

monotonicity of addition

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2002 June 19

```
<< goedel52.o61; << tools.m
:Package Title: goedel52.o61      2002 June 18 at 10:50 p.m.

It is now: 2002 Jun 19 at 5:7

Loading Simplification Rules

TOOLS.M                          Revised 2002 June 12

weightlimit = 40
```

■ Introduction

A formula expressing the monotonicity of addition is derived in this notebook for the case that one of the summands is fixed. The argument uses induction, and the relation **COMMUTE**. The basic commutativity result used is that if **x** commutes with **y** and **z**, then **x** also commutes with **composite[y,z]**. Because **NATADD** does not currently satisfy any normality tests, it needs to be sequestered from the action of **assert** in several steps.

■ some sethood lemmas

For convenience we introduce a temporary abbreviation:

```
r[x_] := restrict[x, omega, omega]
```

Since **omega** is a set, all such restrictions are sets:

```
member[r[x], V] // AssertTest
member[composite[id[omega], x, id[omega]], V] == True
member[composite[id[omega], x_, id[omega]], V] := True
```

In particular:

```
member[r[S], V]
True
```

Various expressions involving **NATADD** are also sets, but one needs to sequester **NATADD** from the action of **assert** to derive these:

```

(member[composite[funpart[z], RIGHT[x]], V] // AssertTest) /. z -> composite[SUCC, NATADD]
member[composite[SUCC, NATADD, RIGHT[x]], V] == True

member[composite[SUCC, NATADD, RIGHT[x_]], V] := True

(member[composite[funpart[z], r[S]], V] // AssertTest) /. z -> composite[NATADD, RIGHT[x]]
member[composite[NATADD, RIGHT[x], id[omega], S, id[omega]], V] == True

member[composite[NATADD, RIGHT[x_], id[omega], S, id[omega]], V] := True

(member[composite[funpart[z], r[S]], V] // AssertTest) /.
  z -> composite[SUCC, NATADD, RIGHT[x]]
member[composite[SUCC, NATADD, RIGHT[x], id[omega], S, id[omega]], V] == True

member[composite[SUCC, NATADD, RIGHT[x_], id[omega], S, id[omega]], V] := True

```

■ a membership rule

For convenience we introduce the following function:

```

lambda[x, composite[n, RIGHT[x]]] /. n -> NATADD
VERTSECT[composite[SWAP, inverse[rotate[NATADD]]]]

```

A temporary membership rule is needed to make good use of this function.

```

member[pair[u, v], composite[w, IMAGE[cross[x, y]]]] // AssertTest
member[pair[u, v], composite[w, IMAGE[cross[x, y]]]] ==
  and[member[u, V], member[v, V], member[composite[y, u, inverse[x]], V],
  member[pair[composite[y, u, inverse[x]], v], w]]

member[pair[u_, v_], composite[w_, IMAGE[cross[x_, y_]]]] :=
  and[member[u, V], member[v, V], member[composite[y, u, inverse[x]], V],
  member[pair[composite[y, u, inverse[x]], v], w]]

```

■ an induction argument

The induction step will be essentially this argument:

```

SubstTest[implies, and[commute[w, y], commute[w, z]], commute[w, composite[y, z]],
  {w -> r[S], y -> r[SUCC], z -> composite[NATADD, RIGHT[x_]]}]

or[equal[composite[id[omega], inverse[IMAGE[inverse[NATADD]]],
  inverse[IMAGE[id[cart[V, singleton[x_]]]]], inverse[IMAGE[FIRST]], E],
  composite[SUCC, NATADD, RIGHT[x_], id[omega], S, id[omega]],
  not[equal[composite[id[omega], S, NATADD, RIGHT[x_]],
  composite[NATADD, RIGHT[x_], id[omega], S, id[omega]]]]] == True

```

We add this as a temporary rule

```

or[equal[composite[id[omega], inverse[IMAGE[inverse[NATADD]]],
  inverse[IMAGE[id[cart[V, singleton[x_]]]], inverse[IMAGE[FIRST]], E],
  composite[SUCC, NATADD, RIGHT[x_], id[omega], S, id[omega]]],
  not[equal[composite[id[omega], S, NATADD, RIGHT[x_]],
  composite[NATADD, RIGHT[x_], id[omega], S, id[omega]]]]] := True

```

The base case for the induction proof is not a problem:

```

member[0, image[inverse[VERTSECT[composite[SWAP, inverse[rotate[NATADD]]]],
  image[COMMUTE, singleton[composite[id[omega], S, id[omega]]]]],
True

```

Here is the induction step, rewritten:

```

implies[member[x, y], member[succ[x], y]] /.
y -> image[inverse[VERTSECT[composite[SWAP, inverse[rotate[NATADD]]]],
  image[COMMUTE, singleton[composite[id[omega], S, id[omega]]]]],
True

```

Our next step is to eliminate the variable `x` in the above statement:

```

Map[equal[V, #] &, SubstTest[class, x, implies[member[x, y], member[succ[x], y]],
  y -> image[inverse[VERTSECT[composite[SWAP, inverse[rotate[NATADD]]]],
  image[COMMUTE, singleton[composite[id[omega], S, id[omega]]]]]] // Reverse
subclass[image[SUCC, image[inverse[VERTSECT[composite[SWAP, inverse[rotate[NATADD]]]],
  fix[composite[inverse[IMAGE[cross[Id, composite[id[omega], S, id[omega]]]],
  IMAGE[cross[composite[id[omega], inverse[S], id[omega]], Id]]]]],
  image[inverse[VERTSECT[composite[SWAP, inverse[rotate[NATADD]]]],
  fix[composite[inverse[IMAGE[cross[Id, composite[id[omega], S, id[omega]]]],
  IMAGE[cross[composite[id[omega], inverse[S], id[omega]], Id]]]]]]] == True

