

REDUNDANCY AND LOCALIZED FRAMES

Christopher Heil
Georgia Tech

heil@math.gatech.edu
<http://www.math.gatech.edu/~heil>

COAUTHORS

Radu Balan, Siemens Research Corporation

Pete Casazza, University of Missouri

Zeph Landau, City College of New York

and

**Karlheinz Gröchenig, Institute of Biomathematics and
Biometry, Munich**

Deguang Han, University of Central Florida

Gitta Kutyniok, University of Giessen

Jayakumar Ramanathan, Eastern Michigan University / MITRE

Pankaj Topiwala, FastVDO LLC / MITRE

David Walnut, George Mason University

OVERTURE: REDUNDANCY

What is redundancy?

How can we quantify redundancy?

Which elements may be removed?

What is the effect of removing/losing elements?

How can we recognize that a system is the union of finitely many nonredundant systems?

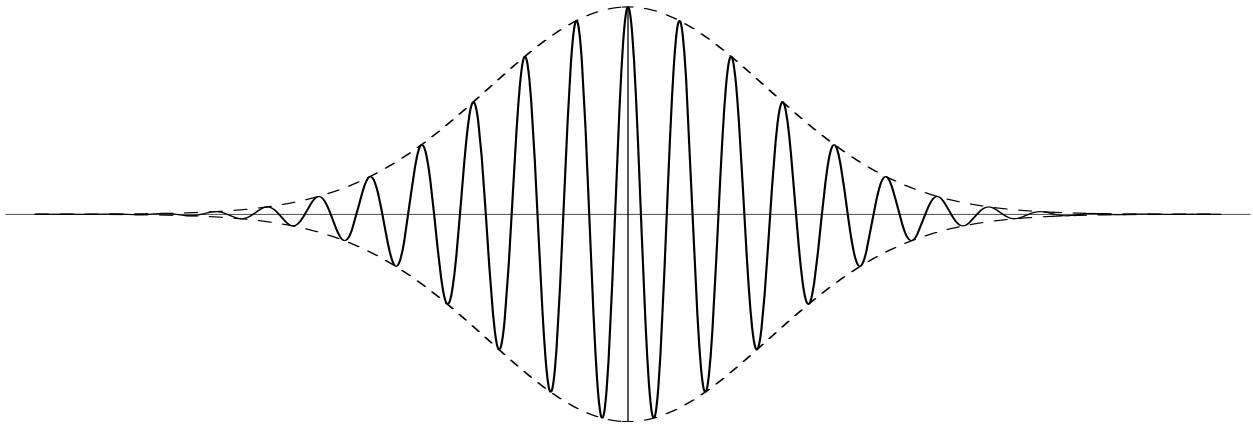
PRELUDE: GABOR SYSTEMS AND FRAMES

Goal

Music-like bases or frames for $L^2(\mathbb{R})$.



Model of a note at time α and frequency β :



$$e^{2\pi i \beta x} g(x - \alpha) = M_{\beta} T_{\alpha} g(x)$$

Gabor System (Weyl–Heisenberg system, coherent states)

$$\begin{aligned}\mathcal{G}(g, \Lambda) &= \{M_\beta T_\alpha g\}_{(\alpha, \beta) \in \Lambda} \\ &= \{e^{2\pi i \beta x} g(x - \alpha)\}_{(\alpha, \beta) \in \Lambda} \\ &= \{\pi(\alpha, \beta, 1)g\}_{(\alpha, \beta) \in \Lambda}\end{aligned}$$

where π is the Schrödinger representation of the Heisenberg group on \mathbb{R}^n .

“Music”

$$f = \sum_{(\alpha, \beta) \in \Lambda} c_{\alpha, \beta}(f) M_\beta T_\alpha g$$



Desired Properties: Stability

(a) **Expansions** $f = \sum_{(\alpha,\beta) \in \Lambda} c_{\alpha,\beta}(f) M_{\beta} T_{\alpha} g$

should converge unconditionally in the norm of an appropriate Banach space X .

