightarrow[0, \infty]$.


## Rotation invariant Log concave measures

## Definition

The measure $\gamma$ on $\mathbb{R}^{n}$ is called rotation invariant, if for any rotation $T$ on $\mathbb{R}^{n}$ and for any set $A \subset \mathbb{R}^{n}$,

$$
\gamma(T A)=\gamma(A)
$$

If $\gamma$ has a density $f(x)$, then $f$ depends on the length of $x$ only.

- We fix a convex function $\varphi(t):[0, \infty) \rightarrow[0, \infty]$. We consider a probability measure $\gamma$ on $\mathbb{R}^{n}$ with density $C_{n} e^{-\varphi(|y|)}$. This measure is both rotation invariant and log concave.


## Rotation invariant Log concave measures

## Definition

The measure $\gamma$ on $\mathbb{R}^{n}$ is called rotation invariant, if for any rotation $T$ on $\mathbb{R}^{n}$ and for any set $A \subset \mathbb{R}^{n}$,

$$
\gamma(T A)=\gamma(A)
$$

If $\gamma$ has a density $f(x)$, then $f$ depends on the length of $x$ only.

- We fix a convex function $\varphi(t):[0, \infty) \rightarrow[0, \infty]$. We consider a probability measure $\gamma$ on $\mathbb{R}^{n}$ with density $C_{n} e^{-\varphi(|y|)}$. This measure is both rotation invariant and log concave.


## Question (generalization of Ball-Nazarov Theorems)

Fix a $\log$ concave rotation invariant measure $\gamma$ on $\mathbb{R}^{n}$ with density $C_{n} e^{-\varphi(|y|)}$ on $\mathbb{R}^{n}$. Let $Q$ be a convex body in $\mathbb{R}^{n}$. What are the bounds for $\max \gamma(\partial Q)$ ?

## Rotation invariant Log concave measures

First example to try: let $p>0$, consider probability measure $\gamma_{p}$ on $\mathbb{R}^{n}$ with density

$$
\varphi_{p}(y)=c_{n, p} e^{-\frac{|y| p}{p}} .
$$

## Rotation invariant Log concave measures

First example to try: let $p>0$, consider probability measure $\gamma_{p}$ on $\mathbb{R}^{n}$ with density

$$
\varphi_{p}(y)=c_{n, p} e^{-\frac{|y|^{p}}{p}}
$$

## Theorem (G. L., JMAA 2013)

For any positive $p$

$$
c(p) n^{\frac{3}{4}-\frac{1}{p}} \leq \max \gamma_{p}(\partial Q) \leq C(p) n^{\frac{3}{4}-\frac{1}{p}},
$$

where $c(p), C(p)$ depend on $p$ only.

## Rotation invariant Log concave measures

First example to try: let $p>0$, consider probability measure $\gamma_{p}$ on $\mathbb{R}^{n}$ with density

$$
\varphi_{p}(y)=c_{n, p} e^{-\frac{|y|^{p}}{p}}
$$

## Theorem (G. L., JMAA 2013)

For any positive $p$

$$
c(p) n^{\frac{3}{4}-\frac{1}{p}} \leq \max \gamma_{p}(\partial Q) \leq C(p) n^{\frac{3}{4}-\frac{1}{p}},
$$

where $c(p), C(p)$ depend on $p$ only.
For $p \geq 1$ the measure $\gamma_{p}$ is log concave, but for $p<1$ it is not.

## The reverse isoperimetric inequality for Rotation invariant Log concave measures. The main result.

## Theorem (G. L., GAFA seminar notes, 2014)

Fix $n \geq 2$. Let $\gamma$ be log concave rotation invariant measure on $\mathbb{R}^{n}$. Consider a random vector $X$ in $\mathbb{R}^{n}$ distributed with respect to $\gamma$.

$$
\max _{Q \in \mathcal{K}_{n}} \gamma(\partial Q)=C \frac{\sqrt{n}}{\sqrt{\mathbb{E}|X|} \sqrt[4]{\operatorname{Var}|X|}}
$$

where $\mathbb{E}|X|$ and $\operatorname{Var}|X|$ denote the expectation and the variance of $X$ correspondingly.

## The reverse isoperimetric inequality for Rotation invariant Log concave measures. The main result.

## Theorem (G. L., GAFA seminar notes, 2014)

Fix $n \geq 2$. Let $\gamma$ be log concave rotation invariant measure on $\mathbb{R}^{n}$. Consider a random vector $X$ in $\mathbb{R}^{n}$ distributed with respect to $\gamma$.

$$
\max _{Q \in \mathcal{K}_{n}} \gamma(\partial Q)=C \frac{\sqrt{n}}{\sqrt{\mathbb{E}|X|} \sqrt[4]{\operatorname{Var}|X|}}
$$

where $\mathbb{E}|X|$ and $\operatorname{Var}|X|$ denote the expectation and the variance of $X$ correspondingly.

- The above implies results by Ball and Nazarov: if $X$ is a standard Gaussian vector, $\mathbb{E}|X| \approx \sqrt{n}$ and $\operatorname{Var}|X| \approx 1$.


## The reverse isoperimetric inequality for Rotation invariant Log concave measures. The main result.

## Theorem (G. L., GAFA seminar notes, 2014)

Fix $n \geq 2$. Let $\gamma$ be log concave rotation invariant measure on $\mathbb{R}^{n}$. Consider a random vector $X$ in $\mathbb{R}^{n}$ distributed with respect to $\gamma$.

$$
\max _{Q \in \mathcal{K}_{n}} \gamma(\partial Q)=C \frac{\sqrt{n}}{\sqrt{\mathbb{E}|X|} \sqrt[4]{\operatorname{Var}|X|}}
$$

where $\mathbb{E}|X|$ and $\operatorname{Var}|X|$ denote the expectation and the variance of $X$ correspondingly.

- The above implies results by Ball and Nazarov: if $X$ is a standard Gaussian vector, $\mathbb{E}|X| \approx \sqrt{n}$ and $\operatorname{Var}|X| \approx 1$.
- The above is also applicable for normalized Lebesgue measure restricted on a unit ball: if $X$ is distributed uniformly in the unit ball, $\mathbb{E}|X| \approx 1$ and $\operatorname{Var}|X| \approx \frac{1}{n^{2}}$.


