

# Outline for Midterm #2

## Math 4318, Spring 2011

### I. Single Variable Functions: Differentiation

#### A. DEFINITIONS AND FIRST PROPERTIES

1. We recalled a few definitions concerning limits from Analysis I.
2. A function  $f : (a, b) \rightarrow \mathbb{R}$  is **differentiable** at a point  $p \in (a, b)$  if the limit

$$\lim_{h \rightarrow 0} \frac{f(p+h) - f(p)}{h}$$

exists. If the limit exists we denote it by  $f'(p)$  and call it the **derivative of  $f$  at  $p$** .

3. Interpreting the derivative as a slope we could also define

$$f'(p) = \lim_{t \rightarrow p} \frac{f(t) - f(p)}{t - p}.$$

4. **Theorem:** If  $f$  is differentiable at  $p$  then  $f$  is continuous at  $p$ .

5. **Theorem:** Suppose  $f$  and  $g$  are differentiable at  $p$ . Then

- i. The function  $f \pm g$  is differentiable at  $p$  with

$$(f \pm g)'(p) = f'(p) \pm g'(p).$$

- ii. The function  $fg$  is differentiable at  $p$  with

$$(fg)'(p) = f'(p)g(p) + f(p)g'(p).$$

- iii. If  $g(p) \neq 0$  then the function  $f/g$  is differentiable at  $p$  and

$$(f/g)'(p) = \frac{f'(p)g(p) - f(p)g'(p)}{g^2(p)}.$$

- iv. If  $h(x) = c$  for some constant  $c \in \mathbb{R}$  then  $h'(x) = 0$  for all  $x$ .

- v. If  $h(x) = x$  then  $h'(x) = 1$  for all  $x$ .

- vi. If  $f$  is differentiable at  $p$  and  $g$  is differentiable at  $f(p)$  then  $g \circ f$  is differentiable at  $p$  and

$$(g \circ f)'(p) = g'(f(p))f'(p).$$

6. Discussed the example

$$f(x) = \begin{cases} x^2 \sin \frac{1}{x} & x \neq 0 \\ 0 & x = 0. \end{cases}$$

It is differentiable on  $\mathbb{R}$  (including 0) but its derivative is not continuous at 0.

7. The  **$n$ th order derivative of  $f$  at  $p$**  is defined to be the derivative of the  $(n-1)$ st derivative of  $f$  at  $p$ , if it exists. Denote the  $n$ th derivative by  $f^{(n)}(p)$ . With this notation we take  $f^{(0)}$  to denote  $f$ .

8. A function is **continuously differentiable of order  $r$  on the interval  $I$**  if  $f^{(r)}$  exists and is continuous on  $I$ . (Note this implies  $f^{(k)}$  exists and is continuous on  $I$  for all  $k \leq r$ .) We denote the set of continuously  $r$ th order differentiable functions on  $I$  by  $C^r(I)$ . The set  $C^\infty(I)$  denotes functions whose derivative of all orders exist on  $I$ .

9. Clearly  $C^r(I) \supset C^{r+1}(I)$ . This inclusion is strict (that is for any  $r$  there are functions that are  $r$ th order continuously differentiable that are not continuously differentiable to order  $r+1$ ). The first few examples are  $f(x) = |x|$ ,  $g(x) = x|x|$ ,  $h(x) = |x|^3 \dots$

#### B. THE MEAN VALUE THEOREM

1. **Theorem (Mean value theorem):** If  $f : [a, b] \rightarrow \mathbb{R}$  is continuous and  $f$  is differentiable on  $(a, b)$  then there is a point  $c \in (a, b)$  such that

$$f(b) - f(a) = f'(c)(b - a).$$

2. **Theorem:** If  $f : (a, b) \rightarrow \mathbb{R}$  is differentiable at  $c \in (a, b)$  and  $f$  has a local maximum or minimum at  $c$  then  $f'(c) = 0$ .
3. **Corollary:** If  $f$  is differentiable on  $(a, b)$  and there is some  $K$  such that  $|f'(x)| \leq K$  for all  $x \in (a, b)$  then

$$|f(x) - f(y)| \leq K|x - y|$$

for all  $x, y \in [a, b]$ . (In particular  $f$  is Lipschitz.)

4. Suppose that  $f$  is differentiable on  $(a, b)$
- If  $f'(x) \geq 0$  for all  $x$  then  $f$  is increasing.
  - If  $f'(x) \leq 0$  for all  $x$  then  $f$  is decreasing.
  - If  $f'(x) > 0$  for all  $x$  then  $f$  is strictly increasing.
  - If  $f'(x) < 0$  for all  $x$  then  $f$  is strictly decreasing.
5. **Corollary (Intermediate value theorem for derivatives):** Suppose that  $f : [a, b] \rightarrow \mathbb{R}$  is differentiable. Given any  $\lambda$  between  $f'(a)$  and  $f'(b)$  there is some point  $c \in (a, b)$  such that  $f'(c) = \lambda$ .
6. **Corollary (Inverse function theorem):** Suppose that  $f : (a, b) \rightarrow \mathbb{R}$  is a differentiable function and  $f'(x) \neq 0$  for all  $x \in (a, b)$ . Then  $f$  is a bijection onto its image. The inverse of  $f$  is continuous and

$$(f^{-1})'(y) = \frac{1}{f'(x)}$$

where  $y = f(x)$ .

