## Supplemental problems: Chapter 4, Determinants

- **1.** If *A* is an  $n \times n$  matrix, is it necessarily true that det(-A) = -det(A)? Justify your answer.
- **2.** Let *A* be an  $n \times n$  matrix.
  - a) Using cofactor expansion, explain why det(A) = 0 if A has a row or a column of zeros.
  - **b)** Using cofactor expansion, explain why det(A) = 0 if A has adjacent identical columns.
- **3.** Find the volume of the parallelepiped in  $\mathbf{R}^4$  naturally determined by the vectors

$$\begin{pmatrix} 4 \\ 1 \\ 3 \\ 8 \end{pmatrix}, \quad \begin{pmatrix} 0 \\ 7 \\ 0 \\ 3 \end{pmatrix}, \quad \begin{pmatrix} 0 \\ 2 \\ 0 \\ 1 \end{pmatrix}, \quad \begin{pmatrix} 5 \\ -5 \\ 0 \\ 7 \end{pmatrix}.$$

- **4.** Let  $A = \begin{pmatrix} -1 & 1 \\ 1 & 7 \end{pmatrix}$ , and define a transformation  $T : \mathbb{R}^2 \to \mathbb{R}^2$  by T(x) = Ax. Find the area of T(S), if *S* is a triangle in  $\mathbb{R}^2$  with area 2.
- **5.** Let

$$A = \begin{pmatrix} 2 & -8 & 6 & 8 \\ 3 & -9 & 5 & 10 \\ -3 & 0 & 1 & -2 \\ 1 & -4 & 0 & 6 \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} 0 & 1 & 5 & 4 \\ 1 & -1 & -3 & 0 \\ -1 & 0 & 5 & 4 \\ 3 & -3 & -2 & 5 \end{pmatrix}$$

- a) Compute det(A).
- **b)** Compute det(*B*).
- c) Compute det(AB).
- **d)** Compute det( $A^2B^{-1}AB^2$ ).
- **6.** If *A* is a  $3 \times 3$  matrix and det(*A*) = 1, what is det(-2A)?
- a) Is there a real 2 × 2 matrix *A* that satisfies A<sup>4</sup> = -I<sub>2</sub>? Either write such an *A*, or show that no such *A* exists.
   (hint: think geometrically! The matrix -I<sub>2</sub> represents rotation by *π* radians).
  - **b)** Is there a real  $3 \times 3$  matrix *A* that satisfies  $A^4 = -I_3$ ? Either write such an *A*, or show that no such *A* exists.

## Supplemental problems: §5.1

- **1.** True or false. Answer true if the statement is always true. Otherwise, answer false.
  - a) If *A* and *B* are  $n \times n$  matrices and *A* is row equivalent to *B*, then *A* and *B* have the same eigenvalues.
  - **b)** If *A* is an  $n \times n$  matrix and its eigenvectors form a basis for  $\mathbb{R}^n$ , then *A* is invertible.
  - c) If 0 is an eigenvalue of the  $n \times n$  matrix A, then rank(A) < n.
  - **d)** The diagonal entries of an  $n \times n$  matrix *A* are its eigenvalues.
  - e) If A is invertible and 2 is an eigenvalue of A, then  $\frac{1}{2}$  is an eigenvalue of  $A^{-1}$ .
  - f) If det(A) = 0, then 0 is an eigenvalue of A.
- **2.** In this problem, you need not explain your answers; just circle the correct one(s).

Let *A* be an  $n \times n$  matrix.

- a) Which one of the following statements is correct?
  - 1. An eigenvector of *A* is a vector *v* such that  $Av = \lambda v$  for a nonzero scalar  $\lambda$ .
  - 2. An eigenvector of *A* is a nonzero vector *v* such that  $Av = \lambda v$  for a scalar  $\lambda$ .
  - 3. An eigenvector of *A* is a nonzero scalar  $\lambda$  such that  $Av = \lambda v$  for some vector *v*.
  - 4. An eigenvector of *A* is a nonzero vector *v* such that  $Av = \lambda v$  for a nonzero scalar  $\lambda$ .
- b) Which one of the following statements is not correct?
  - 1. An eigenvalue of *A* is a scalar  $\lambda$  such that  $A \lambda I$  is not invertible.
  - 2. An eigenvalue of *A* is a scalar  $\lambda$  such that  $(A \lambda I)v = 0$  has a solution.
  - 3. An eigenvalue of *A* is a scalar  $\lambda$  such that  $Av = \lambda v$  for a nonzero vector v.
  - 4. An eigenvalue of *A* is a scalar  $\lambda$  such that det $(A \lambda I) = 0$ .
- **3.** Find a basis  $\mathcal{B}$  for the (-1)-eigenspace of  $Z = \begin{pmatrix} 2 & 3 & 1 \\ 3 & 2 & 4 \\ 0 & 0 & -1 \end{pmatrix}$
- **4.** Suppose *A* is an  $n \times n$  matrix satisfying  $A^2 = 0$ . Find all eigenvalues of *A*. Justify your answer.

**5.** Match the statements (i)-(v) with the corresponding statements (a)-(e). All matrices are  $3 \times 3$ . There is a unique correspondence. Justify the correspondences in words.

(i) 
$$Ax = \begin{pmatrix} 5\\1\\2 \end{pmatrix}$$
 has a unique solution.

(ii) The transformation T(v) = Av fixes a nonzero vector.

(iii) *A* is obtained from *B* by subtracting the third row of *B* from the first row of *B*.(iv) The columns of *A* and *B* are the same; except that the first, second and third columns of A are respectively the first, third, and second columns of *B*.(v) The columns of *A*, when added, give the zero vector.

(a) 0 is an eigenvalue of *A*.
(b) *A* is invertible.
(c) det(*A*) = det(*B*)
(d) det(*A*) = - det(*B*)
(e) 1 is an eigenvalue of *A*.