

The Minkowski Functional

Definition

A subset A of a TVS X is absorbing if

$$\forall x \in X \exists \delta_x > 0 \text{ s.t.}$$

$$0 < t < \delta_x \Rightarrow tx \in A.$$

Remark

If A is absorbing then by considering the point $x=0$ in the preceding definition we see that we must have $0 \in A$.

Definition

The Minkowski functional or gauge of a set A is

$$\mu_A(x) = \inf \{ t > 0 : x \in tA \}$$

Thus $\mu_A(x)$ measures how much we must expand A in order to contain x . For an arbitrary set A we can have $\mu_A(x) = \infty$ for some x (i.e., $x \notin tA$ for any $t > 0$), but if A is absorbing then $\mu_A(x) < \infty$ for all $x \in X$, and thus μ_A is a (nonlinear) functional on X .

We illustrate the Minkowski function by evaluating it on an open strip determined by a seminorm ρ .

Theorem

If ρ is a seminorm on a vector space X , then the "unit strip"

$$B = B_{\rho}^{\rho}(0) = \{x \in X : \rho(x) < 1\}$$

is convex, balanced, & absorbing, and its Minkowski functional is $\mu_B = \rho$.

Proof:

The fact that B is convex follows from the Triangle Inequality for ρ .

If $x \in B$ & $|c| \leq 1$ then we have

$$\rho(cx) = |c| \rho(x) \leq \rho(x) < 1$$

so $cx \in B$. Hence B is balanced.

Suppose that $x \in X$ and $t > \rho(x)$. Then

$$\rho(t^{-1}x) = t^{-1}\rho(x) < 1 \text{ so } t^{-1}x \in B \text{ and hence } x \in tB.$$

Therefore B is absorbing, and this also shows that

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$\mu_B(x) \leq t$. Consequently $\mu_B(x) \leq \rho(x)$.

Conversely, if $0 < t \leq \rho(x)$ then $\rho(t^{-1}x) \geq 1$ so $t^{-1}x \in B$, and therefore $\mu_B(x) \geq \rho(x)$. \square

Theorem

Let A be a convex, absorbing subset of a vector space X . Then:

(a) $0 \leq \mu_A(x) < \infty$

(b) $\mu_A(x+y) \leq \mu_A(x) + \mu_A(y)$

(c) $\mu_A(cx) = c\mu(x)$ for all $c \geq 0$

(d) If A is balanced then μ_A is a seminorm on X .

(e) If we set $B = \{\mu_A < 1\}$ and $C = \{\mu_A \leq 1\}$

then $B \subseteq A \subseteq C$ and $\mu_B = \mu_A = \mu_C$.

Proof:

(a) Follows from the definition of absorbing.

(b) Fix $x, y \in X$, and any $t > \mu_A(x)$, $s > \mu_A(y)$.

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Then $x \in tA$ & $y \in sA$, so $\frac{x}{t}, \frac{y}{s} \in A$. As A is convex, the line segment between these points is contained in A . In particular,

$$\frac{x+y}{s+t} = \frac{t}{s+t} \cdot \frac{x}{t} + \frac{s}{s+t} \cdot \frac{y}{s} \in A$$

so $\mu_A(x+y) \leq s+t$. Taking the inf over all such s, t , we obtain $\mu_A(x+y) \leq \mu_A(x) + \mu_A(y)$.

(c) Follows from scaling & definition of the Minkowski functional.

(d) Suppose A is balanced, $x \in X$, & $c \in \mathbb{F}$.

Write $c = \alpha |c|$ where $\alpha \in \mathbb{C}$, $|\alpha| = 1$. Then

$$\mu_A(cx) = \mu_A(|c| \alpha x)$$

$$= |c| \mu_A(\alpha x)$$

$$= |c| \inf \{ t > 0 : \alpha x \in tA \}$$

$$= |c| \inf \{ t > 0 : x \in tA \} \text{ by balancing}$$

$$= |c| \mu_A(x).$$

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Hence μ_A is a seminorm.