## The reverse isoperimetric inequality for Rotation invariant Log concave measures. The main result.

## Theorem (G. L., GAFA seminar notes, 2014)

Fix $n \geq 2$. Let $\gamma$ be log concave rotation invariant measure on $\mathbb{R}^{n}$. Consider a random vector $X$ in $\mathbb{R}^{n}$ distributed with respect to $\gamma$.

$$
\max _{Q \in \mathcal{K}_{n}} \gamma(\partial Q)=C \frac{\sqrt{n}}{\sqrt{\mathbb{E}|X|} \sqrt[4]{\operatorname{Var}|X|}}
$$

where $\mathbb{E}|X|$ and $\operatorname{Var}|X|$ denote the expectation and the variance of $X$ correspondingly.

- The above implies results by Ball and Nazarov: if $X$ is a standard Gaussian vector, $\mathbb{E}|X| \approx \sqrt{n}$ and $\operatorname{Var}|X| \approx 1$.
- The above is also applicable for normalized Lebesgue measure restricted on a unit ball: if $X$ is distributed uniformly in the unit ball, $\mathbb{E}|X| \approx 1$ and $\operatorname{Var}|X| \approx \frac{1}{n^{2}}$. The maximum for the surface area is attained on the unit sphere and is of order $n$.

Chapter 4: Gaussian surface area of a polytope with $K$ faces

## Gaussian surface area of a polytope with $K$ faces

Let $P=\cap_{i=1}^{K}\left\{\left\langle x, \theta_{i}\right\rangle \leq \rho_{i}\right\}$ be a polytope with at most $K$ faces.


## Gaussian surface area of a polytope with $K$ faces

Let $P=\cap_{i=1}^{K}\left\{\left\langle x, \theta_{i}\right\rangle \leq \rho_{i}\right\}$ be a polytope with at most $K$ faces.


## Theorem (F. Nazarov)

$$
\gamma_{2}(\partial P) \leq C \sqrt{\log K}
$$

for some absolute constant $C$.

## Gaussian surface area of a polytope with $K$ faces

Let $P=\cap_{i=1}^{K}\left\{\left\langle x, \theta_{i}\right\rangle \leq \rho_{i}\right\}$ be a polytope with at most $K$ faces.


## Theorem (F. Nazarov)

$$
\gamma_{2}(\partial P) \leq C \sqrt{\log K}
$$

for some absolute constant $C$.
What about log-concave rotation invariant case?

## Surface area of a polytope with $K$ faces with respect to LCRIPM: Upper bound

## Surface area of a polytope with $K$ faces with respect to LCRIPM: Upper bound

## Theorem (G.L., 2014)

Fix $n \geq 2$. Let $\gamma$ be log concave rotation invariant measure on $\mathbb{R}^{n}$. Consider a random vector $X$ in $\mathbb{R}^{n}$ distributed with respect to $\gamma$.

## Surface area of a polytope with $K$ faces with respect to LCRIPM: Upper

 bound
## Theorem (G.L., 2014)

Fix $n \geq 2$. Let $\gamma$ be log concave rotation invariant measure on $\mathbb{R}^{n}$. Consider a random vector $X$ in $\mathbb{R}^{n}$ distributed with respect to $\gamma$. Fix positive integer $K \in\left[2, \exp \left(\sqrt{\frac{c \mathbb{E}|X|}{\sqrt{\operatorname{Var}|X|}}}\right)\right]$. Let $P$ be a convex polytope in $\mathbb{R}^{n}$ with at most $K$ facets.

## Surface area of a polytope with $K$ faces with respect to LCRIPM: Upper

 bound
## Theorem (G.L., 2014)

Fix $n \geq 2$. Let $\gamma$ be log concave rotation invariant measure on $\mathbb{R}^{n}$. Consider a random vector $X$ in $\mathbb{R}^{n}$ distributed with respect to $\gamma$. Fix positive integer $K \in\left[2, \exp \left(\sqrt{\frac{c \mathbb{E}|X|}{\sqrt{\operatorname{Var}|X|}}}\right)\right]$. Let $P$ be a convex polytope in $\mathbb{R}^{n}$ with at most $K$ facets. Then

$$
\gamma(\partial P) \leq C \frac{\sqrt{n}}{\mathbb{E}|X|} \cdot \sqrt{\log K} \cdot \log \frac{\sqrt{\mathbb{E}|X|}}{\sqrt[4]{\operatorname{Var}|X|} \log K}
$$

## Surface area of a polytope with $K$ faces with respect to LCRIPM: Upper

 bound
## Theorem (G.L., 2014)

Fix $n \geq 2$. Let $\gamma$ be log concave rotation invariant measure on $\mathbb{R}^{n}$. Consider a random vector $X$ in $\mathbb{R}^{n}$ distributed with respect to $\gamma$. Fix positive integer $K \in\left[2, \exp \left(\sqrt{\frac{c \mathbb{E}|X|}{\sqrt{\operatorname{Var}|X|}}}\right)\right]$. Let $P$ be a convex polytope in $\mathbb{R}^{n}$ with at most $K$ facets. Then

$$
\gamma(\partial P) \leq C \frac{\sqrt{n}}{\mathbb{E}|X|} \cdot \sqrt{\log K} \cdot \log \frac{\sqrt{\mathbb{E}|X|}}{\sqrt[4]{\operatorname{Var}|X|} \log K}
$$

where $\mathbb{E}|X|$ and $\operatorname{Var}|X|$ denote the expectation and the variance of $X$ correspondingly, and $C$ and $c$ stand for absolute constants.

## Surface area of a polytope with $K$ faces with respect to LCRIPM: Upper bound

## Theorem (G.L., 2014)

Fix $n \geq 2$. Let $\gamma$ be log concave rotation invariant measure on $\mathbb{R}^{n}$. Consider a random vector $X$ in $\mathbb{R}^{n}$ distributed with respect to $\gamma$. Fix positive integer $K \in\left[2, \exp \left(\sqrt{\frac{c \mathbb{E}|X|}{\sqrt{\operatorname{Var}|X|}}}\right)\right]$. Let $P$ be a convex polytope in $\mathbb{R}^{n}$ with at most $K$ facets. Then

$$
\gamma(\partial P) \leq C \frac{\sqrt{n}}{\mathbb{E}|X|} \cdot \sqrt{\log K} \cdot \log \frac{\sqrt{\mathbb{E}|X|}}{\sqrt[4]{\operatorname{Var}|X|} \log K}
$$

where $\mathbb{E}|X|$ and $\operatorname{Var}|X|$ denote the expectation and the variance of $X$ correspondingly, and $C$ and $c$ stand for absolute constants.