7. **Theorem:** Let  $f$  and  $g$  be two continuous functions on  $[a, b]$  that are differentiable on  $(a, b)$ . There is a point  $c \in (a, b)$  such that

$$(f(b) - f(a))g'(c) = (g(b) - g(a))f'(c).$$

8. **Corollary (L'Hopital's Rule):** Let  $f, g$  be differentiable functions on  $(a, b)$ . Suppose  $f(x) \rightarrow 0$  and  $g(x) \rightarrow 0$  as  $x \rightarrow b$  and  $g'(x)$  and  $f'(x)$  are not zero near  $b$ . If

$$\lim_{x \rightarrow b} \frac{f'(x)}{g'(x)} = L$$

then

$$\lim_{x \rightarrow b} \frac{f(x)}{g(x)} = L.$$

There are of course many other cases of L'Hopital's rule.

## C. TAYLOR POLYNOMIALS

1. Let  $f : [a, b] \rightarrow \mathbb{R}$  be a function and  $c \in (a, b)$ . If  $f(c), f'(c), \dots, f^{(n)}(c)$  exist then the  **$n$ th order Taylor polynomial of  $f$  at  $c$**  is

$$P_n(x) = \sum_{k=0}^n \frac{f^{(k)}(c)}{k!} (x - c)^k.$$

2. **Theorem:** Let  $f : [a, b] \rightarrow \mathbb{R}$  be a function such that  $f', f'', \dots, f^{(n+1)}$  all exist on  $(a, b)$ . Let  $P_n(x)$  be the  $n$ th order Taylor polynomial of  $f$  at  $c$ . Then for each  $x \in [a, b]$  there is some point  $t$  between  $c$  and  $x$  such that

$$f(x) = P_n(x) + \frac{f^{(n+1)}(t)}{(n+1)!} (x - c)^{n+1}.$$

## II. Single Variable Functions: Integration

### A. RIEMANN INTEGRABILITY

1. A **partition** of an interval  $[a, b]$  is a finite collection of points  $\mathcal{P} = \{x_0, x_1, \dots, x_n\}$  such that  $x_i < x_{i+1}$ ,  $x_0 = a$  and  $x_n = b$ . The **intervals of a partition** are  $I_i = [x_{i-1}, x_i]$  for  $i = 1, \dots, n$ . The **lengths of a partition** are  $\Delta x_i = x_i - x_{i-1}$ . The **size of the partition**  $\mathcal{P}$  is  $\|\mathcal{P}\| = \max\{\Delta x_1, \dots, \Delta x_n\}$ .
2. A **tagged partition**  $\mathcal{P}^t$  is a partition  $\mathcal{P} = \{x_0, \dots, x_n\}$  together a choice of point  $t_i$  in each interval  $[x_{i-1}, x_i]$ .
3. If  $f : [a, b] \rightarrow \mathbb{R}$  is a function and  $\mathcal{P}$  is a tagged partition of  $[a, b]$  then the **Riemann sum of  $f$  associated to  $\mathcal{P}^t$**  is

$$S(f, \mathcal{P}^t) = \sum_{i=1}^n f(t_i) \Delta x_i.$$

We say  $f$  is **Riemann integrable** if there is some number  $I \in \mathbb{R}$  such that for every  $\epsilon > 0$  there is some  $\delta > 0$  such that for any tagged partition  $\mathcal{P}^t$  of  $[a, b]$  with  $\|\mathcal{P}^t\| < \delta$  we have

$$|S(f, \mathcal{P}^t) - I| < \epsilon.$$

Let  $\mathcal{R}([a, b])$  be the set of Riemann integrable functions on  $[a, b]$ .

4. **Lemma:** If  $f \in \mathcal{R}([a, b])$  then the  $I$  in the definition above is uniquely determined.
5. If  $f \in \mathcal{R}([a, b])$  then the **Riemann integral of  $f$  over  $[a, b]$**  is the number  $I$  in the definition above. We denoted this number by

$$\int_a^b f(x) dx.$$

#### 6. Proposition:

- i.  $\mathcal{R}([a, b])$  is a vector space.
- ii. The map

$$\mathcal{R}([a, b]) \rightarrow \mathbb{R} : f \mapsto \int_a^b f(x) dx$$

is a linear map.

- iii. The constant function  $f(x) = k$  is in  $\mathcal{R}([a, b])$  for any  $[a, b]$  and

$$\int_a^b k dx = k(b - a)$$

- iv. If  $f(x) \leq g(x)$  and  $f, g \in \mathcal{R}([a, b])$  then

$$\int_a^b f(x) dx \leq \int_a^b g(x) dx.$$

7. **Theorem:** If  $f \in \mathcal{R}([a, b])$  then  $f$  is bounded on  $[a, b]$ .

