

# binary closure of EQUIDIFF under vector addition

Johan G. F. Belinfante  
2011 October 13

```
In[1]:= SetDirectory["1:"]; << goedel.11oct07a

:Package Title: goedel.11oct07a          2011 October 7 at 5:00 p.m.

Loading takes about thirteen minutes, half that time due to builtin pauses.

It is now: 2011 Oct 13 at 14:41

Loading Simplification Rules

TOOLS.M is now incorporated in the GOEDEL program as of 2010 September 3

weightlimit = 40

Loading completed.

It is now: 2011 Oct 13 at 14:53
```

---

## summary

In this notebook it is shown that **EQUIDIFF** is binary closed under the direct square of the direct square of **NATADD**. In fact, an equation holds. The derivation is done entirely without introducing variables. If one were to introduce variables, one would need eight of them. The relation **EQUIDIFF** holds pairs of pairs of natural numbers  $((\mathbf{a}, \mathbf{b}), (\mathbf{c}, \mathbf{d}))$  satisfying  $\mathbf{a} + \mathbf{d} = \mathbf{b} + \mathbf{c}$ . What needs to be shown is that the vector sum of two such vectors is another. That is, if  $\mathbf{a} + \mathbf{d} = \mathbf{b} + \mathbf{c}$  and  $\mathbf{e} + \mathbf{h} = \mathbf{f} + \mathbf{g}$ , then  $(\mathbf{a} + \mathbf{e}) + (\mathbf{d} + \mathbf{h}) = (\mathbf{b} + \mathbf{f}) + (\mathbf{c} + \mathbf{g})$ . The associative and commutative laws of natural number addition are needed to do this.

---

## temporary abbreviation

To save some writing, the following abbreviation is used occasionally.

```
In[2]:= dirsq[x_] := direct[x, x]
```

---

## inclusion in one direction

An inclusion in one direction is established in this section.

Lemma. The ordered pair of pairs  $((\mathbf{0}, \mathbf{0}), (\mathbf{0}, \mathbf{0}))$  belongs to **EQUIDIFF**.

```
In[3]:= subclass[cartsq[cartsq[set[0]]], EQUIDIFF] // AssertTest
Out[3]= subclass[cart[cart[set[0], set[0]], cart[set[0], set[0]]], EQUIDIFF] == True
In[4]:= subclass[cart[cart[set[0], set[0]], cart[set[0], set[0]]], EQUIDIFF] := True
```

Lemma. Simplification rule.

```
In[5]:= composite[FIRST, id[cart[V, cartsq[set[0]]]], inverse[dirsq[NATADD]]] //
FastReifNormality
```

```
Out[5]= composite[FIRST, id[cart[V, cart[set[0], set[0]]]], TWIST,
cross[inverse[NATADD], inverse[NATADD]]] == id[cart[omega, omega]]
```

```
In[6]:= % /. Equal -> SetDelayed
```

Theorem. An inclusion in one direction.

```
In[7]:= SubstTest[implies, subclass[u, v], subclass[image[t, u], image[t, v]],
{t -> composite[dirsq[dirsq[NATADD]], id[cart[EQUIDIFF, V]], inverse[SECOND]],
u -> cartsq[cartsq[set[0]]], v -> EQUIDIFF}] // Reverse
```

```
Out[7]= subclass[EQUIDIFF, composite[cross[NATADD, NATADD], TWIST,
cross[EQUIDIFF, EQUIDIFF], TWIST, cross[inverse[NATADD], inverse[NATADD]]]] == True
```

```
In[8]:= % /. Equal -> SetDelayed
```

## the medial law

Lemma. Any commutative associative binary operation satisfies the medial law.

```
In[9]:= SubstTest[implies, and[associative[x], equal[flip[x], x]],
equal[composite[x, dirsq[x]], composite[x, cross[x, x]]], x -> dirsq[NATADD]] // Reverse
```

```
Out[9]= equal[composite[cross[NATADD, NATADD], TWIST, cross[
composite[cross[NATADD, NATADD], TWIST], composite[cross[NATADD, NATADD], TWIST]]],
composite[cross[NATADD, NATADD], TWIST, cross[composite[cross[NATADD, NATADD], TWIST],
composite[cross[NATADD, NATADD], TWIST]]], TWIST]] == True
```

```
In[10]:= % /. Equal -> SetDelayed
```

