Math 1553 Supplement §4.2, 4.3

Solutions

- **1.** Let *A* be a 3×4 matrix with column vectors v_1, v_2, v_3, v_4 , and suppose $v_2 = 2v_1 3v_4$. Consider the matrix transformation T(x) = Ax.
 - a) Is it possible that T is one-to-one? If yes, justify why. If no, find distinct vectors v and w so that T(v) = T(w).
 - **b)** Is it possible that *T* is onto? Justify your answer.

Solution.

a) From the linear dependence condition we were given, we get

$$-2v_1 + v_2 + 3v_4 = 0.$$

The corresponding vector equation is just

$$\begin{pmatrix} v_1 & v_2 & v_3 & v_4 \end{pmatrix} \begin{pmatrix} -2 \\ 1 \\ 0 \\ 3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}, \quad \text{so} \quad A \begin{pmatrix} -2 \\ 1 \\ 0 \\ 3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}.$$

Therefore, $v = \begin{pmatrix} -2\\1\\0\\3 \end{pmatrix}$ and $w = \begin{pmatrix} 0\\0\\0\\0 \end{pmatrix}$ both satisfy Av = Aw = 0, so T cannot be

b) Yes. If $\{v_1, v_3, v_4\}$ is linearly independent then *A* will have a pivot in every row and *T* will be onto. Such a matrix *A* is

$$A = \begin{pmatrix} 1 & 2 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & -3 & 0 & 1 \end{pmatrix}.$$

- **2.** Which of the following transformations *T* are onto? Which are one-to-one? If the transformation is not onto, find a vector not in the range. If the matrix is not one-to-one, find two vectors with the same image.
 - a) The transformation $T: \mathbb{R}^3 \to \mathbb{R}^2$ defined by T(x, y, z) = (y, y).
 - **b)** JUST FOR FUN: Consider T: (Smooth functions) \rightarrow (Smooth functions) given by T(f) = f' (the derivative of f). Then T is not a transformation from any \mathbf{R}^n to \mathbf{R}^m , but it is still *linear* in the sense that for all smooth f and g and all scalars g (by properties of differentiation we learned in Calculus 1):

$$T(f+g) = T(f) + T(g) \quad \text{since} \quad (f+g)' = f' + g'$$
$$T(cf) = cT(f) \quad \text{since} \quad (cf)' = cf'.$$

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Is *T* one-to-one?

2 Solutions

Solution.

a) This is not onto. Everything in the range of T has its first coordinate equal to its second, so there is no (x, y, z) such that T(x, y, z) = (1, 0). It is not one-to-one: for instance, T(0, 0, 0) = (0, 0) = T(0, 0, 1).

- **b)** T is not one-to-one. If T were one-to-one, then for any smooth function b, the equation T(f) = b would have at most one solution. However, Note that if f and g are the functions f(t) = t and g(t) = t 1, then f and g are different functions but their derivatives are the same, so T(f) = T(g). Therefore, T is not one-to-one. It is not within the scope of Math 1553. If you find it confusing, feel free to ignore it.
- **3.** In each case, determine whether *T* is linear. Briefly justify.

a)
$$T(x_1, x_2) = (x_1 - x_2, x_1 + x_2, 1)$$
.

- **b)** $T(x,y) = (y,x^{1/3}).$
- c) T(x, y, z) = 2x 5z.

Solution.

- a) Not linear. $T(0,0) = (0,0,1) \neq (0,0,0)$.
- **b)** Not linear. The $x^{1/3}$ term gives it away. $T(0,2) = (0,2^{1/3})$ but 2T(0,1) = (0,2).
- c) Linear. In fact, T(v) = Av where

$$A = \begin{pmatrix} 2 & 0 & -5 \end{pmatrix}.$$

4. For each matrix A, describe what the associated matrix transformation T does to \mathbf{R}^3 geometrically.

a)
$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$
 b) $\begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$

Solution.

a) We compute

$$T\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} x \\ -y \\ z \end{pmatrix}.$$

This is the reflection over the xz-plane.

b)

$$T\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} y \\ x \\ 0 \end{pmatrix}.$$

This is projection onto the xy-plane, followed by reflection over the line y = x.

5. Let's go back to the 4.2-4.3 worksheet problem #3. The second little pig has decided to build his house out of sticks. His house is shaped like a pyramid with a triangular base that has vertices at the points (0,0,0), (2,0,0), (0,2,0), and (1,1,1).

The big bad wolf finds the pig's house and blows it down so that the house is rotated by an angle of 45° in a counterclockwise direction about the *z*-axis (look downward onto the *xy*- plane the way we usually picture the plane as \mathbb{R}^2), and then projected onto the *xy*-plane.

In the worksheet, we found the matrix for the transformation T caused by the wolf. Geometrically describe the image of the house under T.

Solution.

In the worksheet, we found T(x) = Ax where

$$A = \begin{pmatrix} & | & & | & & | \\ T(e_1) & T(e_2) & T(e_3) & & | & | \\ & | & & | & & | \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & -1 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}.$$

We know the house has been effectively destroyed, but what do its remains look like? To get an idea, let's look at what happens to the vertices.

$$\frac{1}{\sqrt{2}} \begin{pmatrix} 1 & -1 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}, \qquad \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & -1 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 2 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} \sqrt{2} \\ \sqrt{2} \\ 0 \end{pmatrix}$$
$$\frac{1}{\sqrt{2}} \begin{pmatrix} 1 & -1 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 2 \\ 0 \end{pmatrix} = \begin{pmatrix} -\sqrt{2} \\ \sqrt{2} \\ 0 \end{pmatrix} \qquad \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & -1 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ \sqrt{2} \\ 0 \end{pmatrix}.$$

This indicates the pyramid has been squashed into a triangle in the xy-plane with

vertices
$$\begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$
, $\begin{pmatrix} \sqrt{2} \\ \sqrt{2} \\ 0 \end{pmatrix}$, $\begin{pmatrix} -\sqrt{2} \\ \sqrt{2} \\ 0 \end{pmatrix}$. (the point $\begin{pmatrix} 0 \\ \sqrt{2} \\ 0 \end{pmatrix}$ is along the top side of this triangle).

Effectively, the pyramid was rotated and then destroyed, so that its (rotated) base is all that remains.