(b) More than just $c_{\alpha,\beta} \in X^*$, given an associated sequence space X_d ,

$$\begin{aligned} T : X &\rightarrow X_d \\ f &\mapsto \{c_{\alpha,\beta}(f)\}_{(\alpha,\beta) \in \Lambda} \end{aligned}$$

should be continuously invertible on its range. In particular,

$$\|f\|_X \cong \|\{c_{\alpha,\beta}(f)\}\|_{X_d}$$

(c) **Simultaneous applicability:** Both properties above should hold simultaneously in an entire *family* of Banach spaces (e.g., L^p , Hölder, Sobolev, Besov, modulation spaces).

Uniqueness??

Frames in Hilbert Spaces

$\{f_n\}_{n \in \mathbb{N}}$ is a frame for a Hilbert space H if there exist $A, B > 0$ such that

$$\forall f \in H, \quad A \|f\|^2 \leq \sum_{n=1}^{\infty} |\langle f, f_n \rangle|^2 \leq B \|f\|^2$$

Finite dimensions: Frames = spanning sets

Expansions follow for free:

Analysis operator:

$$Tf = \{\langle f, f_n \rangle\}_{n \in \mathbb{N}} \quad \text{maps } H \rightarrow \ell^2$$

Frame operator:

$$Sf = T^*Tf = \sum_{n=1}^{\infty} \langle f, f_n \rangle f_n \quad \text{is positive definite}$$

Expansions:

$$f = SS^{-1}f = \sum_{n=1}^{\infty} \langle S^{-1}f, f_n \rangle f_n = \sum_{n=1}^{\infty} \langle f, S^{-1}f_n \rangle f_n$$

Duality: $\{\tilde{f}_n\}_{n \in \mathbb{N}} = \{S^{-1}f_n\}_{n \in \mathbb{N}}$ is the dual frame, and

$$\forall f \in H, \quad \frac{1}{B} \|f\|^2 \leq \sum_{n=1}^{\infty} |\langle f, \tilde{f}_n \rangle|^2 \leq \frac{1}{A} \|f\|^2$$

Remark: Frame + basis \iff Riesz basis

(image of ONB under a continuous, invertible map)

Examples

- (a) $\mathcal{G}(\chi_{[0,1]}, \mathbf{Z} \times \mathbf{Z}) = \{e^{2\pi i n x} \chi_{[k, k+1)}(x)\}_{k, n \in \mathbf{Z}}$ is an ONB for $L^2(\mathbf{R})$.
- (b) Gabor's original system $\mathcal{G}(e^{-x^2}, \mathbf{Z} \times \mathbf{Z})$ is overcomplete but not a basis or frame.
- (c) $\mathcal{G}(e^{-x^2}, \mathbf{Z} \times \mathbf{Z} \setminus (0, 0))$ is complete and minimal but not a basis or frame.
- (d) $\mathcal{G}(e^{-x^2}, \alpha\mathbf{Z} \times \beta\mathbf{Z})$ is a frame (overcomplete) exactly when $0 < \alpha\beta < 1$ (via Bargmann transform/analyticity).
- (e) If $\text{supp}(g) \subset [0, \frac{1}{\beta}]$ and

$$0 < C_1 \leq \sum_{k \in \mathbf{Z}} |g(x - k\alpha)|^2 \leq C_2 < \infty$$

then $\mathcal{G}(g, \alpha\mathbf{Z} \times \beta\mathbf{Z})$ is a frame for $L^2(\mathbf{R})$. For this case:

$\alpha\beta > 1$: not possible

$\alpha\beta = 1$: basis, but g is discontinuous

$\alpha\beta < 1$: not a basis, but g can be smooth

Remark

If g is nice, then frame expansions extend to the entire family of modulation spaces.

Balian–Low Theorems $\mathcal{G}(g, \alpha\mathbf{Z} \times \beta\mathbf{Z}) = \{e^{2\pi i\beta n x} g(x - \alpha k)\}_{k, n \in \mathbf{Z}}$

- (a) **Classical BLT [Balian/Low]:** If $\mathcal{G}(g, \alpha\mathbf{Z} \times \beta\mathbf{Z})$ is a Riesz basis for $L^2(\mathbf{R})$, then

$$\left(\int_{-\infty}^{\infty} |tg(t)|^2 dt \right) \left(\int_{-\infty}^{\infty} |\omega \hat{g}(\omega)|^2 d\omega \right) = \infty.$$

