

# binclosed[rotate[gp[x]]]

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```
In[1]:= SetDirectory["1:"]; << goedel.11jun10a
      :Package Title: goedel.11jun10a          2011 June 10 at 10:35 a.m.
      Loading takes about eleven minutes, half that time due to builtin pauses.
      It is now: 2011 Jun 11 at 9:34
      Loading Simplification Rules
      TOOLS.M is now incorporated in the GOEDEL program as of 2010 September 3
      weightlimit = 40
      Loading completed.
      It is now: 2011 Jun 11 at 9:45
```

---

## summary

If  $x$  is a group, binary closure under **rotate[x]** is equivalent to binary closure under  $x$  plus invariance under **inv[x]**.

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## derivation

The **gp[x]** wrapper helps provide automatic simplifications. What needs to be shown is that **binclosed[rotate[gp[x]]]** is equal to the intersection of **binclosed[gp[x]]** and **invar[gp[x]]**. This equation will be derived by combining inclusions in two directions. The easy direction will be done first.

Lemma

```
In[6]:= Map[implies[subclass[image[inv[gp[x]], y], y], #] &,
      SubstTest[implies, subclass[u, v], subclass[image[t, u], image[t, v]],
      {t → gp[x], u → cart[image[inv[gp[x]], y], y], v → cart[y, y]}] // Reverse

Out[6]= or[not[subclass[image[inv[gp[x]], y], y]],
      subclass[image[gp[x], cart[image[inv[gp[x]], y], y], image[gp[x], cart[y, y]]] == True

In[7]:= (% /. {x → x_, y → y_}) /. Equal → SetDelayed
```

Lemma.

```
In[8]:= Map[not, SubstTest[and, implies[and[p1, p3], p4],
  implies[p2, p3], not[implies[and[p1, p2], p4]],
  {p1 -> subclass[image[gp[x], cart[y, y]], y], p2 -> invariant[inv[gp[x]], y],
  p3 -> subclass[image[gp[x], cart[image[inv[gp[x]], y], y]], image[gp[x], cart[y, y]]],
  p4 -> subclass[image[gp[x], cart[image[inv[gp[x]], y], y]], y}}] // Reverse
```

```
Out[8]= or[not[subclass[image[gp[x], cart[y, y]], y]], not[subclass[image[inv[gp[x]], y], y]],
  subclass[image[gp[x], cart[image[inv[gp[x]], y], y]], y]] = True
```

```
In[10]:= or[not[subclass[image[gp[x_], cart[y_, y_]], y_]],
  not[subclass[image[inv[gp[x_]], y_], y_]],
  subclass[image[gp[x_], cart[image[inv[gp[x_]], y_], y_]], y_] := True
```

Theorem. (Eliminating the variable  $y$ .)

```
In[11]:= Map[equal[V, #] &, complement[dif[intersection[binclosed[gp[x]], invar[inv[gp[x]]]],
  binclosed[composite[gp[x], SWAP, cross[Id, inv[gp[x]]]]]]] // Normality
```

```
Out[11]= subclass[intersection[binclosed[gp[x]], invar[inv[gp[x]]]],
  binclosed[composite[gp[x], SWAP, cross[Id, inv[gp[x]]]]] = True
```

```
In[12]:= (% /. x -> x_) /. Equal -> SetDelayed
```

## inclusion in the opposite direction

To derive an inclusion in the opposite direction, it is convenient to consider first subsets of  $\text{range}[\text{gp}[x]]$ , and only later to remove that limitation. The first step will be to show that if a subset  $y \subset \text{range}[\text{gp}[x]]$  is binary closed under  $\text{rotate}[\text{gp}[x]]$ , then it holds the neutral element  $e[\text{gp}[x]]$ . The strategy will be to consider an element  $u \in y$  and its inverse  $\text{APPLY}[\text{inv}[\text{gp}[x]], u]$ .

Theorem. If  $u \in y$  and  $y \subset \text{range}[\text{gp}[x]]$ , then  $\text{APPLY}[\text{inv}[\text{gp}[x]], u] \in \text{image}[\text{inv}[\text{gp}[x]], y]$ .

