# MATH 1553, FALL 2018 SAMPLE MIDTERM 2: 3.5 THROUGH 4.4

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Write your section number here:			

Please **read all instructions** carefully before beginning.

- The maximum score on this exam is 50 points.
- You have 50 minutes to complete this exam.
- There are no aids of any kind (calculators, notes, text, etc.) allowed.
- Please show your work unless instructed otherwise. A correct answer without appropriate work will receive little or no credit. If you cannot fit your work on the front side of the page, use the back side of the page as indicated.
- You may cite any theorem proved in class or in the sections we covered in the text.
- Good luck!

This is a practice exam. It is meant to be similar in format, length, and difficulty to the real exam. It is **not** meant as a comprehensive list of study problems. I recommend completing the practice exam in 50 minutes, without notes or distractions.

The exam is not designed to test material from the previous midterm on its own. However, knowledge of the material prior to section §3.5 is necessary for everything we do for the rest of the semester, so it is fair game for the exam as it applies to §§3.5 through 4.4.

These problems are true or false. Circle **T** if the statement is *always* true. Otherwise, answer **F**. You do not need to justify your answer.

- a) **T F** Suppose *A* is a matrix with more columns than rows. Then the matrix transformation T(x) = Ax cannot be one-to-one.
- b) **T F** If *A* is an  $n \times n$  matrix and Ax = 0 has only the trivial solution, then the equation Ax = b is consistent for every b in  $\mathbb{R}^n$ .
- c) **T F** If A and B are  $3 \times 3$  matrices and the columns of B are linearly dependent, then the columns of AB are linearly dependent.
- d) **T** F There are linear transformations  $T: \mathbb{R}^4 \to \mathbb{R}^3$  and  $U: \mathbb{R}^3 \to \mathbb{R}^4$  so that  $T \circ U$  is onto.
- e)  $\mathbf{T}$   $\mathbf{F}$   $V = \left\{ \begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix} \text{ in } \mathbf{R}^4 \mid x y = 1 + w \right\}$  is a subspace of  $\mathbf{R}^4$ .

#### Solution.

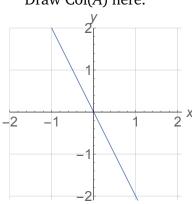
- **a)** True. *A* cannot have more pivots than rows, and since there are more columns than rows, this means *A* cannot have a pivot in every column.
- **b)** True. Since Ax = 0 has only the trivial solution, A has a pivot in each of its n columns, so A has n pivots. Therefore, A has a pivot in each of its n rows, hence Ax = b is consistent for every b in  $\mathbb{R}^n$ .
- c) True. Bv = 0 for some nonzero v in  $\mathbb{R}^3$ , so ABv = A(Bv) = A0 = 0. Therefore, v is a non-trivial solution to ABx = 0, so the columns of AB are linearly dependent.
- **d)** True. Take  $U(x_1, x_2, x_3) = (x_1, x_2, x_3, 0)$  and  $T(x_1, x_2, x_3, x_4) = (x_1, x_2, x_3)$ . Then  $(T \circ U)(x_1, x_2, x_3) = (x_1, x_2, x_3)$  so  $T \circ U$  is onto (in fact, it is also one-to-one: it is the identity transformation!)
- e) False: V doesn't contain the zero vector, so we see immediately that it is not a subspace of  $\mathbb{R}^4$ .

Extra space for scratch work on problem 1

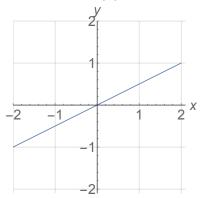
Parts (a) to (d) are unrelated. You do not need to justify answers in (a) or (b).