- (b) **Amalgam BLT [H.]:** If $\mathcal{G}(g, \alpha\mathbf{Z} \times \beta\mathbf{Z})$ is a Riesz basis for $L^2(\mathbf{R})$, then $g, \hat{g} \notin W(C_0, \ell^1)$, where

$$W(C_0, \ell^1) = \left\{ \text{continuous } f : \sum_{k=-\infty}^{\infty} \|f \cdot \chi_{[k, k+1]}\|_{\infty} < \infty \right\}.$$

Open Questions

- (a) **Classical BLT for general lattices in higher dimensions**
(yes if symplectic: Gröchenig/Han/H./Kutyniok,
Benedetto/Czaja/Ya)
- (b) **Amalgam BLT for general lattices in all dimensions.**
- (c) **BLT for non-lattices in all dimensions.**
- (d) **BLT for bases that are not Riesz bases.**

Nyquist Density Theorem for $\mathcal{G}(g, \alpha\mathbf{Z} \times \beta\mathbf{Z})$

- (a) **Frame** $\implies 0 < \alpha\beta \leq 1$.
- (b) **Riesz basis** $\implies \alpha\beta = 1$.
- (c) $\alpha\beta > 1 \implies$ **incomplete**.

Techniques

Baggett, Rieffel: von Neumann algebra generated by T_α, M_β

Daubechies: Zak Transform

Janssen: Wexler–Raz relations

All these tools are useless for general $\mathcal{G}(g, \Lambda)$.

Beurling Densities of Λ

$$D^-(\Lambda) = \liminf_{r \rightarrow \infty} \inf_{z \in \mathbf{R}^2} \frac{\#(\Lambda \cap Q_r(z))}{r^2},$$

$$D^+(\Lambda) = \limsup_{r \rightarrow \infty} \sup_{z \in \mathbf{R}^2} \frac{\#(\Lambda \cap Q_r(z))}{r^2},$$

where $Q_r(z)$ is the square centered at z with side lengths r .

Example: $D^-(\alpha\mathbf{Z} \times \beta\mathbf{Z}) = D^+(\alpha\mathbf{Z} \times \beta\mathbf{Z}) = \frac{1}{\alpha\beta}$

Nyquist Density for $\mathcal{G}(g, \Lambda)$ [Ramanathan/Steger]

(a) **Frame** $\implies 1 \leq D^-(\Lambda) \leq D^+(\Lambda) < \infty$.

(b) **Riesz basis** $\implies D^-(\Lambda) = D^+(\Lambda) = 1$.

Remarks

- Irregular Gabor systems can be complete (but not frames) even if they are very sparse [Walnut/H.]
- \exists (very) irregular Gabor ONB [Y. Wang]

NOCTURNE: REDUNDANCY

Definitions/Facts

- (a) A frame is *redundant* or *overcomplete* if it is not a basis.
- (b) If a frame is a basis then it is a *Riesz basis* (the image of an ONB under a continuous invertible map).
- (c) A *near-Riesz basis* is a Riesz basis plus finitely many elements.
- (d) A frame $\mathcal{F} = \{f_n\}_{n \in \mathbb{N}}$ is *bounded* if $\inf \|f_n\| > 0$.

Q. Does every bounded frame contain a basis?

A. No [Casazza/Christensen, Seip].

Theorem [Duffin/Schaeffer]

If \mathcal{F} is an overcomplete frame then at least finitely many elements can be removed yet still leave a frame.

Q. Aside from near-Riesz bases, can infinitely many elements be removed yet leave a frame?

A. No [Balan/Casazza/H./Landau, with characterization].

Examples

- (a) $\mathcal{G}(\chi_{[0,1]}, \mathbf{Z} \times \mathbf{Z})$ is an ONB.
- (b) $\mathcal{G}(\chi_{[0,1]}, \frac{1}{N}\mathbf{Z} \times \mathbf{Z})$ is the union of N ONBs.
- (c) $\mathcal{G}(e^{-x^2}, \frac{1}{N}\mathbf{Z} \times \mathbf{Z})$ is not the union of N ONBs, but is the union of N minimal systems plus N more elements.

Q. Given a frame, how can you recognize that it is a union of finitely many ON sequences? Or finitely many Riesz sequences (Riesz bases for their closed spans)?

Q. Is frame (c) above a union of finitely many Riesz sequences?

A. Yes [B./C./H./L.]

Feichtinger Conjecture

Every bounded frame is a union of finitely many Riesz sequences.