```
In[13]:= SubstTest[implies, and[member[u, y], subclass[y, domain[funpart[t]]],
  member[APPLY[funpart[t], u], image[funpart[t], y]], t -> inv[gp[x]]] // Reverse
```

```
Out[13]= or[member[APPLY[inv[gp[x]], u], image[inv[gp[x]], y]],
  not[member[u, y]], not[subclass[y, range[gp[x]]]] = True
```

```
In[14]:= or[member[APPLY[inv[gp[x_]], u_], image[inv[gp[x_]], y_]],
  not[member[u_, y_]], not[subclass[y_, range[gp[x_]]]] := True
```

Lemma.

```
In[15]:= Map[or[#, not[subclass[y, range[gp[x]]]]] &, SubstTest[implies, and[member[w, r],
  subclass[r, domain[funpart[t]]], subclass[image[funpart[t], r], y]],
  member[APPLY[funpart[t], w], y], {w → PAIR[APPLY[inv[gp[x]], u], u],
  r → cart[image[inv[gp[x]], y], y], t → gp[x]}] // Reverse
```

```
Out[15]= or[member[e[gp[x]], y], not[member[u, y]], not[member[u, range[gp[x]]]],
  not[member[APPLY[inv[gp[x]], u], image[inv[gp[x]], y]]],
  not[subclass[y, range[gp[x]]]],
  not[subclass[image[gp[x], cart[image[inv[gp[x]], y], y]], y]]] = True
```

```
In[16]:= (% /. {u → u_, x → x_, y → y_}) /. Equal → SetDelayed
```

The preceding lemma can be improved upon by eliminating two redundant literals.

Lemma. If a subset  $y \in \text{range}[\text{gp}[x]]$  is binary closed under  $\text{rotate}[\text{gp}[x]]$  and  $u \in y$ , then  $e[\text{gp}[x]] \in y$ .

```
In[17]:= Map[not, SubstTest[and, implies[and[p1, p2], p4],
  implies[and[p1, p2], p5], (*implies[and[p1, p2, p3, p4, p5], p6], *)
  not[implies[and[p1, p2, p3], p6]], {p1 → member[u, y], p2 → subclass[y, range[gp[x]]],
  p3 → subclass[image[gp[x], cart[image[inv[gp[x]], y], y]], y],
  p4 → member[u, range[gp[x]]], p5 → member[APPLY[inv[gp[x]], u],
  image[inv[gp[x]], y]], p6 → member[e[gp[x]], y]}] // Reverse
```

```
Out[17]= or[member[e[gp[x]], y], not[member[u, y]], not[subclass[y, range[gp[x]]]],
  not[subclass[image[gp[x], cart[image[inv[gp[x]], y], y]], y]]] = True
```

```
In[18]:= (% /. {u → u_, x → x_, y → y_}) /. Equal → SetDelayed
```

The element  $u \in y$  has served its purpose and can now be eliminated.

Theorem. If a non-empty subset  $y \in \text{range}[\text{gp}[x]]$  is binary closed under  $\text{rotate}[\text{gp}[x]]$ , then  $e[\text{gp}[x]] \in y$ .

```
In[19]:= Map[equal[V, #] &, SubstTest[class, u,
  or[member[t, y], not[member[u, y]], not[subclass[y, r]], not[subclass[w, y]]],
  {t → e[gp[x]], r → range[gp[x]], w → image[gp[x], cart[image[inv[gp[x]], y], y]}]]
```

```
Out[19]= or[equal[0, y], member[e[gp[x]], y], not[subclass[y, range[gp[x]]]],
  not[subclass[image[gp[x], cart[image[inv[gp[x]], y], y]], y]]] = True
```

```
In[20]:= or[equal[0, y_], member[e[gp[x_]], y_], not[subclass[y_, range[gp[x_]]]],
  not[subclass[image[gp[x_], cart[image[inv[gp[x_]], y_], y_]], y_]] := True
```

The next step is to show that  $y$  is invariant under inversion. Again, a particular element  $u \in y$  will be chosen, and later eliminated.

Lemma.

