

CHAPTER I. INTEGRAL EQUATIONS

SECTION 1.1. GEOMETRY AND ONE TYPE OF LINEAR FUNCTION

Most often, freshman and sophomore mathematics is a study of the calculus of \mathbb{R}^n , likely with $n = 1, 2, \text{ or } 3$. Instead of working in the space \mathbb{R}^n , we now work in a space of functions on a finite interval. Most often, we will take that interval to be $[0,1]$. Of course, we will not work in the class of *all* functions on $[0,1]$; rather we ask that the linear space should consist of functions f for which

$$\int_0^1 |f(x)|^2 dx < \infty.$$

Then, we have an inner product space as we did in the finite dimensional calculus. This space is called $L^2([0,1])$. The dot product of two functions is given by

$$\langle f, g \rangle = \int_0^1 f(x) g(x) dx$$

and the norm of f is defined in terms of the dot product:

$$\|f\|^2 = \int_0^1 |f(x)|^2 dx.$$

It does not seem appropriate to study in detail the nature of $L^2[0,1]$ at this time. Rather, suffice it to say that the space is large enough to contain all continuous functions - even functions which are continuous except at a finite number of places. The interested student can find what $L^2[0,1]$ is by looking in standard books in Real Analysis.

Having an inner product space, we can now decide if f and g in the space are perpendicular. The distance and the angle between f and g are given by the same formulas as we understood from the finite dimensional calculus: the distance from f to g is $\|f - g\|$ and the angle between f and g satisfies

$$\cos(\theta) = \frac{\langle f, g \rangle}{\|f\| \|g\|}$$

provided neither f nor g is zero.

Suppose $\{f_p\}_{p=1}^{\infty}$ is a sequence of functions in $L^2([0,1])$. It is

valuable to consider the possible meanings for $\lim_p f_p(x) = g(x)$. There are at least three meanings.

The sequence $\{f_p\}_{p=1}$ converges *point-wise* to g at each x in $[0,1]$ provided that for each x in $[0,1]$,

$$\lim_p f_p(x) = g(x).$$

The sequence converges to g *uniformly* on $[0,1]$ provided that

$$\lim_p \sup_x |f_p(x) - g(x)| = 0.$$

And, the sequence converges to g *in norm* if

$$\lim_p || f_p - g || = 0.$$

An understanding of these three modes of convergence should be sought. These are ideas that re-occur in mathematics. In class, we will give examples to contrast these methods of convergence.

A type of integral equation will be studied in this section. For example, given a function called the kernel

$$K: [0,1] \times [0,1] \rightarrow \mathbb{R}$$

and a function $f: [0,1] \rightarrow \mathbb{R}$, we seek a function y such that for each x in $[0,1]$,

$$y(x) = \int_0^1 K(x,t) y(t) dt + f(x).$$

Such equations are called Fredholm equations of the second kind. An equation of the form

$$0 = \int_0^1 K(x,t) y(t) dt + f(x)$$

is a Fredholm equation of the first kind.

The requirements in this section on K and f will be that

$$\int_0^1 \int_0^1 |K(x,t)|^2 dx dt < \infty \quad \text{and} \quad \int_0^1 |f(x)|^2 dx < \infty.$$

These requirements are met if K and f are continuous.

For simplicity, we denote by \mathbf{K} the linear function given by

$$\mathbf{K}(y)(x) = \int_0^1 \mathbf{K}(x,t) y(t) dt.$$

Note that \mathbf{K} has a domain large enough to contain all functions y which are continuous on $[0,1]$. Also, if y is continuous then $\mathbf{K}(y)$ is a function and its value at x is denoted $\mathbf{K}(y)(x)$. In spoken conversation, it is not so easy to distinguish the number valued function K and the function valued \mathbf{K} . The bold character will be used in these notes to denote the latter.

It is well to note the resemblance of this function \mathbf{K} to the multiplication of a matrix A by a vector u :

$$A(u)(p) = \sum_{q=1}^n A(p,q) u(q).$$

This formula has the same form as that for \mathbf{K} given above. The analogy should be instructive.

In order to understand \mathbf{K}^* , one must consider $\langle \mathbf{K}(f), g \rangle$ and seek \mathbf{K}^* such that $\langle \mathbf{K}f, g \rangle = \langle f, \mathbf{K}^*g \rangle$.

$$\begin{aligned} \langle \mathbf{K}(f), g \rangle &= \int_0^1 \mathbf{K}(f)(x) g(x) dx \\ &= \int_0^1 \int_0^1 \mathbf{K}(x,t) f(t) g(x) dt dx. \end{aligned}$$

An examination of these last equations leads one to guess that \mathbf{K}^* is given by

$$\mathbf{K}^*(g)(t) = \int_0^1 \mathbf{K}(x,t) g(x) dx,$$

or, keeping t as the variable of integration,

$$\mathbf{K}^*(g)(x) = \int_0^1 \mathbf{K}(t,x) g(t) dt,$$

Those last equations verified that

$$\langle \mathbf{K}(f), g \rangle = \langle f, \mathbf{K}^*(g) \rangle.$$

Care had to be taken to watch whether the "variable of integration" is t or x in the integrals involved.