### B. DARBOUX INTEGRABILITY

1. Let  $f : [a, b] \rightarrow \mathbb{R}$  be a bounded function and  $\mathcal{P} = \{x_0, \dots, x_n\}$  a partition of  $[a, b]$ . For each  $i = 1, \dots, n$  set

$$M_i = \sup\{f(x) : x \in [x_{i-1}, x_i]\} \quad \text{and} \quad m_i = \inf\{f(x) : x \in [x_{i-1}, x_i]\}.$$

The **lower sum of  $f$  associated to the partition  $\mathcal{P}$**  is

$$L(f, \mathcal{P}) = \sum_{i=1}^n m_i \Delta x_i$$

and the **upper sum** is

$$U(f, \mathcal{P}) = \sum_{i=1}^n M_i \Delta x_i.$$

The **lower integral of  $f$  over  $[a, b]$**  is

$$\int_a^b f(x) dx = \sup\{L(f, \mathcal{P}) : \mathcal{P} \text{ a partition of } [a, b]\}$$

and the **upper integral of  $f$  over  $[a, b]$**  is

$$\overline{\int_a^b} f(x) dx = \int \{U(f, \mathcal{P}) : \mathcal{P} \text{ a partition of } [a, b]\}.$$

We say  $f$  is **Darboux integrable on  $[a, b]$**  if

$$\overline{\int_a^b} f(x) dx = \int_a^b f(x) dx.$$

- 2. Theorem:** A function  $f : [a, b] \rightarrow \mathbb{R}$  is Riemann integrable if and only if it is Darboux integrable. And if it is integrable then

$$\int_a^b f(x) dx = \overline{\int_a^b} f(x) dx = \int_a^b f(x) dx.$$

- 3.** We say a partition  $\mathcal{P}'$  **refines** a partition  $\mathcal{P}$  if  $\mathcal{P} \subset \mathcal{P}'$ .  
**4. Lemma:** If  $\mathcal{P}'$  refines  $\mathcal{P}$  then

$$L(f, \mathcal{P}) \leq L(f, \mathcal{P}') \leq U(f, \mathcal{P}') \leq U(f, \mathcal{P}).$$

- 5. Lemma:** A bounded function  $f : [a, b] \rightarrow \mathbb{R}$  is Darboux integrable if and only if for every  $\epsilon > 0$  there is some partition  $\mathcal{P}$  such that

$$U(f, \mathcal{P}) - L(f, \mathcal{P}) < \epsilon.$$

- 6. Corollary:** A bounded function  $f : [a, b] \rightarrow \mathbb{R}$  is Riemann integrable if and only if for every  $\epsilon > 0$  there is some partition  $\mathcal{P}$  such that

$$U(f, \mathcal{P}) - L(f, \mathcal{P}) < \epsilon.$$

- 7. Corollary:** A continuous function  $f : [a, b] \rightarrow \mathbb{R}$  is Riemann integrable.

## C. SETS OF MEASURE ZERO AND THE RIEMANN-LEBESGUE THEOREM

- 1.** A set  $S \subset \mathbb{R}$  has **measure zero** or is a **set of measure zero** if for every  $\epsilon > 0$  there is a countable collection of intervals  $(a_i, b_i)$  such that  $S \subset \cup(a_i, b_i)$  (that is the intervals are a cover of  $S$ ) and

$$\sum (b_i - a_i) \leq \epsilon.$$

- 2. Lemma:**

- i.** A finite set has measure zero.
- ii.** A subset of a set of measure zero has measure zero.
- iii.** A countable union of sets of measure zero has measure zero.
- iv.** A countable set has measure zero.
- v.** The middle thirds Cantor set has measure zero.

- 3.** A function  $f : [a, b] \rightarrow \mathbb{R}$  is **continuous almost everywhere** if the set of points at which  $f$  is discontinuous has measure zero.

- 4. Theorem (the Riemann-Lebesgue Theorem):** Function  $f : [a, b] \rightarrow \mathbb{R}$  is Riemann integrable if and only if it is bounded and continuous almost everywhere.

5. **Corollary:** Every continuous and bounded piecewise continuous function on  $[a, b]$  is Riemann integrable.
6. **Corollary:** If  $f : [a, b] \rightarrow \mathbb{R}$  is Riemann integrable and  $g : [c, d] \rightarrow \mathbb{R}$  is continuous with  $f([a, b]) \subset [c, d]$  then  $g \circ f$  is Riemann integrable.
7. **Corollary:** If  $f \in \mathcal{R}([a, b])$  then  $|f| \in \mathcal{R}([a, b])$  and

$$\left| \int_a^b f(x) dx \right| \leq \int_a^b |f(x)| dx$$

8. **Corollary:** The product of Riemann integrable functions is Riemann integrable.
9. **Corollary:** If  $a < c < b$  then  $f \in \mathcal{R}([a, b])$  if and only if  $f \in \mathcal{R}([a, c])$  and  $f \in \mathcal{R}([c, b])$ .  
Moreover,

$$\int_a^b f(x) dx = \int_a^c f(x) dx + \int_c^b f(x) dx.$$

10. **Corollary:** Suppose  $f : [a, b] \rightarrow \mathbb{R}$  is non-negative (that is  $f(x) \geq 0$ ) and integrable. Then  $\int_a^b f(x) dx = 0$  implies that  $f(x) = 0$  at every point  $x$  where  $f$  is continuous.

