

P72. 5(a)

HW1

$$\text{Let } A = \begin{pmatrix} -1 & 1 \\ 0 & 2 \end{pmatrix} \quad B = \begin{pmatrix} 1 & 0 \\ 1 & -2 \end{pmatrix}$$

$$\text{If } P = \begin{pmatrix} 1 & 1 \\ 0 & 3 \end{pmatrix} \quad P^{-1} = \begin{pmatrix} 1 & -\frac{1}{3} \\ 0 & \frac{1}{3} \end{pmatrix}, \text{ then}$$

$$P^{-1}AP = \begin{pmatrix} -1 & 0 \\ 0 & 2 \end{pmatrix}$$

$$\text{If } Q = \begin{pmatrix} 0 & 3 \\ 1 & 1 \end{pmatrix} \quad Q^{-1} = \begin{pmatrix} -\frac{1}{3} & 1 \\ \frac{1}{3} & 0 \end{pmatrix} \text{ then}$$

$$Q^{-1}BQ = \begin{pmatrix} -2 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\text{Define } h_1(x) = \begin{cases} x^2, & x \geq 0, \\ -x^2, & x < 0. \end{cases}$$

$$h_2(y) = \begin{cases} \sqrt{|y|}, & y \geq 0, \\ -\sqrt{|y|}, & y < 0. \end{cases}$$

$$h(x, y) = (h_1(x), h_2(y))$$

$$\text{Then } \phi_B(t, Q \circ h \circ P^{-1}(x_0)) = Q \circ h \circ P^{-1}(\phi_A(t, x_0))$$

$H = Q \circ h \circ P^{-1}$ is our conjugacy.

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P136 #6

(a) eigenvalues $\lambda_1 = b$, $\lambda_2 = a + bi$, $\lambda_3 = a - bi$

eigenvectors $\vec{v}_1 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$ $\vec{v}_2 = \begin{pmatrix} 1 \\ 0 \\ i \end{pmatrix}$

general sol'n

$$\vec{X}(t) = c_1 e^{bt} \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} + c_2 e^{at} \begin{pmatrix} \cos bt \\ 0 \\ -\sin bt \end{pmatrix} + c_3 e^{at} \begin{pmatrix} \sin bt \\ 0 \\ \cos bt \end{pmatrix}$$

(b) Let $X = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$

$b < 0$, $\left\{ \begin{array}{l} a < 0 \\ a = 0 \\ a > 0 \end{array} \right.$ $(0,0,0)$ is asym. stable
stable in y direction, spiral sink in xz -plane
 $(0,0,0)$ is stable not asym. stable
a collection of periodic orbits in xz -plane
 $(0,0,0)$ is unstable
spiral source in xz -plane

$b > 0$, $\left\{ \begin{array}{l} a < 0 \\ a = 0 \\ a > 0 \end{array} \right.$ similar behavior in xz -plane as above
 $(0,0,0)$ is unstable in all these cases

$b = 0$, $\left\{ \begin{array}{l} a > 0 \\ a < 0 \end{array} \right.$ $(0,0,0)$ is unstable
 $(0,0,0)$ is stable but not asym. stable

In above two cases, static in y direction, no spirals
in xz -plane

$b = 0$ $a = 0$. every point in \mathbb{R}^3 is equilibrium point

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P138 #15

The equations are equivalent to

$$\begin{pmatrix} x_1'(t) \\ y_1'(t) \\ x_2'(t) \\ y_2'(t) \\ x_3'(t) \\ y_3'(t) \end{pmatrix} = \begin{pmatrix} 0 & 1 & 0 & 0 \\ -1 & 0 & 0 & 0 \\ 0 & 0 & \sqrt{2} & 0 \\ 0 & -\sqrt{2} & 0 & 0 \\ 0 & 0 & 0 & \omega \\ 0 & 0 & -\omega & 0 \end{pmatrix} \begin{pmatrix} x_1(t) \\ y_1(t) \\ x_2(t) \\ y_2(t) \\ x_3(t) \\ y_3(t) \end{pmatrix}$$

If $\frac{\omega}{\sqrt{2}}$ is rational, we have periodic motions in x_2 and x_3 , quasiperiodic everywhere else.

If $\frac{\omega}{\sqrt{2}}$ is irrational, quasiperiodic motions everywhere

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