- **a)** Write three different nonzero vectors  $v_1$ ,  $v_2$ ,  $v_3$  in  $\mathbb{R}^3$  so that  $\{v_1, v_2, v_3\}$  is linearly dependent but  $v_3$  is not in Span $\{v_1, v_2\}$ . Clearly indicate which vector is  $v_3$ .
- **b)** Fill in the blanks: If *A* is a  $5 \times 6$  matrix and its column span has dimension 2, then the null space of *A* is \_\_\_\_\_\_-dimensional subspace of  $\mathbf{R}$
- c) Let  $A = \begin{pmatrix} 1 & 0 & -2 \\ 2 & 0 & -4 \\ -4 & 0 & 8 \end{pmatrix}$ . Find nonzero vectors x and y in  $\mathbf{R}^3$  so that Ax = Ay but  $x \neq y$ .
- **d)** Let  $A = \begin{pmatrix} 1 & -2 \\ -2 & 4 \end{pmatrix}$ . Clearly draw Col(A) and Nul(A). Briefly show work.

Draw Col(A) here.



Draw Nul(A) here.



# Solution.

- **a)** Many examples possible. For example,  $v_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$ ,  $v_2 = \begin{pmatrix} 2 \\ 0 \\ 0 \end{pmatrix}$ ,  $v_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$ .
- **b)** Nul *A* is a subspace of  $\mathbb{R}^6$ , and dim(Col *A*) + dim(Nul *A*) = 6 so 2 + dim(Nul *A*) = 6. Thus Nul *A* is a 4-dimensional subspace of  $\mathbb{R}^6$ .
- c) We find two nonzero vectors in Nul A.  $(A \mid 0) \rightarrow \begin{pmatrix} 1 & 0 & -2 \mid 0 \\ 0 & 0 & 0 \mid 0 \\ 0 & 0 & 0 \mid 0 \end{pmatrix}$ , so  $x_1 = 2x_3$  and  $x_2$  and  $x_3$  are free. We can take  $x = \begin{pmatrix} 2 \\ 0 \\ 1 \end{pmatrix}$  and  $y = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$ , as Ax = Ay = 0.
- **d)** Col(A) is the span of  $\begin{pmatrix} 1 \\ -2 \end{pmatrix}$ ; Nul(A) is the span of  $\begin{pmatrix} 2 \\ 1 \end{pmatrix}$ .

Problem 3. [10 points]

Let  $T: \mathbf{R}^2 \to \mathbf{R}^2$  be the transformation of reflection about the line y = x, and let  $U: \mathbf{R}^2 \to \mathbf{R}^3$  be the transformation  $U \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x - y \\ x \\ 3y \end{pmatrix}$ .

- **a)** Write the standard matrix *A* for *T* . Is *T* onto?
- **b)** Write the standard matrix *B* for *U*. Is *U* one-to-one? Briefly justify your answer.
- **c)** Circle the composition that makes sense:  $T \circ U$   $U \circ T$
- d) Compute the standard matrix for the composition you circled in part (c).

#### Solution.

- a)  $A = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ . Yes, T is onto.
- **b)**  $B = \begin{pmatrix} U(e_1) & U(e_2) \end{pmatrix} = \begin{pmatrix} 1 & -1 \\ 1 & 0 \\ 0 & 3 \end{pmatrix}$ . Yes, U is one-to-one because B has a pivot in every column.
- c)  $U \circ T$  makes sense since it sends  $R^2 \to R^2 \to R^3$ .
- **d)**  $BA = \begin{pmatrix} 1 & -1 \\ 1 & 0 \\ 0 & 3 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} -1 & 1 \\ 0 & 1 \\ 3 & 0 \end{pmatrix}.$

Problem 4. [10 points]

Dino McBarker has put the matrix *A* below in its reduced row echelon form:

$$A = \begin{pmatrix} 1 & -2 & 0 & 4 \\ -7 & 14 & 3 & 2 \\ 4 & -8 & -2 & -4 \end{pmatrix} \xrightarrow{RREF} \begin{pmatrix} 1 & -2 & 0 & 4 \\ 0 & 0 & 1 & 10 \\ 0 & 0 & 0 & 0 \end{pmatrix}.$$

- a) Find a basis  $\mathcal{B}$  for Nul(A).
- **b)** Is  $x = \begin{pmatrix} 2 \\ 3 \\ -10 \\ 1 \end{pmatrix}$  in Nul(A)? If so, write x as a linear combination of your basis vectors from part (a). If not, justify why x is not in Nul(A).

c) Is  $\begin{pmatrix} 0 \\ -3 \\ 2 \end{pmatrix}$  in Col(A)? You do not need to justify your answer.