(c) IF $x \in B$ then $\mu_A(x) < 1$ so $x \in tA$ for some $t < 1$. Hence $t^{-1}x \in A$. But $t^{-1} > 1$, so x is on

the line segment joining 0 & $t^{-1}x$. As A is convex, it follows that $x \in A$.

IF $x \in A$ then by definition ~~we~~ we have $\mu_A(x) \leq 1$ so $x \in C$.

Thus $B \subseteq A \subseteq C$, which implies ~~we have~~

$\mu_B \leq \mu_A \leq \mu_C$. Fix any $x \in X$, and choose scalars $\mu_C(x) < s < t$. Then $\mu_C(\frac{x}{s}) < 1$ so

$\frac{x}{s} \in C$. By definition, this implies $\mu_A(\frac{x}{s}) \leq 1$.

But then $\mu_A(\frac{x}{t}) < \mu_A(\frac{x}{s}) \leq 1$, so $\frac{x}{t} \in B$ by

definition of B . Hence $\mu_B(\frac{x}{t}) \leq 1$, so $\mu_B(x) \leq t$.

As $t > \mu_C(x)$ is arbitrary, we conclude $\mu_B(x) \leq \mu_C(x)$. ▮

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Theorem

Let \mathcal{B} be a convex balanced local base in a TVS.

(In particular, μ_V is a seminorm on X for each $V \in \mathcal{B}$.)

Then:

$$(a) \quad V = B_1^{\mu_V}(0) = \{x \in X : \mu_V(x) < 1\}$$

(b) $\{\mu_V\}_{V \in \mathcal{B}}$ is a separating family of continuous seminorms on X .

Note: Separating is the Hausdorff property:

$$\mu_V(x) = 0 \quad \forall V \in \mathcal{B} \iff x = 0.$$

Proof:

(a) If $x \in V$ then since V is open & scalar multiplication is continuous, we have $tx \in V$

for all scalars t with $|t|$ small enough. In

particular, $tx \in V$ for some ~~small~~ $t > 1$, so

$x \in t^{-1}V$ with $t^{-1} < 1$. By definition of μ_V we

therefore have $\mu_V(x) \leq t^{-1} < 1$.

Conversely, if $x \notin V$ then, since V is balanced,

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$x \in V$ can only happen if $t \geq 1$. Hence $\mu_V(x) \geq 1$.

(b) We know each μ_V is a seminorm. Note

that $\mu_V: X \rightarrow [0, \infty)$. If $r > 0$ then

$$\mu_V^{-1}[0, r) = \{x \in X : \mu_V(x) < r\} = rV,$$

which is open.

Consider an open interval $(t-r, t+r) \subseteq [0, \infty)$.

We have

$$U := \mu_V^{-1}(t-r, t+r) = \{x \in X : t-r < \mu_V(x) < t+r\}.$$

Fix any particular x in \mathbb{Q} set. Suppose

$y \in cV + x$ (which is an open set). Then

$$\begin{aligned} |\mu_V(x) - \mu_V(y)| &\leq \mu_V(x-y) && \text{Reverse triangle} \\ &< c && \text{since } y-x \in cV \end{aligned}$$

Hence if we choose c small enough then we will

have $y \in U$. Thus $cV + x$, which is an open

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neighborhood of x , is contained in U . We can do this for each $x \in U$, so U is open.

Consequently μ_V is continuous.

If $\mu_V(x) = 0$ for every $V \in \mathcal{B}$ we have $x \in V$ for every $V \in \mathcal{B}$. Since \mathcal{B} is a local base for the topology on X , which is Hausdorff, this ~~implies~~ implies that $x = 0$ (why?).

