

Math 1553 Worksheet §6.1, §6.2

Solutions

1. True/False

- (1) If u is in subspace W , and u is also in W^\perp , then $u = 0$.
- (2) If y is in subspace W , the orthogonal projection of y onto W is y .
- (3) If x is orthogonal to v and w , then x is also orthogonal to $v - w$.

Solution.

- (1) TRUE: $u \cdot u = \|u\|^2 = 0$ only when $u = 0$.
- (2) TRUE: y is decomposed into the elements that form a basis for W , so they could be used to give a unique representation for y .
- (3) TRUE: $v - w$ is on the same plane spanned by v and w .

2. Give examples

- (1) two linearly independent vectors that are orthogonal to $\begin{pmatrix} 2 \\ 0 \\ -1 \end{pmatrix}$.
- (2) a subspace of \mathbf{R}^3 , S , such that $\dim(S^\perp) = 2$.

Solution.

- (1) Two linearly independent vectors orthogonal to the first vector can be found, for example, by setting

$$u = \begin{pmatrix} 1 \\ 0 \\ a \end{pmatrix}, v = \begin{pmatrix} 0 \\ 1 \\ b \end{pmatrix}$$

Taking dot products and solving for a and b gives the vectors we need. Students will likely get the answer by inspection in a way that takes advantage of the second element being zero, but you can ask how we might approach a more general problem.

- (2) A few examples:

- The column space of $\begin{pmatrix} 1 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$
- The span of any vector in \mathbf{R}^3 .
- The null space of a 3×3 matrix that has two pivots.

3. a) Compute dot product of every pair of two vectors from $u = \begin{pmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \\ 1 \end{pmatrix}$, $v =$

$$\begin{pmatrix} 1/\sqrt{2} \\ -1/\sqrt{2} \\ 0 \end{pmatrix} \text{ and } w = \begin{pmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \\ -1 \end{pmatrix}.$$

- b) What are the eigenvalues and eigenvectors of the 3×3 matrix $A = vv^T$?
- c) What is the column space and null space of the matrix $A = vv^T$?

Solution.

- a) If we compute the dot products, we find $u \cdot v = u \cdot w = v \cdot w = 0$. They are mutually orthogonal to each other. In fact, these three vectors form an orthogonal basis for \mathbf{R}^3 .
- b) Notice $Av = vv^T v = v(v^T v) = v$ gives us an eigenvalue $\lambda_1 = 1$, eigenvector v . Similarly $Au = vv^T u = v(v^T u) = 0$ and $Aw = vv^T w = v(v^T w) = 0$ gives us eigenvalue $\lambda_2 = \lambda_3 = 0$, eigenvectors u, w . Since A is 3×3 , there is no other eigenvalues.
- c) One way to do this is to compute explicitly

$$A = \begin{pmatrix} 1/2 & -1/2 & 0 \\ -1/2 & 1/2 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

Then one can compute $\text{Col}A = \text{Span} \left\{ \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix} \right\}$, and $\text{Nul}A = \text{Span} \left\{ \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right\}$.

Another way to do this without computing A , is by looking at the geometry through eigenvectors. This matrix A preserves any vector in the space $V = \text{Span}\{v\}$. Moreover A projects vectors in $V^\perp = \text{Span}\{u, w\}$ to the 0 vector. So the geometry suggests, A is a projection matrix which has $\text{Nul}A = V^\perp = \text{Span}\{u, w\}$, and $\text{Col}A = V = \text{Span}\{v\}$.