## Corollary

$$
\gamma(\partial P) \leq C \frac{\sqrt{n}}{\mathbb{E}|X|} \cdot \sqrt{\log K} \cdot \log n
$$

## Surface area of a polytope with $K$ faces with respect to LCRIPM: Lower bound

## Surface area of a polytope with $K$ faces with respect to LCRIPM: Lower bound

## Theorem (G.L., 2014)

Fix $n \geq 2$. Let $\gamma$ be log concave rotation invariant measure on $\mathbb{R}^{n}$. Consider a random vector $X$ in $\mathbb{R}^{n}$ distributed with respect to $\gamma$.

## Surface area of a polytope with $K$ faces with respect to LCRIPM: Lower bound

## Theorem (G.L., 2014)

Fix $n \geq 2$. Let $\gamma$ be log concave rotation invariant measure on $\mathbb{R}^{n}$. Consider a random vector $X$ in $\mathbb{R}^{n}$ distributed with respect to $\gamma$. Fix positive integer $K \in\left[2, \exp \left(\sqrt{\frac{c \mathbb{E}|X|}{\sqrt{\operatorname{Var}|X|}}}\right)\right]$. Then there exists a convex polytope $P$ in $\mathbb{R}^{n}$ with at most $K$ facets such that

## Surface area of a polytope with $K$ faces with respect to LCRIPM: Lower bound

## Theorem (G.L., 2014)

Fix $n \geq 2$. Let $\gamma$ be log concave rotation invariant measure on $\mathbb{R}^{n}$. Consider a random vector $X$ in $\mathbb{R}^{n}$ distributed with respect to $\gamma$. Fix positive integer $K \in\left[2, \exp \left(\sqrt{\frac{c \mathbb{E}|X|}{\sqrt{\operatorname{Var}|X|}}}\right)\right.$. Then there exists a convex polytope $P$ in $\mathbb{R}^{n}$ with at most $K$ facets such that

$$
\gamma(\partial P) \geq C^{\prime} \frac{\sqrt{n}}{\mathbb{E}|X|} \sqrt{\log K}
$$

## Surface area of a polytope with $K$ faces with respect to LCRIPM: Lower bound

## Theorem (G.L., 2014)

Fix $n \geq 2$. Let $\gamma$ be log concave rotation invariant measure on $\mathbb{R}^{n}$. Consider a random vector $X$ in $\mathbb{R}^{n}$ distributed with respect to $\gamma$. Fix positive integer $K \in\left[2, \exp \left(\sqrt{\frac{c \mathbb{E}|X|}{\sqrt{\operatorname{Var}|X|}}}\right)\right]$. Then there exists a convex polytope $P$ in $\mathbb{R}^{n}$ with at most $K$ facets such that

$$
\gamma(\partial P) \geq C^{\prime} \frac{\sqrt{n}}{\mathbb{E}|X|} \sqrt{\log K}
$$

where $\mathbb{E}|X|$ and $\operatorname{Var}|X|$ denote the expectation and the variance of $X$ correspondingly, and $C$ and $c$ stand for absolute constants.

## Surface area of a polytope with $K$ faces with respect to LCRIPM: Lower bound

## Theorem (G.L., 2014)

Fix $n \geq 2$. Let $\gamma$ be log concave rotation invariant measure on $\mathbb{R}^{n}$. Consider a random vector $X$ in $\mathbb{R}^{n}$ distributed with respect to $\gamma$. Fix positive integer $K \in\left[2, \exp \left(\sqrt{\frac{c \mathbb{E}|X|}{\sqrt{\operatorname{Var}|X|}}}\right)\right]$. Then there exists a convex polytope $P$ in $\mathbb{R}^{n}$ with at most $K$ facets such that

$$
\gamma(\partial P) \geq C^{\prime} \frac{\sqrt{n}}{\mathbb{E}|X|} \sqrt{\log K}
$$

where $\mathbb{E}|X|$ and $\operatorname{Var}|X|$ denote the expectation and the variance of $X$ correspondingly, and C and c stand for absolute constants.

- In particular, this Theorem shows that the result of Nazarov for the Gaussian case is exact.


## Chapter 5: On the Gaussian concentration

## On the Gaussian concentration

For a measurable set $Q \subset \mathbb{R}^{n}$ we define a function

$$
\alpha_{Q}(h): \mathbb{R}^{+} \rightarrow \mathbb{R}
$$

by

$$
\alpha_{Q}(h):=1-\gamma_{2}\left(Q+h B_{2}^{n}\right) .
$$

## On the Gaussian concentration

For a measurable set $Q \subset \mathbb{R}^{n}$ we define a function

$$
\alpha_{Q}(h): \mathbb{R}^{+} \rightarrow \mathbb{R}
$$

by

$$
\alpha_{Q}(h):=1-\gamma_{2}\left(Q+h B_{2}^{n}\right) .
$$

It is well known that for every measurable $Q \subset \mathbb{R}^{n}$ such that $\gamma_{2}(Q) \geq \frac{1}{2}$,

$$
\begin{equation*}
\alpha_{Q}(h) \leq \frac{1}{2} e^{-\frac{h^{2}}{2}} . \tag{1}
\end{equation*}
$$

## On the Gaussian concentration

For a measurable set $Q \subset \mathbb{R}^{n}$ we define a function

$$
\alpha_{Q}(h): \mathbb{R}^{+} \rightarrow \mathbb{R}
$$

by

$$
\alpha_{Q}(h):=1-\gamma_{2}\left(Q+h B_{2}^{n}\right) .
$$

It is well known that for every measurable $Q \subset \mathbb{R}^{n}$ such that $\gamma_{2}(Q) \geq \frac{1}{2}$,

$$
\begin{equation*}
\alpha_{Q}(h) \leq \frac{1}{2} e^{-\frac{h^{2}}{2}} . \tag{1}
\end{equation*}
$$

Moreover,

$$
\begin{equation*}
\gamma_{2}\left(Q+h B_{2}^{n}\right) \geq \gamma_{2}\left(H_{Q}+h B_{2}^{n}\right) \tag{2}
\end{equation*}
$$

where $H_{Q}$ is a half space such that $\gamma_{2}(Q)=\gamma_{2}\left(H_{Q}\right)$.

## On the Gaussian concentration

For a measurable set $Q \subset \mathbb{R}^{n}$ we define a function

$$
\alpha_{Q}(h): \mathbb{R}^{+} \rightarrow \mathbb{R}
$$

by

$$
\alpha_{Q}(h):=1-\gamma_{2}\left(Q+h B_{2}^{n}\right) .
$$

It is well known that for every measurable $Q \subset \mathbb{R}^{n}$ such that $\gamma_{2}(Q) \geq \frac{1}{2}$,

$$
\begin{equation*}
\alpha_{Q}(h) \leq \frac{1}{2} e^{-\frac{h^{2}}{2}} . \tag{1}
\end{equation*}
$$

Moreover,

$$
\begin{equation*}
\gamma_{2}\left(Q+h B_{2}^{n}\right) \geq \gamma_{2}\left(H_{Q}+h B_{2}^{n}\right) \tag{2}
\end{equation*}
$$

where $H_{Q}$ is a half space such that $\gamma_{2}(Q)=\gamma_{2}\left(H_{Q}\right)$.