Hence $\{\mu_V\}_{V \in \mathcal{B}}$ is separating. \blacksquare

Theorem

Suppose $\{\rho_\alpha\}_{\alpha \in J}$ is a family of separating seminorms on a vector space X . For $n \in \mathbb{N}$ define

$$V_\alpha(n) = \{x \in X : \rho_\alpha(x) < \frac{1}{n}\} = B_{1/n}^\alpha(0)$$

Let \mathcal{B} be the collection of all finite intersections of the sets $V_\alpha(n)$. Then

(a) \mathcal{B} is a convex balanced local base for a topology T on X ,

(b) X is locally convex ^{TVS} w.r.t. T ,

(c) ρ_α is continuous $\forall \alpha \in J$,

(d) $E \subseteq X$ is bounded $\iff \sup_{x \in E} \rho_\alpha(x) < \infty \forall \alpha \in J$.

Proof:

(a) Let \mathcal{B}_x be the collection of all translates of elements in \mathcal{B} , and let T be the set of all possible unions of elements of \mathcal{B}_x . Then T is a topology, \mathcal{B}_x is a

base for T , and \mathcal{B} is a local base for T .

Further, each element of \mathcal{B} is convex & balanced since it is an open strip determined by a seminorm.

(b) Since each element of \mathcal{B} is convex, the locally convex requirement is satisfied. We need to show that X is a TVS w.r.t. T .

Suppose $x \neq 0$. Then since our family of seminorms is separating, we have $p_\alpha(x) > 0$ for some α .

Hence $x \notin V_\alpha(n)$ for some n . As $V_\alpha(n)$ is an open neighborhood of 0 , it follows that x is not in the closure of $\{0\}$. This is true for all $x \neq 0$, so the closure of $\{0\}$ is $\{0\}$. That is, $\{0\}$ is closed. By construction the topology T is translation-invariant, so $\{x\}$ is closed $\forall x \in X$

(this gives us Rudin's Hausdorffness requirement for a TVS).

Let U be an open neighborhood of 0 . Then U contains a base element from \mathcal{B} , say

$$\bigcap_{k=1}^N V_{\alpha_k}(n_k) \subseteq U.$$

Set

$$V = \bigcap_{k=1}^N V_{\alpha_k}(2n_k).$$

Then given $x, y \in V$ we have $\rho_{\alpha_k}(x) < \frac{1}{2n_k}$ and

$\rho_{\alpha_k}(y) < \frac{1}{2n_k}$, so $\rho_{\alpha_k}(x+y) < \frac{1}{n_k}$. Hence

$x+y \in U$, so $V+V \subseteq U$. Therefore

$$(0,0) \in V \times V \subseteq \tau^{-1}(U)$$

This shows that vector addition is continuous.

A similar argument shows scalar multiplication is continuous (see Rudin, p. 28).

(c) Since $V_{\alpha}(n) = B_{\gamma_n}^{\alpha}(0)$ is open, ρ_{α} is continuous at 0, and the Reverse Triangle inequality can be used to show ρ_{α} is continuous at each x .

(d) Suppose $E \subseteq X$ is bounded. Since $V_{\alpha}(1)$ is an open neighborhood of 0, we must have $E \subseteq t V_{\alpha}(1)$ for some $t > 0$. But then for any $x \in E$ we have $\frac{x}{t} \in V_{\alpha}(1)$, so $\rho_{\alpha}(\frac{x}{t}) < 1$ and therefore $\rho_{\alpha}(x) < t$. Thus $\sup_{x \in E} \rho_{\alpha}(x) < \infty$.

Conversely, suppose each seminorm ρ_{α} is bounded on E . Let U be any open neighborhood of 0. Then as before, $\exists \bigcap_{k=1}^N V_{\alpha_k}(n_k) \subseteq U$. Let

$$M_k = \sup_{x \in E} \rho_{\alpha_k}(x). \quad \text{If } t > n_k M_k \text{ for } k=1, \dots, N$$

Then for any $x \in E$ we have

$$\rho_{\alpha_k}(\frac{x}{t}) < \frac{M_k}{t} < \frac{1}{n_k},$$

so $\frac{x}{t} \in U$. Thus $E \subseteq tU$, so E is

bounded. \square