## D. FUNDAMENTAL THEOREM OF CALCULUS

1. **Theorem (Fundamental theorem of calculus I):** Let  $f \in \mathcal{R}([a, b])$  and set

$$F(x) = \int_a^x f(t) dt$$

for all  $x \in [a, b]$ . Then the function  $F$  is continuous on  $[a, b]$  and if  $f$  is continuous at  $c$  then  $F$  is differentiable at  $c$  and  $F'(c) = f(c)$ .

2. **Corollary:** Any continuous function  $f : [a, b] \rightarrow \mathbb{R}$  has an anti-derivative (*i.e.* a function  $F$  such that  $F'(x) = f(x)$  for all  $x \in [a, b]$ ).
3. **Theorem (Fundamental theorem of calculus II):** If  $f$  is differentiable on  $[a, b]$  and  $f'$  is integrable on  $[a, b]$  then

$$\int_a^b f'(x) dx = f(b) - f(a).$$

4. **Theorem (Integration by parts):** Let  $f$  and  $g$  be functions on  $[a, b]$  for which  $f'$  and  $g'$  are both integrable. Then

$$\int_a^b f'(x)g(x) dx = f(x)g(x)|_a^b - \int_a^b f(x)g'(x) dx.$$

5. **Theorem (Change of variables):** Let  $\phi : [c, d] \rightarrow \mathbb{R}$  have continuous derivative and  $f : [a, b] \rightarrow \mathbb{R}$  be continuous with  $[a, b] \subset \phi([c, d])$ . Then

$$\int_c^d f(\phi(t))\phi'(t) dt = \int_{\phi(c)}^{\phi(d)} f(x) dx.$$

## E. IMPROPER INTEGRALS

1. If  $f : (a, b] \rightarrow \mathbb{R}$  is a function and  $c \in (a, b]$  then if  $f$  is integrable on  $[c, b]$  set

$$I_c = \int_c^b f(x) dx.$$

Define the **improper integral of  $f$  on  $[a, b]$**  to be

$$\int_a^b f(x) dx = \lim_{c \rightarrow a^+} I_c$$

if the limit exists. (One can similarly define the improper integral of  $f : [a, b) \rightarrow \mathbb{R}$ .)

2. If  $f : [a, b] \rightarrow \mathbb{R}$  is integrable then this definition agrees with the Riemann integral of  $f$ .

### III. Sequences of functions and function spaces

#### A. SEQUENCES OF FUNCTIONS

1. If  $S \subset \mathbb{R}$  and  $\{f_n : S \rightarrow \mathbb{R}\}$  is a sequence of functions on  $f$  (that is if  $\mathcal{F}(S, \mathbb{R})$  is the set of all functions from  $S$  to  $\mathbb{R}$ , then  $\{f_n\}$  is a sequence in the set  $\mathcal{F}(S, \mathbb{R})$ ), then we say the sequence **converges point wise to  $f$**  if for each  $x \in S$  we have the sequence of numbers  $\{f_n(x)\}$  converges to  $f(x)$ . That is for all  $x \in S$  and  $\epsilon > 0$  there is some  $N$  such that  $|f(x) - f_n(x)| < \epsilon$  for all  $n \geq N$ .
2. We say that a sequence of functions  $\{f_n : S \rightarrow \mathbb{R}\}$  **converges uniformly to  $f$  on  $S$**  if for all  $\epsilon > 0$  there is a  $N$  such that  $|f(x) - f_n(x)| < \epsilon$  for all  $n \geq N$  and  $x \in S$ .
3. **Lemma:** The sequence  $\{f_n : S \rightarrow \mathbb{R}\}$  converges uniformly to some function on  $S$  if and only if for all  $\epsilon > 0$  there is an  $N$  such that  $|f_n(x) - f_m(x)| < \epsilon$  for all  $n, m \geq N$  and  $x \in S$ .
4. **Theorem:** If  $f_n \rightarrow f$  uniformly on  $S$  and the  $f_n$  are continuous at  $c \in S$  then  $f$  is continuous at  $c$ .
5. **Theorem:** If  $\{f_n\}$  is a sequence in  $\mathcal{R}([a, b])$  and  $f_n \rightarrow f$  uniformly on  $[a, b]$  then  $f \in \mathcal{R}(a, b]$  and

$$\int_a^b f(x) dx = \lim_{n \rightarrow \infty} \int_a^b f_n(x) dx.$$

6. **Theorem:** Let  $\{f_n : [a, b] \rightarrow \mathbb{R}\}$  be a sequence of functions. Suppose that

- i. there is some  $c \in [a, b]$  such that  $\{f_n(c)\}$  converges,
- ii. the functions  $f_n$  are all differentiable on  $[a, b]$ , and
- iii.  $f'_n \rightarrow g$  uniformly on  $[a, b]$  for some function  $g$ .

Then there is some function  $f$  such that  $f_n \rightarrow f$  uniformly on  $[a, b]$  and  $f' = g$ .

#### B. METRIC SPACE TOPOLOGY

1. Let  $X$  be a set. A **metric** on  $X$  is a function

$$d : X \times X \rightarrow \mathbb{R}$$

such that

- i.  $d(p, q) \geq 0$  for all  $p, q \in X$ ,
- ii.  $d(p, q) = 0$  if and only if  $p = q$
- iii.  $d(p, q) = d(q, p)$ , and
- iv.  $d(p, q) \leq d(p, r) + d(r, q)$  for all  $p, q, r \in X$ . We think of  $d(p, q)$  as being the distance between  $p$  and  $q$ . The pair  $(X, d)$  is called a **metric space**.