```
In[21]:= Map[or[#, not[subclass[y, range[gp[x]]]]] &, SubstTest[implies, and[member[w, r],
  subclass[r, domain[funpart[t]]], subclass[image[funpart[t], r], y]],
  member[APPLY[funpart[t], w], y], {w → PAIR[APPLY[inv[gp[x]], u], e[gp[x]]],
  r → cart[image[inv[gp[x]], y], y], t → gp[x]}] // Reverse
```

```
Out[21]= or[equal[0, gp[x]], member[APPLY[inv[gp[x]], u], y], not[member[u, range[gp[x]]]],
  not[member[APPLY[inv[gp[x]], u], image[inv[gp[x]], y]]],
  not[member[e[gp[x]], y]], not[subclass[y, range[gp[x]]]],
  not[subclass[image[gp[x], cart[image[inv[gp[x]], y], y]], y]]] = True
```

```
In[22]:= (% /. {u → u_, x → x_, y → y_}) /. Equal → SetDelayed
```

Theorem. If  $y \subset \text{range}[gp[x]]$  is binary closed under  $\text{rotate}[gp[x]]$  and  $u \in y$ , then  $\text{APPLY}[inv[gp[x]], u] \in y$ .

```
In[23]:= Map[not, SubstTest[and, implies[and[p0, p2, p3], p1],
  implies[p1, p4], implies[and[p0, p2], p5], implies[and[p0, p2], p6],
  (*implies[and[p1, p2, p3, p4, p5, p6], p7]*) not[implies[and[p0, p2, p3], p7]],
  {p0 → member[u, y], p1 → member[e[gp[x]], y], p2 → subclass[y, range[gp[x]]],
  p3 → subclass[image[gp[x], cart[image[inv[gp[x]], y], y]], y],
  p4 → not[empty[gp[x]]], p5 → member[APPLY[inv[gp[x]], u], image[inv[gp[x]], y]],
  p6 → member[u, range[gp[x]]], p7 → member[APPLY[inv[gp[x]], u], y]}] // Reverse
```

```
Out[23]= or[member[APPLY[inv[gp[x]], u], y], not[member[u, y]], not[subclass[y, range[gp[x]]]],
  not[subclass[image[gp[x], cart[image[inv[gp[x]], y], y]], y]]] = True
```

```
In[25]:= or[member[APPLY[inv[gp[x_]], u_], y_], not[member[u_, y_]],
  not[subclass[image[gp[x_], cart[image[inv[gp[x_]], y_], y_]], y_]],
  not[subclass[y_, range[gp[x_]]]]] := True
```

Eliminating the variable  $u$  yields a subvariance statement.

Theorem. If  $y \subset \text{range}[gp[x]]$  is binary closed under  $\text{rotate}[gp[x]]$ , then  $y$  is subvariant under  $inv[gp[x]]$ .

```
In[26]:= Map[equal[V, #] &, SubstTest[class, u, or[member[APPLY[t, u], y],
  not[member[u, y]], not[subclass[y, r]], not[subclass[w, y]]],
  {t → inv[gp[x]], r → range[gp[x]], w → image[gp[x], cart[image[inv[gp[x]], y], y]}]]
```

```
Out[26]= or[not[subclass[y, range[gp[x]]]],
  not[subclass[image[gp[x], cart[image[inv[gp[x]], y], y]], y]],
  subclass[y, image[inv[gp[x]], y]]] = True
```

```
In[27]:= or[not[subclass[y_, range[gp[x_]]]],
  not[subclass[image[gp[x_], cart[image[inv[gp[x_]], y_], y_]], y_]],
  subclass[y_, image[inv[gp[x_]], y_]]] := True
```

Lemma. If a subset  $y \subset \text{range}[gp[x]]$  is subvariant under  $inv[gp[x]]$ , then  $y$  is also invariant under  $inv[gp[x]]$ .