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Kadison–Singer Conjecture (Paving Conjecture) [1959]

$\forall \varepsilon > 0, \exists M$ such that $\forall n, \forall n \times n$ matrices S having zero diagonal, \exists partition $\{\sigma_j\}_{j=1}^M$ of $\{1, \dots, n\}$ such that

$$\|P_{\sigma_j} S P_{\sigma_j}\| \leq \varepsilon \|S\|, \quad j = 1, \dots, M,$$

where P_I is the orthogonal projection onto $\text{span}\{e_i\}_{i \in I}$.

Conjectured Generalization of Bourgain–Tzafriri R.I.T.

$\forall B, \exists M, A$ such that $\forall n \times n$ matrices T such that $\|Te_i\| = 1$ and $\|T\| \leq \sqrt{B}$, \exists partition $\{I_j\}_{j=1}^M$ of $\{1, \dots, n\}$ such that $\forall \{a_i\}_{i \in I_j}$,

$$\left\| \sum_{i \in I_j} a_i T e_i \right\|^2 \geq A \sum_{i \in I_j} |a_i|^2, \quad j = 1, \dots, M.$$

Theorem [Casazza/Christensen/Lindner/Vershynin]

Kadison–Singer \implies Feichtinger \iff Bourgain–Tzafriri

Redundancy is not a “local” issue

A Gabor frame $\mathcal{G}(g, \frac{1}{N}\mathbf{Z} \times \mathbf{Z})$ seems to be “ N times overcomplete.” Yet, every finite subset is (probably) independent.

The following conjecture is known to hold for many special cases, but is open in the generality stated.

Conjecture (H./Ramanathan/Topiwala)

If $g \in L^2(\mathbf{R})$, $g \neq 0$, and $\Lambda = \{(\alpha_k, \beta_k)\}_{k=1}^N$ are distinct points in \mathbf{R}^2 , then $\mathcal{G}(g, \Lambda) = \{e^{2\pi i \beta_k x} g(x - \alpha_k)\}_{k=1}^N$ is linearly independent.

Open HRT Subconjectures

If $g \in L^2(\mathbf{R})$ is continuous and nonzero then the following sets are independent:

- (a) $\{g(x), g(x - 1), e^{2\pi i x} g(x), e^{2\pi i \sqrt{2} x} g(x - \sqrt{2})\}$
- (b) $\{g(x), g(x - 1), g(x - \pi), e^{2\pi i x} g(x)\}$

Remarks

- (a) This is the “Zero Divisor Conjecture” for the case of the Heisenberg group.
- (b) The analogous conjecture for the affine group is false. Moreover, the construction of wavelet ONBs depends crucially on linear *dependence*.

Dual Frames

The dual frame of

$$\mathcal{G}(g, \alpha\mathbf{Z} \times \beta\mathbf{Z}) = \{M_{\beta n}T_{\alpha k}g\}_{k,n \in \mathbf{Z}}$$

has the form

$$\mathcal{G}(\tilde{g}, \alpha\mathbf{Z} \times \beta\mathbf{Z}) = \{M_{\beta n}T_{\alpha k}\tilde{g}\}_{k,n \in \mathbf{Z}}$$

because

$$SM_{\beta n}T_{\alpha k} = M_{\beta n}T_{\alpha k}S$$

Theorem [Gröchenig/Leinert, via C^* algebras]

$$g \in M^1 \implies \tilde{g} \in M^1$$

Fundamental Problem [Open until B./C./H./L.]

If Λ is not a lattice, what does the dual frame of

$$\mathcal{G}(g, \Lambda) = \{M_{\beta}T_{\alpha}g\}_{(\alpha,\beta) \in \Lambda}$$

look like??

WALTZ: LOCALIZED FRAMES

Definition: Localized Frames

Given $\mathcal{F} = \{f_i\}_{i \in I}$, $\mathcal{E} = \{e_j\}_{j \in G}$, and $a: I \rightarrow G$.