2. **Example:** Given a norm  $\|\cdot\|$  on a vector space  $V$  one has a metric associated to the norm by setting

$$d(v, w) = \|v - w\|$$

for all  $v, w \in V$ . Thus if  $\langle \cdot, \cdot \rangle$  is an inner product on  $V$  then  $\|v\| = \sqrt{\langle v, v \rangle}$  is a norm and hence we get a metric associated to the inner product too.

3. Given a metric space  $(X, d)$  most all the concepts from Analysis I can be defined for  $(X, d)$  since they only depended on some notion of distance (where there we used the standard norm on  $\mathbb{R}^n$ ). For example

- i. A set  $U \subset X$  is **open** if for all  $p \in U$  there is some  $r > 0$  such that  $B_r(p) \subset U$  where  $B_r(p) = \{x \in X : d(x, p) < r\}$ .
- ii. A **neighborhood** of a point  $p \in X$  is an open set  $N$  containing  $p$ .
- iii. A subset  $S \subset X$  has  $p \in X$  as a **cluster point** if for all neighborhoods  $N$  of  $p$  we have  $(N - \{p\}) \cap S \neq \emptyset$ . (This is equivalent to saying for all  $\epsilon > 0$  there is some  $q \in S$  with  $q \neq p$  and  $d(q, p) < \epsilon$ .)

- iv. A set  $S$  in  $X$  is **closed** if it contains all of its cluster points.
- v. A set  $S$  is **bounded** if there is some  $p \in X$  and  $R$  such that  $S \subset B_r(p)$ .
- vi. A sequence  $\{x_n\}$  in  $X$  is **Cauchy** if for all  $\epsilon > 0$  there is some  $N$  such that  $d(x_n, x_m) < \epsilon$  for all  $n, m \geq N$ .

Most all the other concepts can be rephrased in terms of  $d$  too.

- 4. A metric space is complete if every Cauchy sequence converges.
- 5. **Theorem (from Analysis I):** The space  $(\mathbb{R}^n, d)$  is complete. (Here  $d(x, y) = \sqrt{\sum (x_i - y_i)^2}$ .)
- 6. Suppose  $V$  is a vector space and  $d$  is a metric on  $V$  that is complete. If  $d$  comes from a norm then  $(V, d)$  is called a **Banach space**. If  $d$  comes from an inner product then  $(V, d)$  is called a **Hilbert space**.

### C. FUNCTION SPACES

- 1. Let  $D \subset \mathbb{R}$ . We set

$$\mathcal{B}(D, \mathbb{R}) = \{\text{bounded functions } f : D \rightarrow \mathbb{R}\}$$

and for  $f \in \mathcal{B}(D, \mathbb{R})$  let

$$\|f\|_\infty = \sup\{|f(x)| : x \in D\}.$$

We call this the **sup-norm** or **uniform norm** on  $\mathcal{B}(D, \mathbb{R})$  and one easily checks that this is a norm.

- 2. **Lemma:** Let  $\{f_n\}$  be a sequence in  $\mathcal{B}(D, \mathbb{R})$ . Then the following are equivalent
  - i.  $f_n \rightarrow f$  uniformly on  $D$ .
  - ii.  $f_n$  converges to  $f$  in the sup-norm.
  - iii.  $\|f_n - f\|_\infty \rightarrow 0$  as  $n \rightarrow \infty$ .
- 3. **Theorem:** The sequence  $\{f_n\}$  in  $\mathcal{B}(D, \mathbb{R})$  is Cauchy in the sup-norm if and only if it converges in the sup-norm. That is  $(\mathcal{B}(D, \mathbb{R}), \|\cdot\|_\infty)$  is a Banach space.
- 4. Let

$$C_b^0\{D\} = \{f \in \mathcal{B}(D, \mathbb{R}) : f \text{ is continuous}\}.$$

(Notice that if  $D$  is compact then  $C_b^0(D) = C^0(D)$ .)

- 5. **Theorem:**  $C_b^0(D)$  is a Banach space (in the sup-norm).
- 6. **Theorem:** The set  $\mathcal{R}([a, b])$  (which is a subset of  $\mathcal{B}([a, b], \mathbb{R})$ ) is a Banach space in the sup-norm and the function

$$I : \mathcal{R}([a, b]) \rightarrow \mathbb{R} : f \rightarrow \int_a^b f(x) dx$$

is continuous.

- 7. For a function in  $f \in C^n([a, b])$  and any  $k \leq n$  define

$$\|f\|_{C^k} = \|f\|_\infty + \|f'\|_\infty + \dots + \|f^{(k)}\|_\infty.$$

It is easy to check this is a norm on  $C^n([a, b])$ .

- 8. **Theorem:**  $(C^n([a, b]), \|\cdot\|_{C^n})$  is a Banach space.

