

CHAPTER I. INTEGRAL EQUATIONS

SECTION 6: K DOES NOT HAVE A SEPARABLE KERNEL AND IS NOT "SMALL".

In case K neither has a separable kernel nor is small, then the next best choice is to approximate K with an operator which has a separable kernel.

Theorem. If

$$\int_0^1 \int_0^1 |K(x,t)|^2 dx dt < 1$$

then there are kernels K_n and G such that

- (1) $K = K_n + G$,
- (2) K_n has a separable kernel,

and (3) $\int_0^1 \int_0^1 |G(x,t)|^2 dx dt < 1$.

In the succeeding pages, we show how to compute K_n and G . However, we first illustrate that the problem is - in theory - solved if we have such a resolution of K into K_n and G . We seek y such that

$$y = Ky + f = K_n y + Gy + f$$

or $y - Gy = K_n y + f$.

Use the resolvent for G :

$$(1-G)^{-1} = 1 + R_G,$$

to get that

$$\begin{aligned} y &= K_n y + R_G(K_n y + f) + f \\ &= [K_n + R_G K_n]y + (R_G f + f). \end{aligned}$$

Define z to be $R_G f + f$, or, what is the same, solve the equation

$$z = Gz + f.$$

We can solve this equation because G is small. Now, we seek y such that

$$y = (K_n + R_G K_n)y + z.$$

Re-writing this as an integral equation, we seek y such that

$$y(x) = \int_0^1 H(x,t) y(t) dt + z(x)$$

where

$$H(x,t) = K_n(x,t) + \int_0^1 R_G(x,s) K_n(s,t) ds.$$

What is astonishing is that this last integral equation is separable! To see this, suppose

$$K_n(x,t) = \sum_{p=1}^n a_p(x) b_p(t).$$

Then

$$\begin{aligned} & \int_0^1 R_G(x,s) K_n(s,t) ds \\ &= \int_0^1 R_G(x,s) \sum_{p=1}^n a_p(s) b_p(t) ds \\ &= \sum_{p=1}^n \int_0^1 R_G(x,s) a_p(s) ds b_p(t) \end{aligned}$$

So, here is the conclusion. If K is $K_n + G$ as in the above Theorem, in order to solve $y = Ky + f$, use the fact that

$$\int_0^1 \int_0^1 |G(x,t)|^2 dx dt < 1$$

to form the resolvent for R_G ; then find z such that $z = (1 + R_G)f$. Finally, solve the separable equation $y = (K_n + R_G K_n)y + z$.

We now must address the question of how to achieve the decomposition of K into $K_n + G$. The ideas are familiar to persons knowledgeable about the techniques of Fourier Series. In summary of those ideas, recall that if p and q are integers, then

$$\begin{aligned} \int_0^1 \sin(p x) \sin(q x) dx &= 0 \text{ if } p \neq q \\ &= \frac{1}{2} \text{ if } p = q. \end{aligned}$$

We seek A_{pq} such that

$$K(x,y) = \sum_{p=1}^{\infty} \sum_{q=1}^{\infty} A_{pq} \sin(p x) \sin(q y).$$

In fact, by integrating both sides of this last equation after multiplying by $\sin(m x) \sin(n y)$, we have

$$\int_0^1 \int_0^1 K(x,y) \sin(m x) \sin(n y) dx dy = \frac{A_{mn}}{4}$$

From the theory of Fourier series,

$$\lim_n \sum_{p=1}^n \sum_{q=1}^n A_{pq} \sin(p x) \sin(q y) = K(x,y)$$

in the sense that

$$\left| \int_0^1 \int_0^1 [K(x,y) - \sum_{p=1}^n \sum_{q=1}^n A_{pq} \sin(p x) \sin(q y)]^2 dx dy \right| \rightarrow 0$$

as $n \rightarrow \infty$. Let n be an integer such that

$$\left| \int_0^1 \int_0^1 [K(x,y) - \sum_{p=1}^n \sum_{q=1}^n A_{pq} \sin(p x) \sin(q y)]^2 dx dy \right| < 1.$$

Define K_n and G by

$$K_n(x,y) = \sum_{p=1}^n \sum_{q=1}^n A_{pq} \sin(p x) \sin(q y)$$

and $G = K - K_n$.

Then these three requirements are met:

- (1) $K = K_n + G$,
- (2) K_n is separable,

and (3) $\int_0^1 \int_0^1 |G(x,y)|^2 dx dy < 1$.

Thus, we have an analysis of an integral equation $y = Ky + f$ where

$$\int_0^1 \int_0^1 |K(x,y)|^2 dx dy < \dots$$

The engineer will want to know about approximations. Here are two appropriate questions:

(a) Suppose one hopes to solve $y = Ky + f$ and that K_n is separable and approximates K . How well does the solution u for $u = K_n u + f$ approximate y ?

(b) Suppose $K = K_n + G$ and $S = \sum_{p=1}^n G^p$ approximates R_G . How well does the solution u for

$$u = [K_n + SK_n] u + [1 + S] f$$

approximate y ?

Exercise 1.6.

Solve the integral equation $y = K[y] + f$ in case $f(t) = t$ and

$$K(x,t) = \begin{cases} xt + x - t & \text{if } t < x \\ xt & \text{if } t > x \end{cases}$$