

# X[composite[x,y]]

*Johan G. F. Belinfante*  
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```
In[1]:= SetDirectory["i:"]; << goedel63.11a; << tools.m

:Package Title: goedel63.10b      2004 November 11 at 1:00 p.m.

It is now: 2004 Nov 12 at 8:9

Loading Simplification Rules

TOOLS.M                          Revised 2004 November 2

weightlimit = 40
```

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## summary

It is shown that if  $\mathbf{x}$  and  $\mathbf{y}$  admit cross-sections, and if  $\mathbf{range}[\mathbf{y}]$  is contained in  $\mathbf{domain}[\mathbf{x}]$ , then  $\mathbf{composite}[\mathbf{x}, \mathbf{y}]$  admits a cross-section. This result is useful for deriving the equivalence of various versions of the axiom of choice.

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## derivation

Lemma.

```
In[2]:= Map[not, SubstTest[and, implies[p3, p5], implies[p4, p6],
  implies[and[p1, p3, p6], p7], implies[p7, p8], implies[and[p2, p5, p8], p9],
  not[implies[and[p1, p2, p3, p4], p9]], {p1 -> equal[domain[u], domain[x]],
  p2 -> equal[domain[v], domain[y]], p3 -> subclass[range[y], domain[x]],
  p4 -> subclass[v, y], p5 -> equal[image[inverse[y], domain[x]], domain[y]],
  p6 -> subclass[range[v], range[y]], p7 -> subclass[range[v], domain[u]],
  p8 -> equal[image[inverse[v], domain[u]], domain[v]],
  p9 -> equal[image[inverse[v], domain[u]], image[inverse[y], domain[x]]]}]]

Out[2]= or[equal[image[inverse[v], domain[u]], image[inverse[y], domain[x]]],
  not[equal[domain[u], domain[x]]], not[equal[domain[v], domain[y]]],
  not[subclass[v, y]], not[subclass[range[y], domain[x]]] = True
```

```
In[3]:= (% /. {u -> u_, v -> v_, x -> x_, y -> y_}) /. Equal -> SetDelayed
```

For the next step one needs to turn off the **equality** flag.

```
In[4]:= equality = False;
```

```
In[5]:= implies[and[subclass[range[y], domain[x]], member[u, X[x]], member[v, X[y]]],
  member[composite[u, v], X[composite[x, y]]] // NotNotTest
```

```
Out[5]= or[and[equal[image[inverse[v], domain[u]], image[inverse[y], domain[x]]],
  FUNCTION[composite[u, v]], member[composite[u, v], V],
  subclass[composite[u, v], composite[x, y]]],
  not[equal[domain[u], domain[x]]], not[equal[domain[v], domain[y]]],
  not[FUNCTION[u]], not[FUNCTION[v]], not[member[u, V]],
  not[member[v, V]], not[subclass[u, x]], not[subclass[v, y]],
  not[subclass[range[y], domain[x]]] == True
```

```
In[6]:= (% /. {u -> u_, v -> v_, x -> x_, y -> y_}) /. Equal -> SetDelayed
```

The variables **u** and **v** are eliminated in the standard way.

```
In[7]:= Map[equal[0, composite[Id, complement[#]]] &,
  SubstTest[class, pair[u, v], implies[and[subclass[range[y], domain[x]],
  member[u, r], member[v, s]], member[composite[u, v], t]],
  {r -> X[x], s -> X[y], t -> X[composite[x, y]]}] // Reverse
```

```
Out[7]= or[not[subclass[range[y], domain[x]]],
  subclass[image[COMPOSE, cart[X[x], X[y]]], X[composite[x, y]]] == True
```

```
In[8]:= or[not[subclass[range[y_], domain[x_]]],
  subclass[image[COMPOSE, cart[X[x_], X[y_]]], X[composite[x_, y_]]] := True
```

Corollary. If **composite[x,y]** has no cross-section, and if **range[y]** is contained in **domain[x]**, then at least one of the classes **x** and **y** has no cross-section.