## Theorem (G.L., 2014)

$$
\alpha_{Q}(h) \leq 1-\gamma_{2}(Q)-\frac{\sqrt{\pi} \gamma_{2}(\partial Q)^{2}}{8 \sqrt{n}} \cdot\left(1-e^{-\frac{\sqrt{n}}{\sqrt{\pi} \gamma_{2}(\partial Q)} h}\right) .
$$

## Chapter 6: the Gaussian Brunn-Minkowski inequality

## Classical Brunn-Minkowski inequality

## Classical Brunn-Minkowski inequality

Recall: the Minkowski sum of the sets $K$ and $Q$ in $\mathbb{R}^{n}$ is the set


## Classical Brunn-Minkowski inequality

Recall: the Minkowski sum of the sets $K$ and $Q$ in $\mathbb{R}^{n}$ is the set


The $\lambda$-dilate of a set $A$ in $\mathbb{R}^{n}$ is the set

$$
\lambda A:=\{\lambda a \mid a \in A\} .
$$

## Classical Brunn-Minkowski inequality

Recall: the Minkowski sum of the sets $K$ and $Q$ in $\mathbb{R}^{n}$ is the set

$$
K+Q=\{a+b \mid a \in K, b \in Q\} .
$$

The $\lambda$-dilate of a set $A$ in $\mathbb{R}^{n}$ is the set

$$
\lambda A:=\{\lambda a \mid a \in A\} .
$$

## Brunn-Minkowski inequality

The classical Brunn-Minkowski inequality states that for any measurable sets $A, B \subset \mathbb{R}^{n}$ and for any $\lambda \in[0,1]$,

$$
|\lambda A+(1-\lambda) B|^{\frac{1}{n}} \geq \lambda|A|^{\frac{1}{n}}+(1-\lambda)|B|^{\frac{1}{n}},
$$

where $|\cdot|$ stands for the Lebesgue Measure on $\mathbb{R}^{n}$.

## The Brunn-Minkowski inequality and "shadow systems" (highlights of the work done by Colesanti)

## The support function of a convex set

Recall, that the support function $h_{Q}$ of a convex set $Q \subset \mathbb{R}^{2}$ is the function on the unit sphere defined by

$$
h_{Q}(\theta)=\max _{x \in Q}\langle x, \theta\rangle .
$$

By homogeneity it extends from the sphere to the whole space. The support function represents the distance from the origin to the support hyperplane of a convex set in a given direction:


## The Brunn-Minkowski inequality and "shadow systems" (highlights of the work done by Colesanti)

## The support function of a convex set

Recall, that the support function $h_{Q}$ of a convex set $Q \subset \mathbb{R}^{2}$ is the function on the unit sphere defined by

$$
h_{Q}(\theta)=\max _{x \in Q}\langle x, \theta\rangle .
$$

By homogeneity it extends from the sphere to the whole space. The support function represents the distance from the origin to the support hyperplane of a convex set in a given direction:


## The Brunn-Minkowski inequality and "shadow systems" (highlights of the work done by Colesanti)

The support function "shadow system"

## The Brunn-Minkowski inequality and "shadow systems" (highlights of the work done by Colesanti)

## The support function "shadow system"

Pick a positive number $a$. Let $h(u)$ be a strictly convex $C^{2}$-smooth function on the circle $\mathbb{S}^{1}$. Consider a function $\psi(u) \in C^{2}\left(\mathbb{S}^{1}\right)$. Let $s \in[0, a]$.

## The Brunn-Minkowski inequality and "shadow systems" (highlights of the work done by Colesanti)

## The support function "shadow system"

Pick a positive number $a$. Let $h(u)$ be a strictly convex $C^{2}$-smooth function on the circle $\mathbb{S}^{1}$. Consider a function $\psi(u) \in C^{2}\left(\mathbb{S}^{1}\right)$. Let $s \in[0, a]$. Consider a family of sets $K_{s}$ in $\mathbb{R}^{2}$, where the support function of each $K_{s}$ is $h_{s}=h+s \psi$.

$$
\mathbf{K}_{2}(h(u), \psi(u), a):=\left\{K_{s}\right\}_{s=0}^{a}
$$

## The Brunn-Minkowski inequality and "shadow systems" (highlights of the work done by Colesanti)

## The support function "shadow system"

Pick a positive number $a$. Let $h(u)$ be a strictly convex $C^{2}$-smooth function on the circle $\mathbb{S}^{1}$. Consider a function $\psi(u) \in C^{2}\left(\mathbb{S}^{1}\right)$. Let $s \in[0, a]$. Consider a family of sets $K_{s}$ in $\mathbb{R}^{2}$, where the support function of each $K_{s}$ is $h_{s}=h+s \psi$.

$$
\mathbf{K}_{2}(h(u), \psi(u), a):=\left\{K_{s}\right\}_{s=0}^{a}
$$



## The Brunn-Minkowski inequality and "shadow systems" (highlights of the work done by Colesanti)

## The support function "shadow system"

Pick a positive number $a$. Let $h(u)$ be a strictly convex $C^{2}$-smooth function on the circle $\mathbb{S}^{1}$. Consider a function $\psi(u) \in C^{2}\left(\mathbb{S}^{1}\right)$. Let $s \in[0, a]$. Consider a family of sets $K_{s}$ in $\mathbb{R}^{2}$, where the support function of each $K_{s}$ is $h_{s}=h+s \psi$.

$$
\mathbf{K}_{2}(h(u), \psi(u), a):=\left\{K_{s}\right\}_{s=0}^{a}
$$



1 A. Colesanti, From the Brunn-Minkowski inequality to a class of Poincare' type inequalities, Communications in Contemporary Mathematics, 10 n. 5 (2008), 765-772.

## Highlights of the work done by Colesanti

Each couple of sets can be "embedded" into a support function shadow system

## Highlights of the work done by Colesanti

Each couple of sets can be "embedded" into a support function shadow system
Pick convex sets $A$ and $B$ in $\mathbb{R}^{2}$ with the support functions $h_{A}(u)$ and $h_{B}(u)$. For $s \in[0,1]$, consider the "support function shadow system" $\left\{K_{s}\right\}$, where the support function of $K_{s}$ is $h_{s}=h_{A}+s\left(h_{B}-h_{A}\right)$. This way, $K_{0}=A$ and $K_{1}=B$.

