Math 1553 Conceptual question list §§2.6-3.6

Worksheet 5 (2.6-3.2)

- **1.** Circle **TRUE** if the statement is always true, and circle **FALSE** otherwise.
 - a) If A is a 3×10 matrix with 2 pivots in its RREF, then dim(NulA) = 8 and rank(A) = 2.

TRUE FALSE

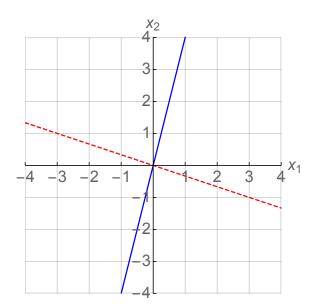
b) If A is an $m \times n$ matrix and Ax = 0 has only the trivial solution, then the transformation T(x) = Ax is onto.

TRUE FALSE

c) If $\{a, b, c\}$ is a basis of a linear space V, then $\{a, a + b, b + c\}$ is a basis of V as well.

TRUE FALSE

2. Write a matrix *A* so that Col(*A*) is the solid blue line and Nul(*A*) is the dotted red line drawn below.



supplemental (2.6-3.2)

- **1.** Circle **TRUE** if the statement is always true, and circle **FALSE** otherwise.
 - **a)** If *A* is a 3×100 matrix of rank 2, then dim(Nul*A*) = 97.

TRUE FALSE

b) If *A* is an $m \times n$ matrix and Ax = 0 has only the trivial solution, then the columns of *A* form a basis for \mathbb{R}^m .

c) The set
$$V = \left\{ \begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix}$$
 in $\mathbf{R}^4 \mid x - 4z = 0 \right\}$ is a subspace of \mathbf{R}^4 .
TRUE FALSE

- **2.** Circle **T** if the statement is always true, and circle **F** otherwise. You do not need to explain your answer.
 - **a)** If $\{v_1, v_2, v_3, v_4\}$ is a basis for a subspace *V* of \mathbb{R}^n , then $\{v_1, v_2, v_3\}$ is a linearly independent set.
 - **b)** The solution set of a consistent matrix equation Ax = b is a subspace.
 - c) A translate of a span is a subspace.
- **3.** True or false (justify your answer). Answer true if the statement is *always* true. Otherwise, answer false.
 - **a)** There exists a 3×5 matrix with rank 4.
 - **b)** If *A* is an 9 × 4 matrix with a pivot in each column, then

 $NulA = \{0\}.$

- c) There exists a 4×7 matrix *A* such that nullity A = 5.
- **d)** If $\{v_1, v_2, \dots, v_n\}$ is a basis for **R**⁴, then n = 4.
- **4.** a) True or false: If *A* is an $m \times n$ matrix and Nul(*A*) = \mathbb{R}^n , then Col(*A*) = {0}.
 - **b)** Give an example of 2×2 matrix whose column space is the same as its null space.
 - c) True or false: For some *m*, we can find an $m \times 10$ matrix *A* whose column span has dimension 4 and whose solution set for Ax = 0 has dimension 5.
- **5.** Fill in the blanks: If *A* is a 7×6 matrix and the solution set for Ax = 0 is a plane, then the column space of *A* is a _____-dimensional subspace of **R**.

- 6. True or false. If the statement is *always* true, answer TRUE. Otherwise, circle FALSE.
 - a) The matrix transformation $T\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -1 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$ performs reflection across the *x*-axis in \mathbb{R}^2 . TRUE FALSE
 - **b)** The matrix transformation $T\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$ performs rotation counterclockwise by 90° in **R**². TRUE FALSE
- 7. Let *A* be a 3×4 matrix with column vectors v_1, v_2, v_3, v_4 , and suppose $v_2 = 2v_1 3v_4$. Consider the matrix transformation T(x) = Ax.
 - a) Is it possible that *T* is one-to-one? If yes, justify why. If no, find distinct vectors v and w so that T(v) = T(w).
 - **b)** Is it possible that *T* is onto? Justify your answer.
- **8.** Answer each question.

a) Suppose $S : \mathbb{R}^3 \to \mathbb{R}^2$ is the matrix transformation $S(x) = \begin{pmatrix} 1 & 0 & 2 \\ 0 & 1 & 3 \end{pmatrix} x$. Is *S* one-to-one? YES NO

Is *S* onto? YES NO

b) Suppose $T : \mathbb{R}^2 \to \mathbb{R}^2$ is given by T(x, y) = (x - y, x - y). Is *T* one-to-one? YES NO

Is T onto? YES NO

- **c)** Suppose $T : \mathbf{R}^n \to \mathbf{R}^m$ is a one-to-one matrix transformation. Which one of the following *must* be true? (cicle one) m = n m < n $m \le n$ m > n $m \ge n$
- 9. Which of the following transformations are onto? Circle all that apply. π
 - **a)** $T : \mathbf{R}^2 \to \mathbf{R}^2$ that rotates counterclockwise by $\frac{\pi}{12}$ radians.
 - **b)** The transformation T(x) = Ax, where A is a 4×3 matrix with three pivots.
 - c) $T : \mathbf{R}^3 \to \mathbf{R}^3$ that reflects across the *yz*-plane.