Theorem. The medial law allows one to remove one copy of **TWIST**.

```

In[11]:= SubstTest[implies, equal[u, v], equal[image[inverse[u], Id], image[inverse[v], Id]],
  {u -> composite[cross[NATADD, NATADD], TWIST, cross[composite[
    cross[NATADD, NATADD], TWIST], composite[cross[NATADD, NATADD], TWIST]]],
  v -> composite[cross[NATADD, NATADD], TWIST, cross[composite[cross[NATADD, NATADD],
    TWIST], composite[cross[NATADD, NATADD], TWIST]]]} // Reverse

Out[11]= equal[composite[cross[Id, SWAP],
  twist[composite[TWIST, cross[inverse[NATADD], inverse[NATADD]],
    EQUIDIFF, cross[NATADD, NATADD], TWIST]], cross[Id, SWAP]],
  composite[cross[SWAP, SWAP], TWIST, cross[inverse[NATADD], inverse[NATADD]],
  EQUIDIFF, cross[NATADD, NATADD], TWIST]] == True

In[12]:= % /. Equal -> SetDelayed

```

---

## main theorem

Lemma.

```

In[13]:= SubstTest[implies, equal[u, v],
  equal[composite[t, u, w], composite[t, v, w]], {t -> cross[SWAP, Id],
  u -> composite[cross[SWAP, SWAP], TWIST, cross[inverse[NATADD], inverse[NATADD]],
    EQUIDIFF, cross[NATADD, NATADD], TWIST], v -> composite[cross[Id, SWAP],
    twist[composite[TWIST, cross[inverse[NATADD], inverse[NATADD]], EQUIDIFF, cross[
      NATADD, NATADD], TWIST]], cross[Id, SWAP]], w -> cross[Id, SWAP]}] // Reverse

Out[13]= equal[composite[cross[SWAP, SWAP],
  twist[composite[TWIST, cross[inverse[NATADD], inverse[NATADD]],
    EQUIDIFF, cross[NATADD, NATADD], TWIST]], id[cart[V, cart[V, V]]]],
  composite[cross[Id, SWAP], TWIST, cross[inverse[NATADD], inverse[NATADD]],
  EQUIDIFF, cross[NATADD, NATADD], TWIST, cross[Id, SWAP]]] == True

In[14]:= % /. Equal -> SetDelayed

```

Lemma.

```

In[15]:= SubstTest[implies, subclass[u, v], subclass[image[t, u], image[t, v]],
  {t -> inverse[cross[dirsq[NATADD], dirsq[NATADD]]],
  u -> cartsq[id[omega]], v -> EQUIDIFF}] // Reverse

Out[15]= subclass[cart[composite[SWAP, EQUIDIFF], composite[SWAP, EQUIDIFF]],
  composite[TWIST, cross[inverse[NATADD], inverse[NATADD]],
  EQUIDIFF, cross[NATADD, NATADD], TWIST]] == True

In[16]:= % /. Equal -> SetDelayed

```

Lemma.

```
In[17]:= SubstTest[implies, subclass[u, v],
  subclass[image[t, u], image[t, v]], {t → composite[cross[Id, cross[SWAP, SWAP]],
  TWIST, inverse[cross[dirs[NATADD], dirs[NATADD]]]},
  u → cartsq[id[omega]], v → EQUIDIFF} // Reverse
```

```
Out[17]= subclass[cross[EQUIDIFF, EQUIDIFF], composite[cross[SWAP, SWAP],
  twist[composite[TWIST, cross[inverse[NATADD], inverse[NATADD]]],
  EQUIDIFF, cross[NATADD, NATADD], TWIST]]] == True
```

```
In[18]:= % /. Equal → SetDelayed
```

Lemma.

```
In[19]:= SubstTest[implies, subclass[u, v], subclass[image[t, u], image[t, v]],
  {t → composite[TWIST, cross[Id, cross[SWAP, SWAP]],
  TWIST, inverse[cross[dirs[NATADD], dirs[NATADD]]]},
  u → cartsq[id[omega]], v → EQUIDIFF} // Reverse
```

```
Out[19]= subclass[cart[EQUIDIFF, EQUIDIFF],
  composite[cross[Id, SWAP], TWIST, cross[inverse[NATADD], inverse[NATADD]],
  EQUIDIFF, cross[NATADD, NATADD], TWIST, cross[Id, SWAP]]] == True
```

```
In[20]:= % /. Equal → SetDelayed
```