## Highlights of the work done by Colesanti

Each couple of sets can be "embedded" into a support function shadow system
Pick convex sets $A$ and $B$ in $\mathbb{R}^{2}$ with the support functions $h_{A}(u)$ and $h_{B}(u)$. For $s \in[0,1]$, consider the "support function shadow system" $\left\{K_{s}\right\}$, where the support function of $K_{s}$ is $h_{s}=h_{A}+s\left(h_{B}-h_{A}\right)$. This way, $K_{0}=A$ and $K_{1}=B$.

The Brunn-Minkowski inequality for convex sets $A, B$ in $\mathbb{R}^{2}$

$$
|\lambda A+(1-\lambda) B|^{\frac{1}{2}} \geq \lambda|A|^{\frac{1}{2}}+(1-\lambda)|B|^{\frac{1}{2}}
$$

follows from the fact that the function $f(s):=\left|K_{s}\right|^{\frac{1}{2}}$ is concave in $s$ on $[0,1]$.

## Highlights of the work done by Colesanti

Each couple of sets can be "embedded" into a support function shadow system
Pick convex sets $A$ and $B$ in $\mathbb{R}^{2}$ with the support functions $h_{A}(u)$ and $h_{B}(u)$. For $s \in[0,1]$, consider the "support function shadow system" $\left\{K_{s}\right\}$, where the support function of $K_{s}$ is $h_{s}=h_{A}+s\left(h_{B}-h_{A}\right)$. This way, $K_{0}=A$ and $K_{1}=B$.

The Brunn-Minkowski inequality for convex sets $A, B$ in $\mathbb{R}^{2}$

$$
|\lambda A+(1-\lambda) B|^{\frac{1}{2}} \geq \lambda|A|^{\frac{1}{2}}+(1-\lambda)|B|^{\frac{1}{2}}
$$

follows from the fact that the function $f(s):=\left|K_{s}\right|^{\frac{1}{2}}$ is concave in $s$ on $[0,1]$.

## Claim

The Brunn-Minkowski inequality holds true for every pair of convex sets in $\mathbb{R}^{2}$ if and only if for every convex smooth function $h(u)$ on $\mathbb{S}^{1}$ and for every smooth function $\psi(u)$ on $\mathbb{S}^{1}$,

$$
f^{\prime \prime}(0)=\left.\left(\left|K_{s}\right|^{\frac{1}{2}}\right)^{\prime \prime}\right|_{s=0} \leq 0
$$

## The Gaussian Brunn-Minkowski inequality

Can we replace the standard Lebesgue measure with other measures?

## The Gaussian Brunn-Minkowski inequality

Can we replace the standard Lebesgue measure with other measures?

Recall: the standard Gaussian Measure $\gamma_{2}$ on $\mathbb{R}^{n}$ is the measure with density

$$
\left(\frac{1}{\sqrt{2 \pi}}\right)^{n} e^{-\frac{|y|^{2}}{2}}
$$



## The Gaussian Brunn-Minkowski inequality

Can we replace the standard Lebesgue measure with other measures?

Recall: the standard Gaussian Measure $\gamma_{2}$ on $\mathbb{R}^{n}$ is the measure with density

$$
\left(\frac{1}{\sqrt{2 \pi}}\right)^{n} e^{-\frac{|y|^{2}}{2}}
$$



## Gaussian Brunn-Minkowski inequality

Gardner and Zvavitch conjectured that for the standard Gaussian measure $\gamma_{2}$ the inequality analogous to BM holds under some natural assumptions on the sets $A$ and $B$ in $\mathbb{R}^{n}$ :

$$
\gamma_{2}(\lambda A+(1-\lambda) B)^{\frac{1}{n}} \geq \lambda \gamma_{2}(A)^{\frac{1}{n}}+(1-\lambda) \gamma_{2}(B)^{\frac{1}{n}}
$$

## The Gaussian Brunn-Minkowski inequality

Gaussian Brunn-Minkowski inequality

$$
\begin{equation*}
\gamma_{2}(\lambda A+(1-\lambda) B)^{\frac{1}{n}} \geq \lambda \gamma_{2}(A)^{\frac{1}{n}}+(1-\lambda) \gamma_{2}(B)^{\frac{1}{n}} \tag{3}
\end{equation*}
$$

Which assumptions on the sets $A$ and $B$ in $\mathbb{R}^{n}$ must be emposed in order for it to hold?

## The Gaussian Brunn-Minkowski inequality

## Gaussian Brunn-Minkowski inequality

$$
\begin{equation*}
\gamma_{2}(\lambda A+(1-\lambda) B)^{\frac{1}{n}} \geq \lambda \gamma_{2}(A)^{\frac{1}{n}}+(1-\lambda) \gamma_{2}(B)^{\frac{1}{n}} \tag{3}
\end{equation*}
$$

Which assumptions on the sets $A$ and $B$ in $\mathbb{R}^{n}$ must be emposed in order for it to hold?

The inequality (3) is false in the full generality: one may shift the set $A$ away from the origin. The farther the shift, the smaller the right hand side of (3) becomes, while the left hand side stays bounded from below by the fixed quantity $(1-\lambda) \gamma_{2}(B)^{\frac{1}{n}}$.


## The Gaussian Brunn-Minkowski inequality

## Gaussian Brunn-Minkowski inequality

$$
\begin{equation*}
\gamma_{2}(\lambda A+(1-\lambda) B)^{\frac{1}{n}} \geq \lambda \gamma_{2}(A)^{\frac{1}{n}}+(1-\lambda) \gamma_{2}(B)^{\frac{1}{n}} \tag{3}
\end{equation*}
$$

Which assumptions on the sets $A$ and $B$ in $\mathbb{R}^{n}$ must be emposed in order for it to hold?

The inequality (3) is false in the full generality: one may shift the set $A$ away from the origin. The farther the shift, the smaller the right hand side of (3) becomes, while the left hand side stays bounded from below by the fixed quantity $(1-\lambda) \gamma_{2}(B)^{\frac{1}{n}}$.


That gives a clue on which assumptions must be reinforced.

## Gaussian Brunn Minkowski inequality: questions

## Question 1

Gardner and Zvavitch asked: Does the Gaussian Brunn-Minkowski inequality hold true for all convex sets $A$ and $B$ containing the origin?