(a) $(\mathcal{F}, a, \mathcal{E})$ is ℓ^p -localized if $\exists r = (r_k)_{k \in G} \in \ell^p(G)$ such that

$$|\langle f_i, e_j \rangle| \leq r_{a(i)-j}$$

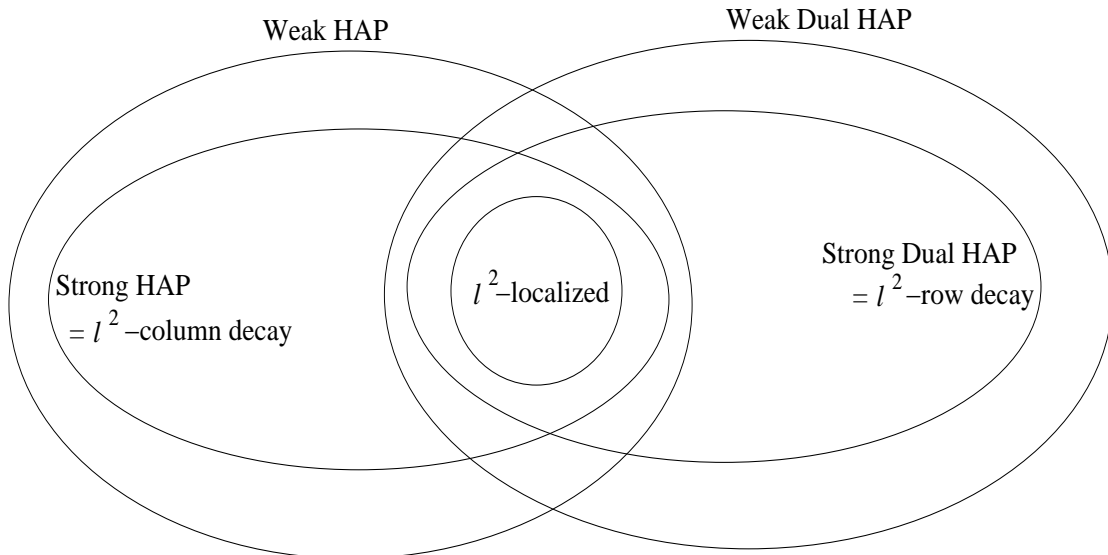
(b) $(\mathcal{F}, a, \mathcal{E})$ has ℓ^p -column decay if $\forall \varepsilon > 0$, $\exists N_\varepsilon > 0$ such that

$$\forall j \in G, \quad \sum_{i \in I \setminus I_{N_\varepsilon}(j)} |\langle f_i, e_j \rangle|^p < \varepsilon$$

(c) $(\mathcal{F}, a, \mathcal{E})$ has ℓ^p -row decay if $\forall \varepsilon > 0$, $\exists N_\varepsilon > 0$ such that

$$\forall i \in I, \quad \sum_{j \in G \setminus S_{N_\varepsilon}(a(i))} |\langle f_i, e_j \rangle|^p < \varepsilon$$

Relations among localization and HAP properties



Theorem [B./C./H./L.]

If

- (a) $\mathcal{F} = \{f_i\}_{i \in I}$ and $\mathcal{E} = \{e_j\}_{j \in G}$ are frame sequences,
- (b) $D^+(I) < \infty$, and
- (c) $(\mathcal{F}, a, \mathcal{E})$ has both ℓ^2 -column and row decay,

then

$$D(I) \cdot \mathcal{M}_{\mathcal{E}}(\mathcal{F}) = \mathcal{M}_{\mathcal{F}}(\mathcal{E})$$

where

$$\mathcal{M}_{\mathcal{E}}(\mathcal{F}) = \left\{ \begin{array}{l} \text{Limits of averages of diagonal} \\ \text{elements of } [\langle P_{\mathcal{E}} f_i, \tilde{f}_j \rangle]_{i,j \in I} \end{array} \right.$$

and

$$\mathcal{M}_{\mathcal{F}}(\mathcal{E}) = \left\{ \begin{array}{l} \text{Limits of averages of diagonal} \\ \text{elements of } [\langle P_{\mathcal{F}} e_i, \tilde{e}_j \rangle]_{i,j \in G} \end{array} \right.$$

Remark

“Limits” include Beurling-type upper and lower limits as well as ultrafilter limits.

Example

If \mathcal{F} is a frame and \mathcal{E} is a Riesz basis then $\mathcal{M}_{\mathcal{F}}(\mathcal{E}) = M(\mathcal{E}) = 1$.