```
In[34]:= Map[implies[and[subclass[y, range[gp[x]]], #], invariant[inv[gp[x]], y]] &,
  SubstTest[member, y, subvar[t], t → inv[gp[x]]]
```

```
Out[34]= or[not[subclass[y, image[inv[gp[x]], y]]],
  not[subclass[y, range[gp[x]]]], subclass[image[inv[gp[x]], y], y]] = True
```

```
In[36]:= or[not[subclass[y_, image[inv[gp[x_]], y_]]],
          not[subclass[y_, range[gp[x_]]]], subclass[image[inv[gp[x_]], y_], y_] := True
```

Corollary. If  $y \subset \text{range}[gp[x]]$  is binary closed under  $\text{rotate}[gp[x]]$ , then  $y$  is invariant under  $\text{inv}[gp[x]]$ .

```
In[37]:= Map[not, SubstTest[and, implies[p1, p2],
                          not[implies[p1, p3]], {p1 → and[subclass[y, range[gp[x]]],
                          subclass[image[gp[x], cart[image[inv[gp[x]], y], y]], y]],
                          p2 → subvariant[inv[gp[x]], y], p3 → invariant[inv[gp[x]], y]}]] // Reverse
```

```
Out[37]= or[not[subclass[y, range[gp[x]]]],
           not[subclass[image[gp[x], cart[image[inv[gp[x]], y], y]], y]],
           subclass[image[inv[gp[x]], y], y] == True
```

```
In[38]:= (% /. {x → x_, y → y_}) /. Equal → SetDelayed
```

The condition  $y \subset \text{range}[gp[x]]$  is not needed.

Theorem. Any class that is binary closed under  $\text{rotate}[gp[x]]$  is invariant under  $\text{inv}[gp[x]]$ .

```
In[40]:= SubstTest[or, not[subclass[t, range[gp[x]]]],
                not[subclass[image[gp[x], cart[image[inv[gp[x]], t], t]], t]],
                subclass[image[inv[gp[x]], t], t], t → intersection[y, range[gp[x]]]] // Reverse
```

```
Out[40]= or[not[subclass[image[gp[x], cart[image[inv[gp[x]], y], y]], y]],
           subclass[image[inv[gp[x]], y], y] == True
```

```
In[42]:= or[not[subclass[image[gp[x_], cart[image[inv[gp[x_]], y_], y_]], y_]],
           subclass[image[inv[gp[x_]], y_], y_] := True
```

Corollary. The class  $\text{binclosed}[\text{rotate}[gp[x]]]$  is a subclass of  $\text{invar}[\text{inv}[gp[x]]]$ .

```
In[43]:= Map[equal[V, #] &,
            complement[dif[binclosed[rotate[gp[x]]], invar[inv[gp[x]]]]] // Normality]
```

```
Out[43]= subclass[binclosed[composite[gp[x], SWAP, cross[Id, inv[gp[x]]]]], invar[inv[gp[x]]]] ==
          True
```

```
In[44]:= (% /. x → x_) /. Equal → SetDelayed
```

## binary closure

It remains to be shown that a set that is binary closed under  $\text{rotate}[gp[x]]$  is also binary closed under  $gp[x]$  itself.

Lemma.

```
In[3]:= SubstTest[implies, subclass[u, v], subclass[image[t, u], image[t, v]],
                {t → gp[x], u → cart[y, y], v → cart[image[inv[gp[x]], y], y]}] // Reverse
```

```
Out[3]= or[not[subclass[y, image[inv[gp[x]], y]]],
          subclass[image[gp[x], cart[y, y]], image[gp[x], cart[image[inv[gp[x]], y], y]]] == True
```

```
In[4]:= (% /. {x → x_, y → y_}) /. Equal → SetDelayed
```

Theorem. If a subset  $y \subset \text{range}[\text{gp}[x]]$  is binary closed under  $\text{rotate}[\text{gp}[x]]$ , then  $y$  is binary closed under  $\text{gp}[x]$ .