## Gaussian Brunn Minkowski inequality: questions

## Question 1

Gardner and Zvavitch asked: Does the Gaussian Brunn-Minkowski inequality hold true for all convex sets $A$ and $B$ containing the origin?

The answer is NO (obtained by Nayar, Tkozh).

## Gaussian Brunn Minkowski inequality: questions

## Question 1

Gardner and Zvavitch asked: Does the Gaussian Brunn-Minkowski inequality hold true for all convex sets $A$ and $B$ containing the origin?

The answer is NO (obtained by Nayar, Tkozh). Their counterexample looks roughly like this:


## Gaussian Brunn Minkowski inequality: questions

## Question 1

Gardner and Zvavitch asked: Does the Gaussian Brunn-Minkowski inequality hold true for all convex sets $A$ and $B$ containing the origin?

The answer is NO (obtained by Nayar, Tkozh). Their counterexample looks roughly like this:


## Question 2

Gardner, Zvavitch, and Nayar and Tkozh conjectured:The Gaussian Brunn-Minkowski inequality holds true for all symmetric convex sets $A$ and $B$.

## The approach

## Once again, a support function shadow system

Pick a positive number $a$. Let $h(u)$ be a strictly convex $C^{2}$-smooth function on the circle $\mathbb{S}^{1}$. Consider a function $\psi(u) \in C^{2}\left(\mathbb{S}^{1}\right)$. Let $s \in[0, a]$. Consider a family of sets $K_{s}$ in $\mathbb{R}^{2}$, where the support function of each $K_{s}$ is $h_{s}=h+s \psi$.

$$
\mathbf{K}_{2}(h(u), \psi(u), a):=\left\{K_{s}\right\}_{s=0}^{a}
$$

## The approach

## Once again, a support function shadow system

Pick a positive number $a$. Let $h(u)$ be a strictly convex $C^{2}-$ smooth function on the circle $\mathbb{S}^{1}$. Consider a function $\psi(u) \in C^{2}\left(\mathbb{S}^{1}\right)$. Let $s \in[0, a]$. Consider a family of sets $K_{s}$ in $\mathbb{R}^{2}$, where the support function of each $K_{s}$ is $h_{s}=h+s \psi$.

$$
\mathbf{K}_{2}(h(u), \psi(u), a):=\left\{K_{s}\right\}_{s=0}^{a}
$$

The Gaussian Brunn-Minkowski inequality for symmetric convex sets would be implied by the fact that $\left.\gamma_{2}\left(K_{s}\right)^{\prime \prime}\right|_{s=0} \leq 0$ for all such systems when $h$ and $\psi$ are even.

## The approach

## Once again, a support function shadow system

Pick a positive number $a$. Let $h(u)$ be a strictly convex $C^{2}$-smooth function on the circle $\mathbb{S}^{1}$. Consider a function $\psi(u) \in C^{2}\left(\mathbb{S}^{1}\right)$. Let $s \in[0, a]$. Consider a family of sets $K_{s}$ in $\mathbb{R}^{2}$, where the support function of each $K_{s}$ is $h_{s}=h+s \psi$.

$$
\mathbf{K}_{2}(h(u), \psi(u), a):=\left\{K_{s}\right\}_{s=0}^{a}
$$

The Gaussian Brunn-Minkowski inequality for symmetric convex sets would be implied by the fact that $\left.\gamma_{2}\left(K_{s}\right)^{\prime \prime}\right|_{s=0} \leq 0$ for all such systems when $h$ and $\psi$ are even. We need a formula expressing the standard Gaussian measure of a set in terms of the support function.

## The approach

## Once again, a support function shadow system

Pick a positive number $a$. Let $h(u)$ be a strictly convex $C^{2}$-smooth function on the circle $\mathbb{S}^{1}$. Consider a function $\psi(u) \in C^{2}\left(\mathbb{S}^{1}\right)$. Let $s \in[0, a]$. Consider a family of sets $K_{s}$ in $\mathbb{R}^{2}$, where the support function of each $K_{s}$ is $h_{s}=h+s \psi$.

$$
\mathbf{K}_{2}(h(u), \psi(u), a):=\left\{K_{s}\right\}_{s=0}^{a}
$$

The Gaussian Brunn-Minkowski inequality for symmetric convex sets would be implied by the fact that $\left.\gamma_{2}\left(K_{s}\right)^{\prime \prime}\right|_{s=0} \leq 0$ for all such systems when $h$ and $\psi$ are even. We need a formula expressing the standard Gaussian measure of a set in terms of the support function.

## Formula for the Gaussian measure via the support function

Let $\gamma_{2}$ be the Standard Gaussian measure in $\mathbb{R}^{2}$. Let $K$ be a strictly convex body in $\mathbb{R}^{2}$ containing the origin with the support function $h(u) \in C^{2}\left(\mathbb{S}^{1}\right)$.
Then

$$
\gamma_{2}(K)=\frac{1}{2 \pi} \int_{-\pi}^{\pi} \frac{h^{2}+h \ddot{h}}{h^{2}+\dot{h}^{2}}\left(1-e^{-\frac{h^{2}+\dot{म}^{2}}{2}}\right) d u
$$

## Sketch of the proof of the formula

$$
\gamma_{2}(K)=\frac{1}{2 \pi} \int_{-\pi}^{\pi} \frac{h^{2}+h \ddot{h}}{h^{2}+\dot{h}^{2}}\left(1-e^{-\frac{h^{2}+\dot{h}^{2}}{2}}\right) d u .
$$

## Proof.

## Sketch of the proof of the formula

$$
\gamma_{2}(K)=\frac{1}{2 \pi} \int_{-\pi}^{\pi} \frac{h^{2}+h \ddot{h}}{h^{2}+\dot{h}^{2}}\left(1-e^{-\frac{h^{2}+\dot{h}^{2}}{2}}\right) d u .
$$

## Proof.

- We write

$$
\gamma_{2}(K)=\frac{1}{2 \pi} \int_{K} e^{-\frac{|y|^{2}}{2}} d y
$$

## Sketch of the proof of the formula

$$
\gamma_{2}(K)=\frac{1}{2 \pi} \int_{-\pi}^{\pi} \frac{h^{2}+h \ddot{h}}{h^{2}+\dot{h}^{2}}\left(1-e^{-\frac{h^{2}+\dot{h}^{2}}{2}}\right) d u .
$$

## Proof.

- We write

$$
\gamma_{2}(K)=\frac{1}{2 \pi} \int_{K} e^{-\frac{|y|^{2}}{2}} d y
$$

- We make a change of variables $X: \partial K \times(0, \infty) \rightarrow \mathbb{R}^{2}$, where $X(y, t)=y t$. The Jacobian of such change is $t|y| \cos \left(y, n_{y}\right)$, where $n_{y}$ is the normal vector at $y$.


