

transitive law for final segments

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```
In[1]:= SetDirectory["1:"]; << goedel.10jul09a; << tools.m

:Package Title: goedel.10jul09a          2010 July 8 at 1:10 p.m.

It is now: 2010 Jul 11 at 15:9

Loading Simplification Rules

TOOLS.M                                Revised 2010 February 26

weightlimit = 40
```

summary

A theorem about transitivity of final segments is stated in this book:

```
In[3]:= "Egbert Harzheim, Ordered Sets, Advances in Mathematics, volume 7, Springer
        Science+Business Media, Inc., 2005. ISBN 0387-24219-8. QA171.48 .H37";
```

A class y is a **final segment** of a relation x if $\text{image}[x, y] = y$. That is, the class y is both invariant and subvariant under x . The class of final segments of a relation x is $\text{fix}[\text{IMAGE}[x]]$.

A variable-free formulation of this theorem is derived in this notebook.

introductory remarks

The function that takes a set x to the set $\text{fix}[\text{IMAGE}[x]]$ of final segments is:

```
In[2]:= VERTSECT[reify[x, fix[IMAGE[x]]]]
Out[2]= VERTSECT[fix[composite[inverse[SECOND], IMG]]]
```

The following relation is also needed:

```
In[4]:= class[pair[x, v], member[v, fix[IMAGE[x]]]]
Out[4]= fix[composite[inverse[SECOND], IMG]]
```

A simple membership rule for this relation can be formulated in terms of the **setpart** wrapper:

```
In[5]:= member[pair[setpart[x], setpart[v]], fix[composite[inverse[SECOND], IMG]]]
```

```
Out[5]= equal[image[setpart[x], setpart[v]], setpart[v]]
```

derivation

In this section, a transitive law for final segments is derived. The theorem is concerned with a final segment u of a restriction of a relation x to a final segment v of x .

Lemma.

```
In[6]:= or[equal[u, image[x, u]], not[equal[u, intersection[v, image[x, u]]],
          not[subclass[image[x, u], v]]] // NotNotTest
```

```
Out[6]= or[equal[u, image[x, u]],
          not[equal[u, intersection[v, image[x, u]]], not[subclass[image[x, u], v]]] = True
```

```
In[7]:= (% /. {x -> x_, u -> u_, v -> v_}) /. Equal -> SetDelayed
```

Lemma.

```
In[8]:= (Map[not, SubstTest[and, implies[p1, p3],
                          implies[and[p0, p1], p4], implies[and[p0, p3], p5], implies[and[p4, p5], p8],
                          not[implies[and[p0, p1], p8]], {p0 -> equal[t, intersection[u, v]],
                          p1 -> equal[u, intersection[v, image[x, intersection[u, v]]]}, p3 -> subclass[u, v],
                          p4 -> equal[u, intersection[v, image[x, t]]], p5 -> equal[t, u],
                          p8 -> equal[u, intersection[v, image[x, u]]]]] /. t -> intersection[u, v]) // Reverse
```

```
Out[8]= or[equal[u, intersection[v, image[x, u]]],
          not[equal[u, intersection[v, image[x, intersection[u, v]]]]] = True
```

```
In[9]:= (% /. {x -> x_, u -> u_, v -> v_}) /. Equal -> SetDelayed
```

The following is the transitive law for final segments, as stated by Harzheim, page 32, Theorem 8.10.

Theorem. If v is a final segment of x , and if u is a final segment of the two-sided restriction of x to v , then u is a final segment of x .

```
In[10]:= Map[not, SubstTest[and, implies[p1, p8], implies[p1, p3], implies[p3, p6],
                          implies[and[p2, p6], p7], implies[and[p7, p8], p9], not[implies[and[p1, p2], p9]],
                          {p1 -> equal[u, intersection[v, image[x, intersection[u, v]]]},
                          p2 -> equal[v, image[x, v]], p3 -> subclass[u, v],
                          p6 -> subclass[image[x, u], image[x, v]], p7 -> subclass[image[x, u], v],
                          p8 -> equal[u, intersection[v, image[x, u]]], p9 -> equal[u, image[x, u]]}] // Reverse
```

```
Out[10]= or[equal[u, image[x, u]], not[equal[u, intersection[v, image[x, intersection[u, v]]]],
          not[equal[v, image[x, v]]]] = True
```

```
In[11]:= or[equal[u_, image[x_, u_]],
           not[equal[u_, intersection[v_, image[x_, intersection[u_, v_]]]]],
           not[equal[v_, image[x_, v_]]]] := True
```

eliminating variables

Temporary Lemma.

