D. Surfaces (Kirby pictures, classification, and diffeomorphisms)

we will use handlebodies to classify closed surfaces First we have

ereru'se:

<u>examples:</u> 1) 5² call Zo 2) $T^2 = s' \times s'$ (a) call Σ_1 3) $\Sigma_n = \overline{\Sigma}_{n-1} + \overline{\Sigma}_1 \quad (\checkmark \checkmark)$ 4) $P^2 = \frac{5^2}{\pi}$ call N_i ident untipodes 5) $N_n = N_{n-1} \# N_1$ The:any closed connected surface I is diffeomorphic to In or NA for some n we prove this by showing I has a handlebody decomp. that agrees with one for En or Nn how to "see" handle decomps? Kirby pictures! <u>note</u>: for surfaces F_0, F_1 , we have $F_0 \cong F_1 \Leftrightarrow \widehat{F_0} \cong \widehat{F_1}$

so given a connected surface F we can hid a handle decomposition
with one O-handle and one 2-handle
and we can understand F's diffeomorphism type by considering

$$F-(2-handle)=(0-handle) \cup k (1-handles)$$

to understand this, just need to know how 1-handles are
attached to $\partial(0-handle) = 5'$ called jointed
is heep track of framed so's in 5' matched circle
is heep track of framed so's in 5' matched circle
in S'-ipt3 \cong R
preduced studying
2-mitds to prefures
in S'-ipt3 \cong R
so this is a protive of T^2
2) show if F₀ has protive T^2
and
 F_1 " " $Track$ Men
 $F_0 + F_1$ " " $Track$ Men
 $Track$ Men
 $Track Men they point " ort" " ort"$

3) $P^2 = \square = \square \square \square$ with pt on 2 identified with "antipode"

note union of purple is D² glued to rest along 5', 1e. a 2-handle



So we now have pictures of all En and Nn We now show any F has a picture that agrees with one of these If the picture for F has no I-handles, then F=S² now suppose F has k>O I-handles consider one of them: ho' that is attached first <u>Case 1</u>: ho' not oriented

any handle h' attached after ho can be "slid" over ho that is recall we get the some manifold it we change the attaching map of h' by an iso topy

one toot of h

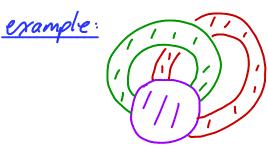
so a "handle slide" changes the picture by

exercise: Show handle slide rule is
a) can push a point into tip/tail of another
handle h's and it comes out the tip/tail
of the other "bot" of h's
b) if h's is oriented the arrow of the
slid point stays same, otherwise it flips
so notice only foot" in rule can be slid out of I
(say to right)
and any point to left of I can be slid to right
of I by 2 handle slides
so
$$F = \underbrace{rect}_{I} = f' = F' has there I - handles$$

(ase 2: h's oriented
 $F \equiv P^* \# F' = F' has there I - handles$
(ase 2: h's oriented
 $F \equiv P^* = S' = connected$
but $\Im F^\circ = S' = connected$
so must be h', with one that in I and one foot art
if h's oriented, then can slide to get
 $f = h' = connected$
if h's oriented, then consider interval J

 J_1 J_3 J_2

note: any foot in J, can be slid over h' to get out of J $\cdots \quad J_2 \qquad \cdots \qquad J_4 \qquad \cdots \qquad$ then over h's to get out of J similarly any foot to left of J can be shid to right of J : as in case 1 F = T² # F' with F' having fewer 1-handles So by induction on $k F = (\#_k T^2) \# (\#_p P^2)$ $\underline{exercise}: T^2 \# P^2 \cong P^2 \# P^2 \# P^2$ so we are done with proof of theorem! Subtle Point: Given a handlebody F and F'obtained from F by isotoping the attaching maps, ls F = F'?NO! but they are diffeomorphic! there is a difference between "is the same as " and "diffeomorphic to"

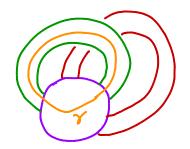


isotope attaching region of red as follows

so it comes back to where it started

we get a family of surfaces Ft te [0.1] with F = F = F, and diffeomorphisms really equal! $\phi_t: F_o \to F_t$

<u>exercise</u>: so f.: F→F is a diffeomorphism of F! 1) Show f. is isotopic to a "Dehn twist" about 8



2) Show any diffeomorphism of an oriented surface is obtained by handle slides (is it true for non orientable?)

E. <u>h-cobordism theorem</u> the goal of this section is to prove $\frac{Th^{m}(h-cobordism theorem)}{If W is an n-dimensional cobordism s.t.$ $i) <math>\pi_{i}(W) = \{e\} = \pi_{i}(\partial_{\pm}W)$ $2) H_{i}(W_{i}\partial_{-}W_{j}Z) = 0$ $3 n \ge 6$ Then $W \cong \partial_{-}W \times [o,1]$ note: hypothesis equivalent to $\partial_{\pm}V \longrightarrow bomotryp$ equivalence and $\pi_{i}(W) = \{e\}$