## Sketch of the proof of the formula

$$
\gamma_{2}(K)=\frac{1}{2 \pi} \int_{-\pi}^{\pi} \frac{h^{2}+h \ddot{h}}{h^{2}+\dot{h}^{2}}\left(1-e^{-\frac{h^{2}+\dot{h}^{2}}{2}}\right) d u .
$$

## Proof.

- We write

$$
\gamma_{2}(K)=\frac{1}{2 \pi} \int_{K} e^{-\frac{|y|^{2}}{2}} d y
$$

- We make a change of variables $X: \partial K \times(0, \infty) \rightarrow \mathbb{R}^{2}$, where $X(y, t)=y t$. The Jacobian of such change is $t|y| \cos \left(y, n_{y}\right)$, where $n_{y}$ is the normal vector at $y$.



## The proof of the formula

$$
\gamma_{2}(K)=\frac{1}{2 \pi} \int_{\partial K} \int_{0}^{1} t|y| \cos \left(y, n_{y}\right) e^{-\frac{(t|y|)^{2}}{2}} d t d \sigma(y)
$$

## The proof of the formula

$$
\gamma_{2}(K)=\frac{1}{2 \pi} \int_{\partial K} \int_{0}^{1} t|y| \cos \left(y, n_{y}\right) e^{-\frac{(t|y|)^{2}}{2}} d t d \sigma(y)
$$

- In the latter integral we make the change of variables via Gauss map, passing the integration from $\partial K$ to $\mathbb{S}^{1}$. The Jacobian of the Gauss map is the curvature function of $K$, which in the planar case is $h+\ddot{h}$, where $h$ is the support function of $K$.


## The proof of the formula

$$
\gamma_{2}(K)=\frac{1}{2 \pi} \int_{\partial K} \int_{0}^{1} t|y| \cos \left(y, n_{y}\right) e^{-\frac{(t|y|)^{2}}{2}} d t d \sigma(y)
$$

- In the latter integral we make the change of variables via Gauss map, passing the integration from $\partial K$ to $\mathbb{S}^{1}$. The Jacobian of the Gauss map is the curvature function of $K$, which in the planar case is $h+\ddot{h}$, where $h$ is the support function of $K$.

$$
\gamma_{2}(K)=\frac{1}{2 \pi} \int_{-\pi}^{\pi} h(h+\ddot{h}) \int_{0}^{1} t e^{-\frac{(t|\nabla h|)^{2}}{2}} d t d u
$$

## The proof of the formula

$$
\gamma_{2}(K)=\frac{1}{2 \pi} \int_{\partial K} \int_{0}^{1} t|y| \cos \left(y, n_{y}\right) e^{-\frac{(t|y|)^{2}}{2}} d t d \sigma(y)
$$

- In the latter integral we make the change of variables via Gauss map, passing the integration from $\partial K$ to $\mathbb{S}^{1}$. The Jacobian of the Gauss map is the curvature function of $K$, which in the planar case is $h+\ddot{h}$, where $h$ is the support function of $K$.

$$
\gamma_{2}(K)=\frac{1}{2 \pi} \int_{-\pi}^{\pi} h(h+\ddot{h}) \int_{0}^{1} t e^{-\frac{(t|\nabla h|)^{2}}{2}} d t d u
$$

- Observation that $|\nabla h|^{2}=h^{2}+\dot{h}^{2}$, and integration in $t$ leads to the desired conclusion

$$
\gamma_{2}(K)=\frac{1}{2 \pi} \int_{-\pi}^{\pi} \frac{h^{2}+h \ddot{h}}{h^{2}+\dot{h}^{2}}\left(1-e^{-\frac{h^{2}+\dot{म}^{2}}{2}}\right) d u . \square
$$

## The general statement

## The formula for any measure in $\mathbb{R}^{n}$

Let $\gamma$ be a measure in $\mathbb{R}^{n}$ with density $f(x)$. Let $K$ be a strictly convex body in $\mathbb{R}^{n}$ containing the origin with the support function $h(u) \in C^{2}\left(\mathbb{S}^{n-1}\right)$, where $u \in \mathbb{S}^{n-1}$. Let det $Q(h(u))$ be the curvature function of $K$. Denote the gradient of $h$ by $\nabla h$. Then

$$
\gamma(K)=\int_{\mathbb{S}^{n-1}} \frac{h(u) \operatorname{det} Q(h(u))}{|\nabla h(u)|^{n}} \int_{0}^{|\nabla h|} t^{n-1} f\left(t \cdot \frac{\nabla h}{|\nabla h|}\right) d t d u
$$

## The general statement

## The formula for any measure in $\mathbb{R}^{n}$

Let $\gamma$ be a measure in $\mathbb{R}^{n}$ with density $f(x)$. Let $K$ be a strictly convex body in $\mathbb{R}^{n}$ containing the origin with the support function $h(u) \in C^{2}\left(\mathbb{S}^{n-1}\right)$, where $u \in \mathbb{S}^{n-1}$. Let $\operatorname{det} Q(h(u))$ be the curvature function of $K$. Denote the gradient of $h$ by $\nabla h$. Then

$$
\gamma(K)=\int_{\mathbb{S}^{n-1}} \frac{h(u) \operatorname{det} Q(h(u))}{|\nabla h(u)|^{n}} \int_{0}^{|\nabla h|} t^{n-1} f\left(t \cdot \frac{\nabla h}{|\nabla h|}\right) d t d u .
$$

This formula might find its use in other questions, such as B-Theorem, S-Theorem, Isoperimetric inequalities etc.