```
In[12]:= member[u, fix[composite[IMAGE[composite[id[v], x]], IMAGE[id[v]]]] // AssertTest
```

```
Out[12]= member[u, fix[composite[IMAGE[composite[id[v], x]], IMAGE[id[v]]]] =
          and[equal[u, intersection[v, image[x, intersection[u, v]]]], member[u, V]]
```

```
In[13]:= member[u_, fix[composite[IMAGE[composite[id[v_], x_]], IMAGE[id[v_]]]] :=
          and[equal[u, intersection[v, image[x, intersection[u, v]]]], member[u, V]]
```

Lemma. Eliminating u .

```
In[14]:= Map[equal[V, #] &,
             SubstTest[class, u, implies[and[member[u, s], equal[v, image[x, v]]], member[u, t]],
             {s -> fix[IMAGE[restrict[x, v, v]]], t -> fix[IMAGE[x]]}]
```

```
Out[14]= or[not[equal[v, image[x, v]]], subclass[
           fix[composite[IMAGE[composite[id[v], x]], IMAGE[id[v]]], fix[IMAGE[x]]] = True
```

```
In[15]:= (% /. {x -> x_, v -> v_}) /. Equal -> SetDelayed
```

It helps to introduce an additional relation variable y and reformulate the result found so far as follows.

```
In[16]:= implies[and[equal[v, image[x, v]], equal[y, restrict[x, v, v]]],
            subclass[fix[IMAGE[y]], fix[IMAGE[x]]]
```

```
Out[16]= True
```

The following key observation requires introducing `setpart`.

```
In[17]:= member[pair[pair[setpart[x], setpart[v]], y],
               composite[CAP, cross[Id, composite[CART, DUP]]]
```

```
Out[17]= equal[y, composite[id[setpart[v]], setpart[x], id[setpart[v]]]
```

Lemma. Introducing `setpart`.

```
In[18]:= SubstTest[implies, and[equal[t, image[u, t]], equal[y, restrict[u, t, t]]],
            subclass[fix[IMAGE[y]], fix[IMAGE[u]]], {u -> setpart[x], t -> setpart[v]} // Reverse
```

```
Out[18]= or[not[equal[y, composite[id[setpart[v]], setpart[x], id[setpart[v]]]],
            not[equal[image[setpart[x], setpart[v]], setpart[v]]],
            subclass[fix[IMAGE[y]], fix[IMAGE[setpart[x]]]] = True
```

```
In[19]:= (% /. {v -> v_, x -> x_, y -> y_}) /. Equal -> SetDelayed
```

Observation.

```
In[20]:= member[pair[setpart[y], setpart[x]], composite[inverse[s], S, s]] /.
         s -> VERTSECT[fix[composite[inverse[SECOND], IMG]]]
```

```
Out[20]= subclass[fix[IMAGE[setpart[y]]], fix[IMAGE[setpart[x]]]]
```

One can now eliminate all variables from the transitive law for final segments.

Theorem. Variable-free statement of the transitive laws for final segments.

```
In[21]:= Map[empty[range[#]] &, Map[composite[complement[#], id[cart[V, V]]] &, SubstTest[class,
    pair[pair[x, v], y], implies[and[member[pair[setpart[x], setpart[v]], z],
    member[pair[pair[setpart[x], setpart[v]], setpart[y]], w]],
    member[pair[setpart[y], setpart[x]], composite[inverse[s], S, s]]],
    {s -> VERTSECT[fix[composite[inverse[SECOND], IMG]]],
    w -> composite[CAP, cross[Id, composite[CART, DUP]]],
    z -> fix[composite[inverse[SECOND], IMG]]}]]]
```

```
Out[21]= subclass[composite[fix[composite[inverse[SECOND], IMG]], CAP,
    id[composite[CART, DUP, fix[composite[inverse[SECOND], IMG]]], inverse[FIRST]],
    fix[composite[inverse[SECOND], IMG]]] == True
```

```
In[22]:= subclass[composite[fix[composite[inverse[SECOND], IMG]], CAP,
    id[composite[CART, DUP, fix[composite[inverse[SECOND], IMG]]], inverse[FIRST]],
    fix[composite[inverse[SECOND], IMG]]] := True
```