WALTZ: IMPLICATIONS FOR GABOR FRAMES

Approximate Definition

$$M^1 \approx \{f \in L^2 : f, \hat{f} \in L^1\}$$

Theorem

(a) **If $g \in L^2$ and $\varphi \in M^1$ then**

$$(\mathcal{G}(g, \Lambda), a, \mathcal{G}(\varphi, \alpha\mathbf{Z} \times \beta\mathbf{Z}))$$

is ℓ^2 -localized.

(b) **If $g \in M^1$ and $\varphi \in M^1$ then**

$$(\mathcal{G}(g, \Lambda), a, \mathcal{G}(\varphi, \alpha\mathbf{Z} \times \beta\mathbf{Z}))$$

is ℓ^1 -localized.

Here $a(\lambda) =$ closest point in $\alpha\mathbf{Z} \times \beta\mathbf{Z}$

Application 1: Necessary Density Conditions

Let $\mathcal{G}(g, \Lambda) = \{M_\beta T_\alpha g\}_{(\alpha, \beta) \in \Lambda}$ be Gabor frame for $L^2(\mathbf{R})$. Then:

(a) $D^\pm(\Lambda) = \frac{1}{\mathcal{M}^\mp(\mathcal{G}(g, \Lambda))}$.

(b) $D^-(\Lambda) \geq 1$.

(c) **Riesz basis** $\implies D^-(\Lambda) = D^+(\Lambda) = 1$.

Application 2: Relations between Density and Frame Bounds

Let $\mathcal{G}(g, \Lambda) = \{M_\beta T_\alpha g\}_{(\alpha, \beta) \in \Lambda}$ be Gabor frame for $L^2(\mathbf{R})$ with frame bounds A, B . Then:

(a) $A \leq \|g\|_2^2 D^-(\Lambda) \leq \|g\|_2^2 D^+(\Lambda) \leq B$.

(b) **Tight frame** ($A = B$) $\implies D^-(\Lambda) = D^+(\Lambda)$.

Application 3: Quantifying Excess; Feichtinger Conjecture

Let $\mathcal{G}(g, \Lambda) = \{M_\beta T_\alpha g\}_{(\alpha, \beta) \in \Lambda}$ be Gabor frame for $L^2(\mathbf{R})$ with $g \in M^1$. Then:

(a) **If** $D^-(\Lambda) > 1$, then there exists $J \subset \Lambda$ with $D^-(J) = D^+(J) > 0$ such that $\mathcal{G}(g, \Lambda \setminus J)$ is a frame for $L^2(\mathbf{R})$.

(b) $\mathcal{G}(g, \Lambda)$ can be written as a finite union of Riesz sequences.

Application 4: Structure of the Dual Frame

Let $\mathcal{G}(g, \Lambda) = \{M_\beta T_\alpha g\}_{(\alpha, \beta) \in \Lambda}$ be Gabor frame for $L^2(\mathbf{R})$ with $g \in M^1$. Then:

(a) The dual frame $\tilde{\mathcal{G}} = \{\tilde{g}_{\alpha, \beta}\}_{(\alpha, \beta) \in \Lambda}$ is also contained in M^1 .

(Gröchenig/Leinert is for $\Lambda =$ lattice only.)

(b) The dual frame $\tilde{\mathcal{G}} = \{\tilde{g}_{\alpha, \beta}\}_{(\alpha, \beta) \in \Lambda}$ is a set of Gabor molecules, i.e., $\exists F \in L^1(\mathbf{R}^2)$ such that

$$|V_\varphi(\tilde{g}_{\alpha, \beta})(x, \omega)| \leq F(x - \alpha, \omega - \beta).$$

Compare:

$$|V_\varphi(M_\beta T_\alpha g)(x, \omega)| = |V_\varphi g(x - \alpha, \omega - \beta)|.$$

Remarks

(a) Applications 1–4 continue to hold (with minor changes) if the Gabor frame $\mathcal{G}(g, \Lambda)$ is replaced by a frame of Gabor molecules $\{g_{\alpha, \beta}\}_{(\alpha, \beta) \in \Lambda}$.

(b) Applications 1–4 are only special cases of results for general localized frames.

FINALE: CONCLUSIONS AND RELATED TOPICS

- a. Localization is a powerful tool for dealing with frames which possess modest amounts of structure but are largely “irregular.”
- b. Insights into relations among density, redundancy, frame properties, the structure of the dual frame, ...
- c. Extensions to families of associated spaces.
- d. Insights and contrasts with wavelets.