### D. APPROXIMATION OF FUNCTIONS

- 1. **Theorem (Weierstrass):** Polynomials are dense in  $C^0([a, b])$ . (That is for every  $f \in C^0([a, b])$  and  $\epsilon > 0$  there is a polynomial  $p$  such that  $\|f - p\| < \epsilon$ .)
- 2. Given two functions  $f, g : \mathbb{R} \rightarrow \mathbb{R}$  we define the **convolution** of  $f$  and  $g$  to be

$$f * g(x) = \int_{\mathbb{R}} f(x-t)g(t) dt,$$

if the integral is well defined (and it will be if, for example, one of the functions has compact support and the functions are integrable on compact intervals).

- 3. A sequence of functions  $K_n(x)$  is called an **approximation to the identity** if

- i.  $K_n(x) \geq 0$  for all  $x$  and  $n$ ,
  - ii.  $\int K_n(x) dx = 1$  for all  $n$ , and
  - iii.  $\int_{|x| \geq \epsilon} K_n(x) dx \rightarrow 0$  as  $n \rightarrow \infty$  for any  $\epsilon > 0$ .
4. **Lemma:** If  $\{K_n\}$  is an approximation to the identity and  $f$  is a compactly supported continuous function then  $(f * K_n) \rightarrow f$  uniformly.
5. **Lemma:** If  $p$  is a polynomial and  $f \in \mathcal{R}([a, b])$  has compact support then  $p * f$  is a polynomial.

## E. FIXED POINT THEOREMS AND DIFFERENTIAL EQUATIONS

1. **Theorem (Contraction mapping theorem):** Let  $(M, d)$  be a complete metric space and  $f : M \rightarrow M$  a contraction mapping (that is there is some  $0 \leq k < 1$  such that  $d(f(x), f(y)) \leq kd(x, y)$  for all  $x, y \in M$ ). Then there is a unique fixed point  $p \in M$  for  $f$ . (That is  $f(p) = p$  and  $p$  is the only point with this property.)
2. **Theorem (Existence and uniqueness of solutions to ODEs):** Let  $f : D \subset \mathbb{R}^2 \rightarrow \mathbb{R}$  be a function on a neighborhood  $D$  of  $(t_0, x_0)$  in  $\mathbb{R}^2$ . Assume that
- i.  $f$  is Lipschitz in the  $x$  variable (that is there is some  $K$  such that  $|f(t, x) - f(t, x')| \leq K|x - x'|$ ) and
  - ii.  $f$  is continuous on  $D$ .

Then there is some  $\delta > 0$  and a unique  $C^1$  solution to the initial value problem

$$\frac{dx}{dt} = f(t, x) \quad x(t_0) = x_0$$

on  $(t_0 - \delta, t_0 + \delta)$ . (That is there is some continuously differentiable function  $\gamma : (t_0 - \delta, t_0 + \delta) \rightarrow \mathbb{R}$  such that  $\gamma'(t) = f(t, \gamma(t))$  and  $\gamma(t_0) = x_0$ .)

3. A function  $\gamma$  solves the initial value problem if and only if it is a fixed point of

$$\Phi(\gamma)(t) = x_0 + \int_{t_0}^t f(s, \gamma(s)) ds.$$

## F. COMPACTNESS IN FUNCTION SPACES

1. A subset  $S \subset \mathcal{F}(D, \mathbb{R}) = \{\text{functions from } D \text{ to } \mathbb{R}\}$  is called **equicontinuous** if for every  $\epsilon > 0$  there is a  $\delta > 0$  such that  $|f(x) - f(y)| < \epsilon$  for all  $x, y \in D$  with  $|x - y| < \delta$  and  $f \in S$ . (Of course sequences are subsets so we can talk about equicontinuous sequences.)
2. **Theorem:** A subset  $S \subset \mathcal{F}(D, \mathbb{R})$  is compact (in the sup-norm) if and only if it is closed, bounded and equicontinuous.
3. Recall that a set in a metric space is called compact if every open cover of the set has a finite sub-cover. This is equivalent to saying that every sequence in the set has a convergent sub-sequence.
4. **Theorem (Arzelá-Ascoli Theorem):** Let  $\{f_n\}$  be a sequence of functions  $f_n : D \rightarrow \mathbb{R}$ . If
- i.  $D$  is compact,
  - ii.  $\{f_n\}$  is bounded in the sup-norm and
  - iii.  $\{f_n\}$  is equicontinuous (not this implies that each  $f_n$  is continuous),
- then there is a sub-sequence of  $\{f_n\}$  that converges uniformly on  $D$ .
5. **Theorem (Peano's Theorem):** Let  $f : D \subset \mathbb{R}^2 \rightarrow \mathbb{R}$  be a function on a neighborhood  $D$  of  $(t_0, x_0)$  in  $\mathbb{R}^2$ . If  $f$  is continuous on  $D$  then there is some  $\delta > 0$  and a unique  $C^1$  solution to the initial value problem

$$\frac{dx}{dt} = f(t, x) \quad x(t_0) = x_0$$

on  $[t_0, t_0 + \delta]$ .



6. Notice that when you drop the hypothesis of  $f$  being Lipschitz in the  $x$  variable you lose uniqueness of solutions. For example you can see that  $x'(t) = \sqrt{x(t)}$  with the initial condition  $x(0) = 0$  has infinitely many solutions. Indeed for  $c \geq 0$  let  $\gamma_c(t) = 0$  for  $t \leq c$  and  $\frac{1}{4}(t - c)^2$  for  $t \geq c$  and we see that  $\gamma_c$  solves the initial value problem.