```

We add this as a temporary rule:

```

subclass[image[SUCC, image[inverse[VERTSECT[composite[SWAP, inverse[rotate[NATADD]]]],
  fix[composite[inverse[IMAGE[cross[Id, composite[id[omega], S, id[omega]]]],
  IMAGE[cross[composite[id[omega], inverse[S], id[omega]], Id]]]]],
  image[inverse[VERTSECT[composite[SWAP, inverse[rotate[NATADD]]]],
  fix[composite[inverse[IMAGE[cross[Id, composite[id[omega], S, id[omega]]]],
  IMAGE[cross[composite[id[omega], inverse[S], id[omega]], Id]]]]]]] := True

```

The induction theorem can now be applied:

```

SubstTest[implies, and[member[0, w], subclass[image[SUCC, w], w]], subclass[omega, w],
  w -> image[inverse[VERTSECT[composite[SWAP, inverse[rotate[NATADD]]]],
  image[COMMUTE, singleton[composite[id[omega], S, id[omega]]]]],
subclass[omega, image[inverse[VERTSECT[composite[SWAP, inverse[rotate[NATADD]]]],
  fix[composite[inverse[IMAGE[cross[Id, composite[id[omega], S, id[omega]]]],
  IMAGE[cross[composite[id[omega], inverse[S], id[omega]], Id]]]]]]] == True
subclass[omega, image[inverse[VERTSECT[composite[SWAP, inverse[rotate[NATADD]]]],
  fix[composite[inverse[IMAGE[cross[Id, composite[id[omega], S, id[omega]]]],
  IMAGE[cross[composite[id[omega], inverse[S], id[omega]], Id]]]]]]] := True

```

The result looks better if one reintroduces a variable:

```

SubstTest[implies, and[member[x, y], subclass[y, z]], member[x, z],
  {y -> omega,
   z -> image[inverse[VERTSECT[composite[SWAP, inverse[rotate[NATADD]]]]],
    fix[composite[inverse[IMAGE[cross[Id, composite[id[omega], S, id[omega]]]]],
      IMAGE[cross[composite[id[omega], inverse[S], id[omega]], Id]]]]]} // MapNotNot
or[equal[composite[id[omega], S, NATADD, RIGHT[x]],
  composite[NATADD, RIGHT[x], id[omega], S, id[omega]], not[member[x, omega]]] == True

```

We add this as a temporary rule, but it will be replaced later with a better rule.

```

or[equal[composite[id[omega], S, NATADD, RIGHT[x_]], composite[NATADD,
  RIGHT[x_], id[omega], S, id[omega]], not[member[x_, omega]]] := True

```

■ final steps

The final steps are designed to remove the condition that x be a member of ω . The basic idea is that if this is not the case, then both sides of the equation reduce to 0 . We begin with a simplification rule:

```

subclass[omega, 0] // AssertTest

subclass[omega, 0] == False

subclass[omega, 0] := False

```

With this rule in place, we have:

```

equal[0, composite[NATADD, RIGHT[x]]]
not[member[x, omega]]

```

We now add a temporary rule:

```

SubstTest[implies, equal[y, z], equal[composite[u, y], composite[u, z]],
  {u -> r[S], y -> composite[NATADD, RIGHT[x]], z -> 0}]

or[member[x, omega],
  subclass[omega, complement[range[iterate[SUCC, singleton[x]]]]] == True

or[member[x_, omega],
  subclass[omega, complement[range[iterate[SUCC, singleton[x_]]]]] := True

```

The transitive property of equality is needed:

```

SubstTest[implies, and[equal[u, 0], equal[v, 0]], equal[u, v],
  {u -> composite[r[S], NATADD, RIGHT[x_]], v -> composite[NATADD, RIGHT[x_], r[S]]}]

or[equal[composite[id[omega], S, NATADD, RIGHT[x_]],
  composite[NATADD, RIGHT[x_], id[omega], S, id[omega]], member[x_, omega],
  not[subclass[omega, complement[range[iterate[SUCC, singleton[x_]]]]]]] == True

or[equal[composite[id[omega], S, NATADD, RIGHT[x_]],
  composite[NATADD, RIGHT[x_], id[omega], S, id[omega]], member[x_, omega],
  not[subclass[omega, complement[range[iterate[SUCC, singleton[x_]]]]]]] := True

```

We just need to do a bit of reasoning to complete the derivation

```

Map[not, SubstTest[and, implies[p1, p2],
  implies[not[p1], p3], implies[and[not[p1], p3], p2], not[p2],
  {p1 -> member[x, omega],
    p2 -> equal[composite[id[omega], S, NATADD, RIGHT[x]],
      composite[NATADD, RIGHT[x], id[omega], S, id[omega]]],
    p3 -> subclass[omega, complement[range[iterate[SUCC, singleton[x]]]]]]]]
equal[composite[id[omega], S, NATADD, RIGHT[x]],
  composite[NATADD, RIGHT[x], id[omega], S, id[omega]]] == True

```

It is not entirely clear how to orient this equation, but composites with functions behave better with respect to complementation when the function is on the right. For this reason, it seems desirable to orient the rewrite rule this way:

```

composite[NATADD, RIGHT[x_], id[omega], S, id[omega]] :=
  composite[id[omega], S, NATADD, RIGHT[x]]

```