```
In[9]:= Map[implies[equal[0, X[composite[x, y]]], #] &, SubstTest[and,
  implies[p, subclass[u, v]], equal[0, v], {p -> subclass[range[y], domain[x]],
  u -> image[COMPOSE, cart[X[x], X[y]]], v -> X[composite[x, y]]}] // Reverse
```

```
Out[9]= or[equal[0, X[x]], equal[0, X[y]], not[equal[0, X[composite[x, y]]],
  not[subclass[range[y], domain[x]]] == True
```

```
In[10]:= or[equal[0, X[x_]], equal[0, X[y_]], not[equal[0, X[composite[x_, y_]]],
  not[subclass[range[y_], domain[x_]]] := True
```

---

## an application

To demonstrate the usefulness of the corollary derived in the preceding section, consider the argument that led to the equivalence between two versions of the axiom of choice, **ac1** and **ac2**. One lemma is needed:

```
In[11]:= SubstTest[implies, and[subclass[u, v], member[v, V]], member[u, V],
  {u -> range[VERTSECT[setpart[x]]], v -> P[range[setpart[x]]]}
```

```
Out[11]= member[range[VERTSECT[setpart[x]]], V] == True
```

```
In[12]:= member[range[VERTSECT[setpart[x_]]], V] := True
```

The essential step in the proof of **ac1**  $\Leftrightarrow$  **ac2** can now be deduced from the corollary in the preceding section as follows:

```
In[13]:= SubstTest[implies,
  and[subclass[range[v], domain[u]], equal[0, X[composite[u, v]]]],
  or[equal[0, X[u]], equal[0, X[v]], {u -> composite[inverse[E], id[t]],
  v -> composite[id[t], VERTSECT[setpart[x]]}] /.
  t -> dif[P[range[setpart[x]]], singleton[0]]
```

```
Out[13]= or[equal[0, X[composite[inverse[E], id[P[range[setpart[x]]]]]]],
  not[equal[0, X[setpart[x]]]] == True
```

```
In[14]:= (% /. x -> x_) /. Equal -> SetDelayed
```

To remove the **setpart** wrappers, the **equality** flag needs to be set.

```
In[15]:= equality = True;
```

```
In[16]:= Map[implies[member[x, y], #] &,
  SubstTest[implies, equal[w, setpart[x]], or[equal[0,
  X[composite[inverse[E], id[P[range[w]]]]]], not[equal[0, X[w]]], w -> x]]
```

```
Out[16]= or[equal[0, X[composite[inverse[E], id[P[range[x]]]]]],
  not[equal[0, X[x]]], not[member[x, y]] == True
```

```
In[17]:= or[equal[0, X[composite[inverse[E], id[P[range[x_]]]]]],
  not[equal[0, X[x_]]], not[member[x_, y_]] := True
```

The equivalence of the **ac2** and **ac3** versions of the axiom of choice can be derived in a similar fashion. To demonstrate this, a key step of that proof will be rederived. But first one needs to remove the rewrite rule in question:

```
In[18]:= or[equal[0, X[composite[id[x_], inverse[FIRST]]]], not[equal[0, X[x_]]] =.
```

The following result is weaker, but still suffices to prove that **ac2**  $\Leftrightarrow$  **ac3**. because for that one only needs to consider the case that **x** is a set.

---

```
In[19]:= SubstTest[implies,  
  and[subclass[range[v], domain[u]], equal[0, X[composite[u, v]]],  
  or[equal[0, X[u]], equal[0, X[v]]],  
  {u → composite[SECOND, id[x]], v → composite[id[x], inverse[FIRST]]}]  
Out[19]= or[equal[0, X[composite[id[x], inverse[FIRST]]]], not[equal[0, X[x]]],  
  not[member[domain[x], V]], not[member[range[x], V]]] = True
```