```
In[45]:= Map[not,
  SubstTest[and, implies[and[p1, p2], p3], implies[p3, p4], implies[and[p2, p4], p5],
    not[implies[and[p1, p2], p5]], {p1 → subclass[y, range[gp[x]]],
      p2 → subclass[image[gp[x], cart[image[inv[gp[x]], y], y]], y],
      p3 → subclass[y, image[inv[gp[x]], y]], p4 →
        subclass[image[gp[x], cart[y, y]], image[gp[x], cart[image[inv[gp[x]], y], y]]],
      p5 → subclass[image[gp[x], cart[y, y], y]}] // Reverse
```

```
Out[45]= or[not[subclass[y, range[gp[x]]]],
  not[subclass[image[gp[x], cart[image[inv[gp[x]], y], y]], y]],
  subclass[image[gp[x], cart[y, y], y]] = True
```

```
In[46]:= (% /. {x → x_, y → y_}) /. Equal → SetDelayed
```

Again, the condition  $y \subset \text{range}[\text{gp}[x]]$  is not needed.

Corollary. Any class that is binary closed under  $\text{rotate}[\text{gp}[x]]$  is binary closed under  $\text{gp}[x]$ .

```
In[47]:= SubstTest[or, not[subclass[t, range[gp[x]]]],
  not[subclass[image[gp[x], cart[image[inv[gp[x]], t], t]], t]],
  subclass[image[gp[x], cart[t, t], t], t → intersection[y, range[gp[x]]] // Reverse
```

```
Out[47]= or[not[subclass[image[gp[x], cart[image[inv[gp[x]], y], y]], y]],
  subclass[image[gp[x], cart[y, y], y]] = True
```

```
In[48]:= or[not[subclass[image[gp[x_], cart[image[inv[gp[x_]], y_], y_]], y_]],
  subclass[image[gp[x_], cart[y_, y_], y_] := True
```

The variable  $y$  can be eliminated.

Theorem.

```
In[49]:= Map[equal[V, #] &,
  complement[dif[binclosed[rotate[gp[x]]], binclosed[gp[x]]] // Normality]
```

```
Out[49]= subclass[binclosed[composite[gp[x], SWAP, cross[Id, inv[gp[x]]]]], binclosed[gp[x]]] ==
  True
```

```
In[50]:= (% /. x → x_) /. Equal → SetDelayed
```

Main Theorem. An equation for  $\text{binclosed}[\text{rotate}[\text{gp}[x]]]$ .

```
In[51]:= SubstTest[and, subclass[u, v], subclass[v, u],
  {u → binclosed[rotate[gp[x]]], v → intersection[binclosed[gp[x]], invar[inv[gp[x]]]]}]
```

```
Out[51]= equal[binclosed[composite[gp[x], SWAP, cross[Id, inv[gp[x]]]]],
  intersection[binclosed[gp[x]], invar[inv[gp[x]]]]] = True
```

```
In[53]:= binclosed[composite[gp[x_], SWAP, cross[Id, inv[gp[x_]]]]] :=  
  intersection[binclosed[gp[x]], invar[inv[gp[x]]]
```

Corollary. (Remove the **gp** wrapper.)

```
In[55]:= SubstTest[implies, equal[x, gp[t]], equal[binclosed[rotate[x]],  
  intersection[binclosed[x], invar[inv[x]]]], t → x] // Reverse // MapNotNot
```

```
Out[55]= or[equal[binclosed[rotate[x]], intersection[binclosed[x], invar[inv[x]]]],  
  not[member[x, GROUPS]]] == True
```

```
In[56]:= or[equal[binclosed[rotate[x_]], intersection[binclosed[x_], invar[inv[x_]]]],  
  not[member[x_, GROUPS]]] := True
```