In summary, if K is the kernel associated with the linear operator \mathbf{K} , then the kernel associated with \mathbf{K}^* is given by $K^*(x,y) = K(y,x)$. It is of value to compare how to get \mathbf{K}^* from \mathbf{K} with the process of how to get A^* from A :

$$A^*_{p,q} = A_{q,p}.$$

Consistent with the rather standard notation we have adopted above, it is clear that a briefer representation of the equation

$$y(x) = \int_0^1 K(x,t) y(t) dt + f(x)$$

is the concise equation $y = \mathbf{K}(y) + f$, or $(1 - \mathbf{K}) y = f$.

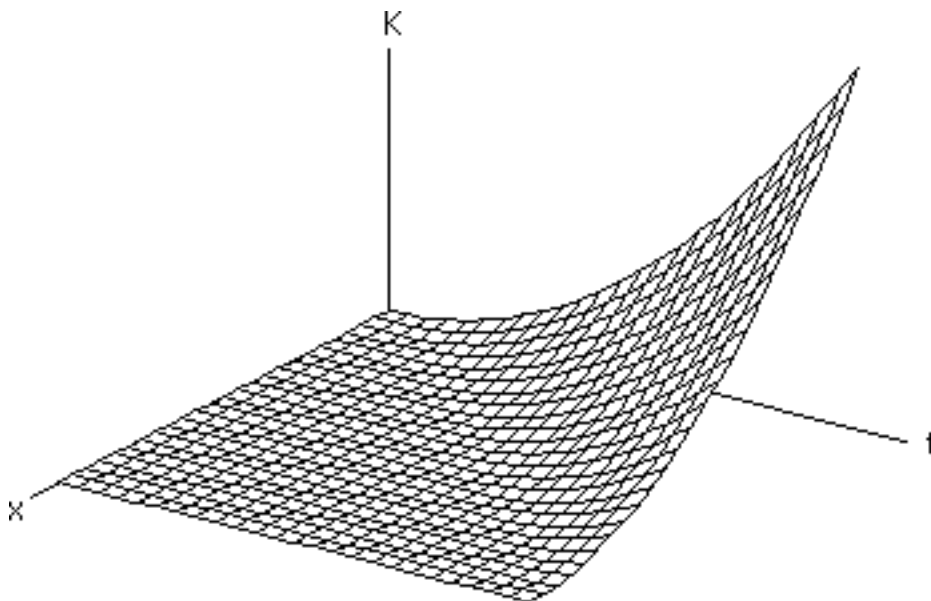
EXAMPLE: Suppose that

$$K(x,t) = \begin{cases} (x-t)^2 & \text{if } 0 < x < t < 1 \\ 0 & \text{if } 0 < t < x < 1 \end{cases}.$$

To get K^* , let's use other letters for the argument of K^* and K to avoid confusion. Suppose that $0 < u < v < 1$. Then, $K^*(u,v) = K(v,u) = 0$. In a similar manner, $K^*(u,v) = (u-v)^2$ if $0 < v < u < 1$. Note that K^* is not K .

$$K^*(x,t) = \begin{cases} 0 & \text{if } 0 < x < t < 1 \\ (x-t)^2 & \text{if } 0 < t < x < 1 \end{cases}.$$

The discussion of this example has been algebraic to this point. Consider this geometric notion that is suggested by the alternate name for "self-adjoint", namely, some call K "symmetric" if $K(x,t) = K(t,x)$. The geometric name suggests a picture and the picture is the graph of K . The K of this example is not symmetric in x and t . Its graph is not symmetric about the line $x = t$. The function K is different from the function K^* .

**EXERCISE 2.1:**

1. (a) Find the distance from $\sin(x)$ to $\cos(x)$ in $L^2[0,1]$ and $L^2[-1,1]$.

$$\text{Ans: } 1, \sqrt{2}$$

- (b) Find the angle between $\sin(x)$ and $\cos(x)$ in $L^2[0,1]$ and $L^2[-1,1]$.

$$\text{Ans: } \pi/2, \pi/2.$$

2. Repeat 1. (a) and (b) for x and x^2 .

$$\text{Ans: } 1/\sqrt{30}, 4/\sqrt{15},$$

$$\arccos(\sqrt{15}/4), \pi/2$$

3. Suppose $K(x,t) = 1 + 2xt^2$ on $[0,1] \times [0,1]$ and $y(x) = 3 - x$. Compute $K(y)$ and $K^*(y)$.

$$\text{Ans: } (5+3x)/2,$$

$$(15+14x^2)/6$$

4. Suppose $K(x,t) = \begin{cases} xt & \text{if } 0 < x < t < 1 \\ xt^2 & \text{if } 0 < t < x < 1 \end{cases}$. For $y(x) = 3 - x$, compute $K(y)$

and $K^*(y)$.

$$\text{Ans: } K[y](x) = -\frac{x^5}{4} + \frac{4x^4}{3} - \frac{3x^3}{2} + \frac{7x}{6}$$