## The neighborhood of the disc

## Once again, a shadow system for $h(u)=R$

Pick a positive number $a$. Pick a positive number $R$. Consider a function $\psi(u) \in C^{2}\left(\mathbb{S}^{1}\right)$. Let $s \in[0, a]$. Consider a family of sets $K_{s}$ in $\mathbb{R}^{2}$, where the support function of each $K_{s}$ is $h_{s}=R+s \psi$.

$$
\mathbf{K}_{2}(R, \psi(u), a):=\left\{K_{s}\right\}_{s=0}^{a}
$$

## The neighborhood of the disc

## Once again, a shadow system for $h(u)=R$

Pick a positive number $a$. Pick a positive number $R$. Consider a function $\psi(u) \in C^{2}\left(\mathbb{S}^{1}\right)$. Let $s \in[0, a]$. Consider a family of sets $K_{s}$ in $\mathbb{R}^{2}$, where the support function of each $K_{s}$ is $h_{s}=R+s \psi$.

$$
\mathbf{K}_{2}(R, \psi(u), a):=\left\{K_{s}\right\}_{s=0}^{a}
$$



## The neighborhood of the disc

## Once again, a shadow system for $h(u)=R$

Pick a positive number $a$. Pick a positive number $R$. Consider a function $\psi(u) \in C^{2}\left(\mathbb{S}^{1}\right)$. Let $s \in[0, a]$. Consider a family of sets $K_{s}$ in $\mathbb{R}^{2}$, where the support function of each $K_{s}$ is $h_{s}=R+s \psi$.

$$
\mathbf{K}_{2}(R, \psi(u), a):=\left\{K_{s}\right\}_{s=0}^{a}
$$



## Gaussian Brunn-Minkovski is true in a neighborhood of any disc

Pick $R \in(0, \infty)$. Fix $\psi \in C^{2}\left(\mathbb{S}^{1}\right)$. Then there exists an $\epsilon=\epsilon(R, \psi)$ such that for every $K, L \in \mathbf{K}_{2}(R, \psi, \epsilon)$ and for every $\lambda \in[0,1]$,

$$
\gamma_{2}^{\frac{1}{2}}(\lambda K+(1-\lambda) L) \geq \lambda \gamma_{2}^{\frac{1}{2}}(K)+(1-\lambda) \gamma_{2}^{\frac{1}{2}}(L)
$$

## Sketch of the proof

## Sketch of the proof

- We apply the formula for the Gaussian measure

$$
\gamma_{2}(K)=\frac{1}{2 \pi} \int_{-\pi}^{\pi} \frac{h^{2}+h \ddot{h}}{h^{2}+\dot{h}^{2}}\left(1-e^{-\frac{h^{2}+\dot{\dot{h}}^{2}}{2}}\right) d u
$$

when the support function of the set is $h=R+s \psi$

$$
\gamma(s):=\int_{-\pi}^{\pi} \frac{(R+s \psi)^{2}+(R+s \psi) s \ddot{\psi}}{(R+s \psi)^{2}+(s \dot{\psi})^{2}}\left(1-e^{-\frac{(R+s \psi)^{2}+(s \dot{\psi})^{2}}{2}}\right) d u .
$$

## Sketch of the proof

- We apply the formula for the Gaussian measure

$$
\gamma_{2}(K)=\frac{1}{2 \pi} \int_{-\pi}^{\pi} \frac{h^{2}+h \ddot{h}}{h^{2}+\dot{h}^{2}}\left(1-e^{-\frac{h^{2}+\dot{\dot{h}}^{2}}{2}}\right) d u
$$

when the support function of the set is $h=R+s \psi$

$$
\gamma(s):=\int_{-\pi}^{\pi} \frac{(R+s \psi)^{2}+(R+s \psi) s \ddot{\psi}}{(R+s \psi)^{2}+(s \dot{\psi})^{2}}\left(1-e^{-\frac{(R+s \psi)^{2}+(s \dot{\psi})^{2}}{2}}\right) d u .
$$

- We differentiate it at zero twice.


## Sketch of the proof

- We apply the formula for the Gaussian measure

$$
\gamma_{2}(K)=\frac{1}{2 \pi} \int_{-\pi}^{\pi} \frac{h^{2}+h \ddot{h}}{h^{2}+\dot{h}^{2}}\left(1-e^{-\frac{h^{2}+\dot{म}^{2}}{2}}\right) d u
$$

when the support function of the set is $h=R+s \psi$

$$
\gamma(s):=\int_{-\pi}^{\pi} \frac{(R+s \psi)^{2}+(R+s \psi) s \ddot{\psi}}{(R+s \psi)^{2}+(s \dot{\psi})^{2}}\left(1-e^{-\frac{(R+s \psi)^{2}+(s \dot{\psi})^{2}}{2}}\right) d u .
$$

- We differentiate it at zero twice. We observe that $(\sqrt{\gamma(s)})_{0}^{\prime \prime} \leq 0$ whenever

$$
2\left(e^{\frac{R^{2}}{2}}-1\right) \int\left[\left(1-R^{2}\right) \psi^{2}-\dot{\psi}^{2}\right]-R^{2}\left(\int \psi\right)^{2} \leq 0
$$

## Sketch of the proof

We want to prove that

$$
2\left(e^{\frac{R^{2}}{2}}-1\right) \int\left[\left(1-R^{2}\right) \psi^{2}-\dot{\psi}^{2}\right]-R^{2}\left(\int \psi\right)^{2} \leq 0
$$

## Sketch of the proof

We want to prove that

$$
2\left(e^{\frac{R^{2}}{2}}-1\right) \int\left[\left(1-R^{2}\right) \psi^{2}-\dot{\psi}^{2}\right]-R^{2}\left(\int \psi\right)^{2} \leq 0
$$

- We apply Poincare inequality.


## Sketch of the proof

We want to prove that

$$
2\left(e^{\frac{R^{2}}{2}}-1\right) \int\left[\left(1-R^{2}\right) \psi^{2}-\dot{\psi}^{2}\right]-R^{2}\left(\int \psi\right)^{2} \leq 0
$$

- We apply Poincare inequality.
- We arrive to an inequality

$$
2\left(e^{\frac{R^{2}}{2}}-1\right)\left(1-2 R^{2}\right)-R^{2}<0,
$$

for $R>0$

## Sketch of the proof

We want to prove that

$$
2\left(e^{\frac{R^{2}}{2}}-1\right) \int\left[\left(1-R^{2}\right) \psi^{2}-\dot{\psi}^{2}\right]-R^{2}\left(\int \psi\right)^{2} \leq 0
$$

- We apply Poincare inequality.
- We arrive to an inequality

$$
2\left(e^{\frac{R^{2}}{2}}-1\right)\left(1-2 R^{2}\right)-R^{2}<0,
$$

for $R>0$

## Sketch of the proof

We want to prove that

$$
2\left(e^{\frac{R^{2}}{2}}-1\right) \int\left[\left(1-R^{2}\right) \psi^{2}-\dot{\psi}^{2}\right]-R^{2}\left(\int \psi\right)^{2} \leq 0
$$

- We apply Poincare inequality.
- We arrive to an inequality

$$
2\left(e^{\frac{R^{2}}{2}}-1\right)\left(1-2 R^{2}\right)-R^{2}<0
$$

for $R>0$, which we brutal force. $\square$


# Thanks for your attention! 