Theorem.

```
In[21]:= SubstTest[implies, and[subclass[u, v], equal[v, w]], subclass[u, w],
  {u → cross[EQUIDIFF, EQUIDIFF], v → composite[cross[SWAP, SWAP],
  twist[composite[TWIST, cross[inverse[NATADD], inverse[NATADD]]],
  EQUIDIFF, cross[NATADD, NATADD], TWIST]], id[cart[v, cart[v, v]]]},
  w → composite[cross[Id, SWAP], TWIST, cross[inverse[NATADD], inverse[NATADD]],
  EQUIDIFF, cross[NATADD, NATADD], TWIST, cross[Id, SWAP]]} // Reverse
```

```
Out[21]= subclass[cross[EQUIDIFF, EQUIDIFF],
  composite[cross[Id, SWAP], TWIST, cross[inverse[NATADD], inverse[NATADD]],
  EQUIDIFF, cross[NATADD, NATADD], TWIST, cross[Id, SWAP]]] == True
```

```
In[22]:= % /. Equal → SetDelayed
```

Theorem.

```
In[23]:= Assoc[composite[TWIST, cross[inverse[NATADD], inverse[NATADD]]], EQUIDIFF,
  cross[NATADD, NATADD]], SWAP, composite[TWIST, cross[SWAP, SWAP]] // Reverse
```

```
Out[23]= composite[cross[SWAP, SWAP], TWIST, cross[inverse[NATADD], inverse[NATADD]],
  EQUIDIFF, cross[NATADD, NATADD], TWIST, cross[SWAP, SWAP]] == composite[TWIST,
  cross[inverse[NATADD], inverse[NATADD]], EQUIDIFF, cross[NATADD, NATADD], TWIST]
```

```
In[24]:= % /. Equal → SetDelayed
```

Lemma.

```
In[25]:= SubstTest[implies, subclass[u, v], subclass[composite[t, u, w], composite[t, v, w]],
  {t -> cross[SWAP, Id], u -> cross[EQUIDIFF, EQUIDIFF],
   v -> composite[cross[Id, SWAP], TWIST, cross[inverse[NATADD], inverse[NATADD]],
    EQUIDIFF, cross[NATADD, NATADD], TWIST, cross[Id, SWAP]},
   w -> cross[SWAP, Id]}] // Reverse
```

```
Out[25]= subclass[cross[EQUIDIFF, EQUIDIFF],
  composite[TWIST, cross[inverse[NATADD], inverse[NATADD]],
  EQUIDIFF, cross[NATADD, NATADD], TWIST] == True
```

```
In[26]:= % /. Equal -> SetDelayed
```

Theorem.

```
In[27]:= SubstTest[implies, subclass[u, v], subclass[image[t, u], image[t, v]],
  {t -> cross[dirsq[NATADD], dirsq[NATADD]], u -> cross[EQUIDIFF, EQUIDIFF],
   v -> composite[TWIST, cross[inverse[NATADD], inverse[NATADD]],
    EQUIDIFF, cross[NATADD, NATADD], TWIST]}] // Reverse
```

```
Out[27]= subclass[composite[cross[NATADD, NATADD], TWIST, cross[EQUIDIFF, EQUIDIFF],
  TWIST, cross[inverse[NATADD], inverse[NATADD]]], EQUIDIFF] == True
```

```
In[28]:= % /. Equal -> SetDelayed
```

Main Theorem. An equation that says  $\text{EQUIDIFF} + \text{EQUIDIFF} = \text{EQUIDIFF}$ , where  $+$  denotes vector addition of sets.

```
In[29]:= SubstTest[and, subclass[u, v], subclass[v, u],
  {u -> composite[cross[NATADD, NATADD], TWIST, cross[EQUIDIFF, EQUIDIFF],
    TWIST, cross[inverse[NATADD], inverse[NATADD]]}, v -> EQUIDIFF}]
```

```
Out[29]= equal[EQUIDIFF, composite[cross[NATADD, NATADD], TWIST,
  cross[EQUIDIFF, EQUIDIFF], TWIST, cross[inverse[NATADD], inverse[NATADD]]]] == True
```

```
In[30]:= composite[cross[NATADD, NATADD], TWIST, cross[EQUIDIFF, EQUIDIFF],
  TWIST, cross[inverse[NATADD], inverse[NATADD]]] := EQUIDIFF
```

It follows from this that **EQUIDIFF** is binary closed under the direct square of the direct square of **NATADD**.

```
In[31]:= member[EQUIDIFF, binclosed[dirsq[dirsq[NATADD]]]]
```

```
Out[31]= True
```