

epsilon induction

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```
In[1]:= SetDirectory["i:"]; << goedel64.28a; << tools.m

:Package Title: goedel64.28a          2004 December 28 at 8:50 a.m.

It is now: 2004 Dec 30 at 10:11

Loading Simplification Rules

TOOLS.M                      Revised 2004 December 21

weightlimit = 40
```

epsilon induction

In this notebook, the proof of theorem **TC-REG-2** obtained by **Otter** on 2001 March 24 is rederived. This theorem is similar to what Thomas Jech calls proof by epsilon induction. See Theorem 25(A) on page 73 of the following reference:

```
In[2]:= "Thomas Jech, Set Theory, Academic Press, San Diego (1978).";
```

The notation and terminology differs slightly. What is here called the full class \mathbf{x} he calls a transitive class, which he denotes by \mathbf{T} . Jech talks about a property Φ instead of the class \mathbf{y} of sets that satisfy some property. Jech assumes that the axiom of regularity holds, in which case **REGULAR** = **V**, so one can omit the intersection with the class **REGULAR** that appears in theorem **TC-REG-2**. Jech adds an unnecessary hypothesis that the empty set belongs to the class \mathbf{y} . When the axiom of regularity holds, any non-empty full class \mathbf{x} holds the empty set. If \mathbf{x} is not empty, the condition **subclass[intersection[x,P[y]],y]** implies that the empty set belongs to \mathbf{y} . When \mathbf{x} is empty, the theorem holds trivially.

main argument

Lemma.

```
In[3]:= SubstTest[implies, and[member[z, w], subclass[w, y]],
  member[z, y], w → intersection[x, P[y]]]
```

```
Out[3]= or[member[z, y], not[member[z, x]], not[subclass[z, y]],
  not[subclass[intersection[x, P[y]], y]]] == True
```

```
In[4]:= (% /. {x → x_, y → y_, z → z_}) /. Equal → SetDelayed
```

Main part of **Otter's** argument.

```
In[5]:= Map[not, SubstTest[and, implies[and[p1, p4], p5], implies[and[p3, p5], p6],
  implies[and[p2, p4, p6], p7], not[implies[and[p1, p2, p3, p4], p7]],
  {p1 → full[x], p2 → subclass[intersection[x, P[y]], y],
  p3 → subclass[intersection[x, z], y], p4 → member[z, x],
  p5 → subclass[z, x], p6 → subclass[z, y], p7 → member[z, y]}]]]
```

```
Out[5]= or[member[z, y], not[member[z, x]], not[subclass[intersection[x, z], y]],
  not[subclass[intersection[x, P[y]], y]], not[subclass[U[x], x]]] == True
```

```
In[6]:= (% /. {x → x_, y → y_, z → z_}) /. Equal → SetDelayed
```

Elimination of the variable **z**.

```
In[7]:= Map[equal[V, #] &, SubstTest[class, z, or[member[z, y], not[member[z, x]],
  not[subclass[intersection[x, z], y]], not[subclass[w, y]],
  not[subclass[U[x], x]]], w → intersection[x, P[y]]] // Reverse
```

```
Out[7]= or[not[subclass[intersection[x, P[y]], y]], not[subclass[U[x], x]],
  subclass[intersection[x, P[union[y, complement[x]]], y]] == True
```

```
In[8]:= (% /. {x → x_, y → y_, z → z_}) /. Equal → SetDelayed
```

the rest of the story

The following special case is available, and will be used to prove the general case.

```
In[9]:= implies[subclass[P[x], x], subclass[REGULAR, x]]
```

```
Out[9]= True
```

A straightforward substitution yields a result with the desired conclusion, but a different hypothesis.

```
In[10]:= SubstTest[implies, subclass[P[z], z],
  subclass[REGULAR, z], z → union[y, complement[x]]]
```

```
Out[10]= or[not[subclass[intersection[x, P[union[y, complement[x]]]], y]],
  subclass[intersection[REGULAR, x], y]] == True
```

```
In[11]:= (% /. {x → x_, y → y_}) /. Equal → SetDelayed
```

This result is combined with that of the preceding section.

```
In[12]:= Map[not, SubstTest[and, implies[and[p1, p2], p3],
  implies[p3, p4], not[implies[and[p1, p2], p4]],
  {p1 → full[x], p2 → subclass[intersection[x, P[y]], y],
  p3 → subclass[intersection[x, P[union[y, complement[x]]]], y],
  p4 → subclass[intersection[REGULAR, x], y]}]]
```

```
Out[12]= or[not[subclass[intersection[x, P[y]], y]],
  not[subclass[U[x], x]], subclass[intersection[REGULAR, x], y]] == True
```

```
In[13]:= or[not[subclass[intersection[x_, P[y_]], y_]],
  not[subclass[U[x_], x_]], subclass[intersection[REGULAR, x_], y_]] := True
```