## G. SERIES OF FUNCTIONS

1. Given a sequence  $\{g_k\}$  of functions on a set  $D \subset \mathbb{R}$  we can associate the partial sums

$$s_n(x) = \sum_{k=0}^n g_k(x).$$

We say the **series**  $\sum_{k=0}^{\infty} g_k$  **converges uniformly, respectively point-wise** to  $g$  if the sequence of partial sums  $\{s_n\}$  converges uniformly, respectively point-wise, to  $g$ . We say the series **converges absolutely** if for each  $x \in D$  the series of real numbers  $\sum_{k=0}^{\infty} |g_k(x)|$  converges.

2. **Theorem (Weierstrass  $M$ -test):** Let  $\{g_k\}$  be a sequence of functions on  $D$  and  $M_k$  be constants such that  $|g_k(x)| \leq M_k$  for all  $x \in D$ . If  $\sum_{k=0}^{\infty} M_k$  converges then  $\sum_{k=0}^{\infty} g_k$  converges absolutely and uniformly on  $D$ .
3. **Theorem:** If  $\sum_{k=0}^{\infty} g_k$  converges uniformly to  $g$  on  $[a, b]$  and each  $g_k \in \mathcal{R}([a, b])$  then  $g \in \mathcal{R}([a, b])$  and

$$\int_a^b g(x) dx = \int_a^b \sum_{k=0}^{\infty} g_k(x) dx = \sum_{k=0}^{\infty} \int_a^b g_k(x) dx.$$

4. Suppose that  $\sum_{k=0}^{\infty} g_k$  converges point-wise on  $[a, b]$  and each of the  $g_k$  is differentiable. If  $\sum_{k=0}^{\infty} g'_k$  converges uniformly on  $[a, b]$  then

$$\left( \sum_{k=0}^{\infty} g_k(x) \right)' = \sum_{k=0}^{\infty} g'_k(x).$$

5. **Theorem:** There is a continuous function  $f : \mathbb{R} \rightarrow \mathbb{R}$  that is nowhere differentiable!
6. Facts we did not prove: Lipschitz functions are differentiable almost everywhere. The set of nowhere differentiable functions is dense in the set of continuous functions.

## H. POWER SERIES

1. A **power series** about the point  $c$  is a series of the form

$$\sum_{k=0}^{\infty} a_n(x - c)^n.$$

2. Recall from Analysis I:

- i. The **radius of convergence** is defined to be  $R = \frac{1}{\rho}$  where

$$\rho = \limsup_k |a_k|^{\frac{1}{k}}.$$

- ii. If  $\lim_{n \rightarrow \infty} \frac{|a_n|}{|a_{n+1}|}$  exists then it is equal to the radius of convergence.
- iii. For any  $|x - c| < R$  the series  $\sum_{k=0}^{\infty} a_n(x - c)^n$  converges absolutely and for  $|x - c| > R$  the series diverges.
- iv. A power series converges uniformly on any compact subset of  $(c - R, c + R)$ .
- v. A power series defines a continuous function on  $(c - R, c + R)$ .

3. **Theorem:** If  $R$  is the radius of convergence of the power series

$$f(x) = \sum_{n=0}^{\infty} a_n(x - c)^n$$

Then  $f$  is differentiable of all orders on  $(c - R, c + R)$  and

$$f^{(k)}(x) = \sum_{n=k}^{\infty} n(n-1)\dots(n-k+1)a_n(x-c)^{n-k}.$$

4. **Corollary:** Suppose  $f(x) = \sum_{n=0}^{\infty} a_n(x-c)^n$  and  $g(x) = \sum_{n=0}^{\infty} b_n(x-c)^n$  converge on some interval  $(a, b)$  containing  $c$ . If  $f(x) = g(x)$  for all  $x \in (a, b)$  then  $a_n = b_n$  for all  $n$ .
5. A function  $f$  on an open interval is called **analytic** if it can be represented as a power series with non-zero radius of convergence, about each point in its domain.
6. **Theorem:** if  $f : (a, b) \rightarrow \mathbb{R}$  is  $C^\infty$  and there is some constant  $M$  such that

$$|f^{(k)}(x)| \leq M$$

for all  $x \in (a, b)$  then  $f$  is analytic.

7. Given a function  $f : (a, b) \rightarrow \mathbb{R}$  that is infinitely differentiable,  $c \in (a, b)$  and  $\delta > 0$  such that  $I_{c,\delta} = [c - \delta, c + \delta] \subset (a, b)$ , we can set  $M_{c,\delta}^k = \sup\{|f^{(k)}(x)| : x \in I_{c,\delta}\}$ . We call

$$g_{c,\delta} = \limsup_{k \rightarrow \infty} (M_{c,\delta}^k / k!)^{1/k}$$

the **derivative growth rate of  $f$   $\delta$ -near  $c$** . We say  $f$  has **locally bounded derivative growth rate in  $(a, b)$**  if for all  $c \in (a, b)$  there is some  $\delta$  so that  $g_{c,\delta}$  is finite.

