

Chapter 8

$$\#5 (a) \begin{cases} x^2 + y = 0 \\ x - y + a = 0 \end{cases} \Rightarrow \begin{cases} y = -x^2 \\ x^2 + x + a = 0 \end{cases}$$

$$\Delta = 1 - 4a$$

• If $a > \frac{1}{4}$, then no solution for above system, no equilibrium points for the original system

• If $a = \frac{1}{4} \Rightarrow (-\frac{1}{2}, -\frac{1}{4})$ one equilibrium point

$$\text{Let } F(x, y) = \begin{pmatrix} x^2 + y \\ x - y + a \end{pmatrix} \Rightarrow DF(x, y) = \begin{pmatrix} 2x & 1 \\ 1 & -1 \end{pmatrix}$$

$$DF(-\frac{1}{2}, -\frac{1}{4}) = \begin{pmatrix} -1 & 1 \\ 1 & -1 \end{pmatrix}$$

• If $a < \frac{1}{4} \Rightarrow x_{\pm} = \frac{-1 \pm \sqrt{1-4a}}{2}$, equilibria:

$$\left(\frac{-1 + \sqrt{1-4a}}{2}, -\frac{2-4a-2\sqrt{1-4a}}{4} \right), \left(\frac{-1 - \sqrt{1-4a}}{2}, -\frac{2-4a+2\sqrt{1-4a}}{4} \right)$$

$$DF(x_+, -x_+^2)$$

$$= \begin{pmatrix} -1 + \sqrt{1-4a} & 1 \\ 1 & -1 \end{pmatrix}$$

$$DF(x_-, -x_-^2)$$

$$= \begin{pmatrix} -1 - \sqrt{1-4a} & 1 \\ 1 & -1 \end{pmatrix}$$

(b) • $a = \frac{1}{4}$ $\lambda_1 = 0, \lambda_2 = -2$ for $DF(-\frac{1}{2}, -\frac{1}{4})$

one stable direction, one center direction

$$y + \frac{1}{4} = x + \frac{1}{2} \quad \text{line of equilibria}$$

• For $a < \frac{1}{4}$,

$$(x_+, -x_+^2) \quad \det(DF(x_+, -x_+^2)) = -\sqrt{1-4a} < 0,$$

\Rightarrow linearized system is of saddle type

$$(x_-, -x_-^2) \quad \det(DF(x_-, -x_-^2)) = \sqrt{1-4a} > 0$$

$$\text{tr}(DF(x_-, -x_-^2)) = -2 - \sqrt{1-4a} < 0$$

$\Rightarrow \lambda_1, \lambda_2 < 0$, linearized system has a sink at $(x_-, -x_-^2)$

(c) $a = \frac{1}{4}$, there is a bifurcation point

$a < \frac{1}{4}$, two equilibria with one saddle, one sink

$a = \frac{1}{4}$, one equilibrium.

$a > \frac{1}{4}$, no equilibrium.

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$$\#9 \quad (a) \quad \begin{cases} r - r^2 = 0 & \Rightarrow r = 0 \text{ or } r = 1 \\ \sin \theta + a = 0 & \Rightarrow \sin \theta = -a \end{cases}$$

$(0,0)$ is an equilibrium; $r=1$ is invariant.

$a < -1$, $a = 1$, bifurcation occurs

(b) • $a < -1$, $\sin \theta + a < 0$ for $\forall \theta$
 every solution will move clockwise
 if $0 < r < 1$, then $r' > 0$, $r \uparrow$
 $r > 1$ then $r' < 0$, $r \downarrow$

All solutions will approach $r=1$ (limit cycle)

• $a = -1$, $\sin \theta + a < 0$ if $\theta \neq \frac{\pi}{2} + 2k\pi$, $k \in \mathbb{Z}$

$\sin \theta + a = 0$ if $\theta = \frac{\pi}{2} + 2k\pi$, $k \in \mathbb{Z}$.

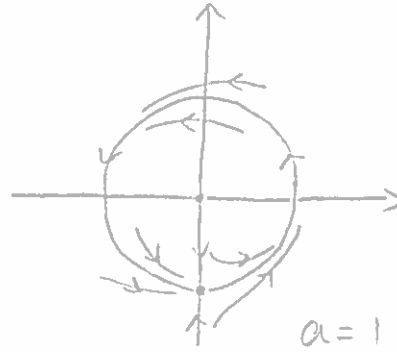
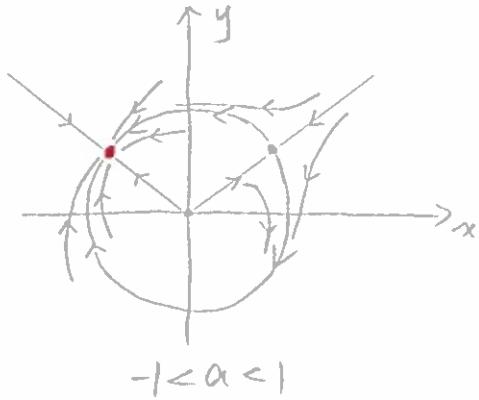
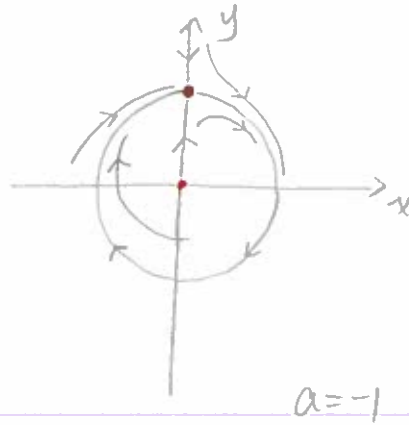
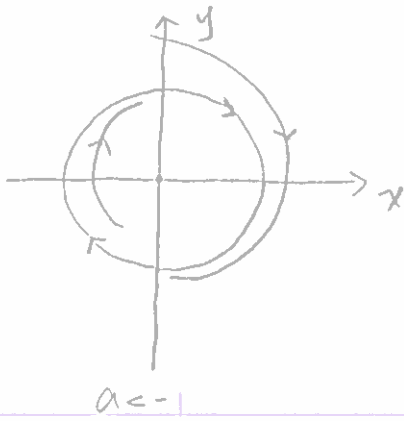
an equilibrium point $(r, \theta) = (1, \frac{\pi}{2})$ occurs

• $-1 < a < 1$ $\sin \theta + a = 0$ has two solutions for $\theta \in [0, 2\pi)$
 we have two equilibria on $r=1$, one is of saddle type,
 the other one is sink.

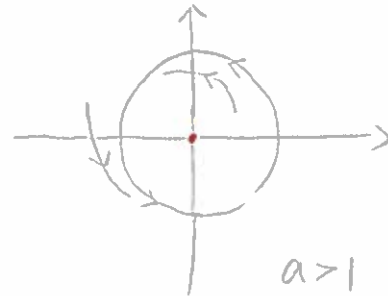
• $a = 1$ $\sin \theta + a = 0$ has one solution for $\theta \in [0, 2\pi)$
 one equilibrium $(r, \theta) = (1, \frac{3\pi}{2})$

• $a > 1$ $\sin \theta + a > 0$ every solution will move
 counterclockwise

(c)



(equilibria symmetric about y axis maybe above or below or on x axis)



(d) $a < -1$ or $a > 1$, only 1 equilibrium

$a = \pm 1$, 2 equilibria

$-1 < a < 1$, 3 equilibria

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