Worksheet 6 (3.3-3.4)

- If A is a 3 × 5 matrix and B is a 3 × 2 matrix, which of the following are defined?
 a) A-B
 - **b)** AB
 - c) $A^T B$
 - **d)** $B^T A$
 - **e)** *A*²
- **2.** *A* is $m \times n$ matrix, *B* is $n \times m$ matrix. Select proper answers from the box. Multiple answers are possible
 - a) Take any vector x in \mathbb{R}^m , then ABx must be in: $\boxed{\operatorname{Col}(A), \operatorname{Nul}(A), \operatorname{Col}(B), \operatorname{Nul}(B)}$
 - **b)** Take any vector x in \mathbb{R}^n , then *BAx must be* in: Col(*A*), Nul(*A*), Col(*B*), Nul(*B*)

c) If m > n, then columns of AB could be linearly *independent*, *dependent*,

d) If m > n, then columns of *BA* could be linearly *independent*, *dependent*

e) If m > n and Ax = 0 has nontrivial solutions, then columns of BA could be linearly *independent*, *dependent*

Supplemental (3.3-3.4)

- **1.** Circle **T** if the statement is always true, and circle **F** otherwise.
 - a) **T F** If $T : \mathbf{R}^n \to \mathbf{R}^n$ is linear and $T(e_1) = T(e_2)$, then the homogeneous equation T(x) = 0 has infinitely many solutions.
 - b) **T F** If $T : \mathbf{R}^n \to \mathbf{R}^m$ is a one-to-one linear transformation and $m \neq n$, then *T* must not be onto.
- **2.** Consider $T : \mathbf{R}^3 \to \mathbf{R}^3$ given by

$$T(x, y, z) = (x, x + z, 3x - 4y + z, x).$$

Is T one-to-one? Justify your answer.

- **3.** In each case, determine whether *T* is linear. Briefly justify.
 - **a)** $T(x_1, x_2) = (x_1 x_2, x_1 + x_2, 1).$
 - **b)** $T(x, y) = (y, x^{1/3}).$
 - c) T(x, y, z) = 2x 5z.
- **4.** True or false (justify your answer). Answer true if the statement is *always* true. Otherwise, answer false.
 - a) If *A* and *B* are matrices and the products *AB* and *BA* are both defined, then *A* and *B* must be square matrices with the same number of rows and columns.
 - **b)** If *A*, *B*, and *C* are nonzero 2×2 matrices satisfying BA = CA, then B = C.
 - c) Suppose *A* is an 4×3 matrix whose associated transformation T(x) = Ax is not one-to-one. Then there must be a 3×3 matrix *B* which is not the zero matrix and satisfies AB = 0.
 - **d)** Suppose $T : \mathbf{R}^n \to \mathbf{R}^m$ and $U : \mathbf{R}^m \to \mathbf{R}^p$ are one-to-one linear transformations. Then $U \circ T$ is one-to-one. (What if *U* and *T* are not necessarily linear?)
- **5.** In each case, use geometric intuition to either give an example of a matrix with the desired properties or explain why no such matrix exists.
 - a) A 3 × 3 matrix *P*, which is not the identity matrix or the zero matrix, and satisfies $P^2 = P$.
 - **b)** A 2 × 2 matrix A satisfying $A^2 = I$.
 - c) A 2 × 2 matrix A satisfying $A^3 = -I$.

Worksheet 7 (3.5-3.6)

- **1.** True or false (justify your answer). Answer true if the statement is *always* true. Otherwise, answer false.
 - a) If *A* and *B* are $n \times n$ matrices and both are invertible, then the inverse of *AB* is $A^{-1}B^{-1}$.
 - **b)** If *A* is an $n \times n$ matrix and the equation Ax = b has at least one solution for each *b* in \mathbb{R}^n , then the solution is *unique* for each *b* in \mathbb{R}^n .
 - c) If A is an $n \times n$ matrix and the equation Ax = b has at most one solution for each b in \mathbb{R}^n , then the solution must be *unique* for each b in \mathbb{R}^n .
 - **d)** If *A* and *B* are invertible $n \times n$ matrices, then A + B is invertible and $(A + B)^{-1} = A^{-1} + B^{-1}$.
 - e) If *A* and *B* are $n \times n$ matrices and ABx = 0 has a unique solution, then Ax = 0 has a unique solution.
 - **f)** If *A* is a 3 × 4 matrix and *B* is a 4 × 2 matrix, then the linear transformation *Z* defined by Z(x) = ABx has domain \mathbb{R}^3 and codomain \mathbb{R}^2 .
 - **g)** Suppose *A* is an $n \times n$ matrix and every vector in \mathbb{R}^n can be written as a linear combination of the columns of *A*. Then *A* must be invertible.