8. **Theorem:** An infinitely differentiable function  $f : (a, b) \rightarrow \mathbb{R}$  is analytic if and only if it has locally bounded derivative growth rate.

## IV. Derivatives in higher dimensions

### A. DEFINITIONS AND FIRST PROPERTIES

1. A map  $f : A \subset \mathbb{R}^n \rightarrow \mathbb{R}^m$  is **differentiable at  $c \in A$**  if there is a linear map

$$L : \mathbb{R}^n \rightarrow \mathbb{R}^m$$

such that

$$\lim_{x \rightarrow c} \frac{\|f(x) - (f(c) + L(x-c))\|}{\|x-c\|} = 0.$$

If such an  $L$  exists then we call it the **derivative of  $f$  at  $c$**  and denote it by  $Df(c)$ .

2. Alternate definition:  $L$  is the derivative of  $f$  at  $c$  if and only if for all  $\epsilon > 0$  there is some  $\delta > 0$  such that  $\|x - c\| < \delta$  implies that  $\|f(x) - (f(c) + L(x-c))\| \leq \epsilon\|x - c\|$ .
3. **Lemma:** If there is a linear map  $L$  as in the definition above then it is uniquely determined by  $f$  and  $c$ .
4. **Theorem:** If  $f : A \rightarrow \mathbb{R}^m$  is differentiable at  $c \in A$  with  $A$  an open set in  $\mathbb{R}^n$ , then  $f$  is continuous at  $c$ .
5. Let  $f : A \subset \mathbb{R}^n \rightarrow \mathbb{R}^m$  be a function on the open set  $A$ . We can write

$$f(x_1, \dots, x_n) = (f_1(x_1, \dots, x_n), \dots, f_m(x_1, \dots, x_n)).$$

The  $i^{\text{th}}$  **partial derivative of  $f_j$**  at  $(x_1, \dots, x_n)$  is

$$\frac{\partial f_j}{\partial x_i} = \lim_{h \rightarrow 0} \frac{f_j(x_1, \dots, x_{i-1}, x_i + h, x_{i+1}, \dots, x_n) - f_j(x_1, \dots, x_n)}{h}$$

(if the limit exists).

6. **Theorem:** Let  $f : A \subset \mathbb{R}^n \rightarrow \mathbb{R}^m$  be a function on the open set  $A$ . If  $f$  is differentiable on  $A$  then the partial derivatives  $\frac{\partial f_j}{\partial x_i}$  exist for all  $i$  and  $j$  and in the standard basis for  $\mathbb{R}^n$

and  $\mathbb{R}^m$  the linear map  $Df(x_1, \dots, x_n)$  is given by the matrix

$$\begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \cdots & \frac{\partial f_1}{\partial x_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial f_m}{\partial x_1} & \cdots & \frac{\partial f_m}{\partial x_n} \end{bmatrix}$$

This matrix is called the **Jacobian matrix of  $f$  at  $(x_1, \dots, x_n)$** .

7. If  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  is a differentiable function then  $Df = \begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \cdots & \frac{\partial f_1}{\partial x_n} \end{bmatrix}$ . That is it is a linear map from  $\mathbb{R}^n$  to  $\mathbb{R}$ . This is very similar to a familiar concept: the **gradient of  $f$** . The gradient is a vector containing the partial derivatives of  $f$

$$\nabla f = \begin{bmatrix} \frac{\partial f_1}{\partial x_1} \\ \vdots \\ \frac{\partial f_1}{\partial x_n} \end{bmatrix}.$$

While it is common to write this vector as a row vector, we will always write it as a column vector (actually all our vectors are column vectors, so when we think of a point  $x \in \mathbb{R}^n$  we will think of it as a column vector so our matrix can act on it by matrix multiplication).

8. **Theorem:** Let  $A \subset \mathbb{R}^m$  be an open set and  $f : A \rightarrow \mathbb{R}^n$ . Suppose that  $f = (f_1, \dots, f_m)$  and each partial derivative  $\frac{\partial f_i}{\partial x_j}$  exists and is continuous near on  $A$ . Then  $f$  is differentiable on  $A$ .
9. Let  $A \subset \mathbb{R}^m$  be an open set and  $f : A \rightarrow \mathbb{R}^n$ . For  $e$  a unit vector in  $\mathbb{R}^n$  and  $c \in A$  we define the **directional derivative of  $f$  at  $c$  in the direction of  $e$**  to be

$$f'(c, e) = \lim_{h \rightarrow 0} \frac{f(c + he) - f(c)}{h}$$

if the limit exists.

10. It is simple to check that  $(Df(c))e = f'(c, e)$ .

## B. CHAIN RULE AND PRODUCT RULE

1. **Theorem (Chain Rule):** Let  $A \subset \mathbb{R}^n$  and  $B \subset \mathbb{R}^m$  be open sets. Suppose that  $f : A \rightarrow \mathbb{R}^m$ ,  $g : B \rightarrow \mathbb{R}^p$  and  $f(A) \subset B$ . If  $f$  is differentiable at  $x_0 \in A$  and  $g$  is differentiable at  $f(x_0) \in B$  then  $g \circ f$  is differentiable at  $x_0$  and

$$D(g \circ f)(x_0) = (Dg(f(x_0))) (Df(x_0)).$$