### Solution.

a) The RREF of A shows that if Ax = 0 then

$$x_{1} = 2x_{2} - 4x_{4}, \ x_{2} = x_{2}, \ x_{3} = -10x_{4}, \ x_{4} = x_{4}.$$

$$So\begin{pmatrix} x_{1} \\ x_{2} \\ x_{3} \\ x_{4} \end{pmatrix} = \begin{pmatrix} 2x_{2} - 4x_{4} \\ x_{2} \\ -10x_{4} \\ x_{4} \end{pmatrix} = x_{2} \begin{pmatrix} 2 \\ 1 \\ 0 \\ 0 \end{pmatrix} + x_{4} \begin{pmatrix} -4 \\ 0 \\ -10 \\ 1 \end{pmatrix}. \text{ Thus } \mathcal{B} = \left\{ \begin{pmatrix} 2 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} -4 \\ 0 \\ -10 \\ 1 \end{pmatrix} \right\}.$$

$$\begin{pmatrix} 2 & -4 & 2 \\ 1 & 0 & 3 \\ 0 & -10 & -10 \\ 0 & 1 & 1 \end{pmatrix} \xrightarrow{R_1 \hookrightarrow R_2} \begin{pmatrix} 1 & 0 & 3 \\ 2 & -4 & 2 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \end{pmatrix} \xrightarrow{R_2 = R_2 - 2R_1} \begin{pmatrix} 1 & 0 & 3 \\ 0 & -4 & -4 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{pmatrix} \xrightarrow{R_2 = R_2 / -4} \begin{pmatrix} 1 & 0 & 3 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{pmatrix}.$$

Therefore, 
$$x$$
 is in Nul( $A$ ), in fact  $x = 3 \begin{pmatrix} 2 \\ 1 \\ 0 \\ 0 \end{pmatrix} + \begin{pmatrix} -4 \\ 0 \\ -10 \\ 1 \end{pmatrix}$ .

c) Yes.  $\begin{pmatrix} 0 \\ -3 \\ 2 \end{pmatrix}$  is (-1)\* (third column of A) so it is in Col(A), no work required.

Problem 5. [8 points]

Parts (a), (b), and (c) are unrelated.

You do not need to show any work for parts (a) and (b).

- a) I. Is the set  $\left\{ \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 4 \end{pmatrix} \right\}$  linearly independent? YES NO
  - II. If *A* is a  $3 \times 3$  matrix, is it possible that Col(A) = Nul(A)?

(dimensions add to 3, so they can't even have the same dimension)

**b)** Give a specific example of a subspace of  $\mathbb{R}^3$  that contains  $\begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix}$ .

(You may express this subspace any way you like, as long as you are clear.)

There are endless possibilities. For example,  $\mathbb{R}^3$  itself, or Span  $\left\{ \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix} \right\}$ .

c) Write a  $2 \times 3$  matrix A and a  $3 \times 2$  matrix B so that AB is the standard matrix for the transformation of *clockwise* rotation by  $90^{\circ}$  in  $\mathbb{R}^2$ . Compute AB to demonstrate that your answer is correct.

Many possibilities. For example,  $A = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}$  and  $B = \begin{pmatrix} 0 & 1 \\ -1 & 0 \\ 0 & 0 \end{pmatrix}$ .

 $AB = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ -1 & 0 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}, \text{ which is clockwise rotation by } 90^{\circ}.$