

MATH 4581 Lecture 19 Thursday Oct. 28, 2021

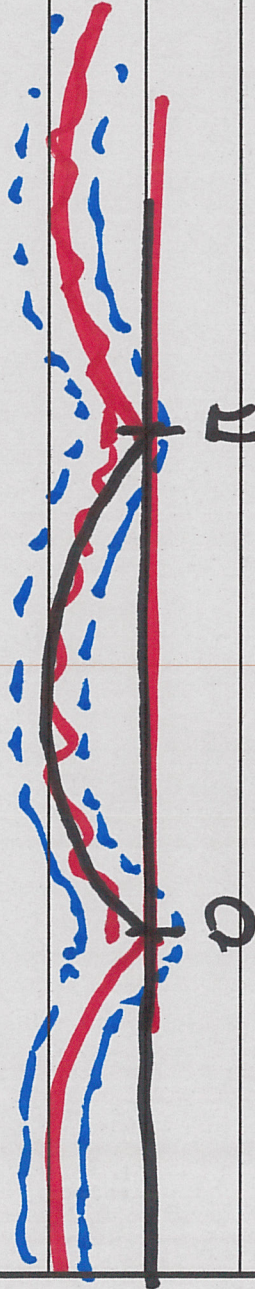
Assignment 4 Problem 4

$$\begin{cases} u_t = u_{xx} & \text{on } (0, \pi) \times (0, \infty) \end{cases}$$

$$u_x(0, t) = 0 = u_x(\pi, t) \leftarrow \text{cosine basis}$$

$$\{ e^{-j^2 t} \cos jx \}_{j=0}^{\infty}$$

$$u(x, 0) = \sin x$$



$$\sin x = a_0 + \sum_{j=1}^{\infty} a_j \cos jx$$

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$$u_t = u_{xx}$$

$$u = A(x)B(t)$$

$$\begin{cases} u_x(0, t) = 0 \end{cases}$$

$$\begin{cases} u_x(\pi, t) = 0 \end{cases}$$

$$AB' = A''B$$

$$\frac{A''}{A} = \frac{B'}{B} = \lambda$$

$$A'(0)B(t) = 0$$

$$A'(\pi)B(t) = 0$$

$$\begin{cases} A'' = \lambda A \end{cases}$$

$$\begin{cases} A'(0) = 0 \end{cases}$$

$$\begin{cases} A'(\pi) = 0 \end{cases}$$

$$\lambda > 0, \lambda = 0, \lambda < 0$$

$$\uparrow A_0 B_0 = \text{const.} = a_0$$

$$\lambda < 0$$

$$A(x) = a \cos \mu x + b \sin \mu x$$

$$-\mu^2$$

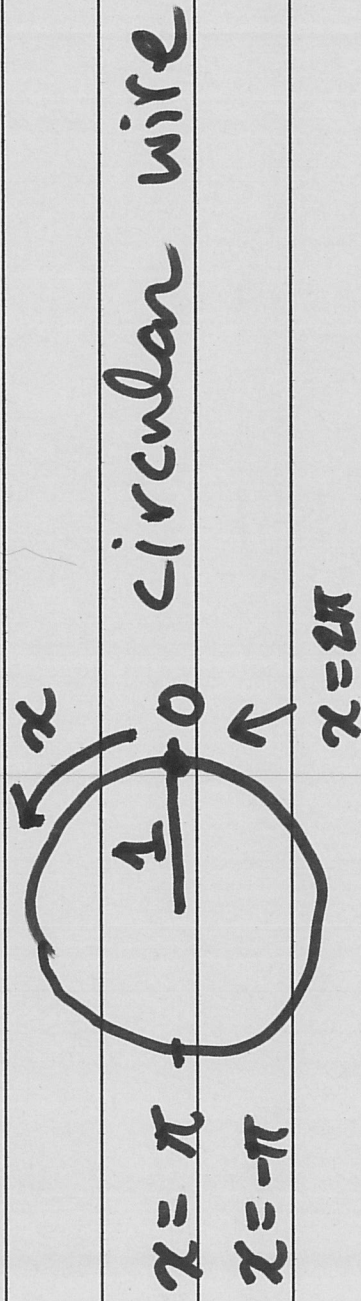
$$A'(x) = -a\mu \sin \mu x + b\mu \cos \mu x$$

$$A'(0) = 0 \Rightarrow b = 0.$$

$$A'(\pi) = 0 \Rightarrow \boxed{\sin \mu \pi = 0}$$

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Assignment 4 Problem 5 (typo)



Correct "boundary" conditions

$$\begin{cases} u(0, t) = u(2\pi, t), & t > 0 \\ u_x(0, t) = u_x(2\pi, t), & t > 0 \end{cases}$$

periodicity conditions

Wave Equation:

0 l equilibrium

tension force \rightarrow homogeneous extension

force $|F| = k(l' - l)$

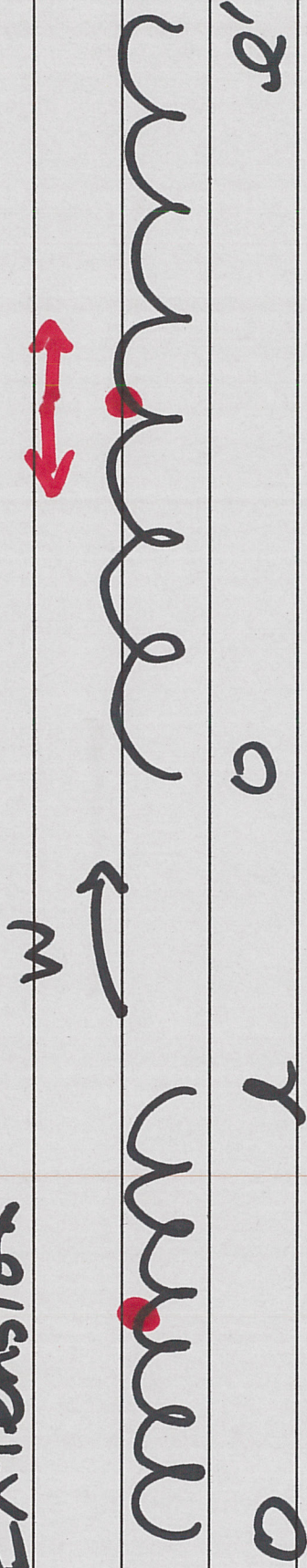
l' MAPPING FUNCTION $w(x) = \frac{l'}{l} x$

homogeneous compression

force $|F| = k(l - l')$

l' MAPPING FUNCTION $w(x) = \frac{l'}{l} x$

Extension



$$F = -k(l' - l) = -k \left(\frac{x'}{l} - 1 \right) \epsilon$$

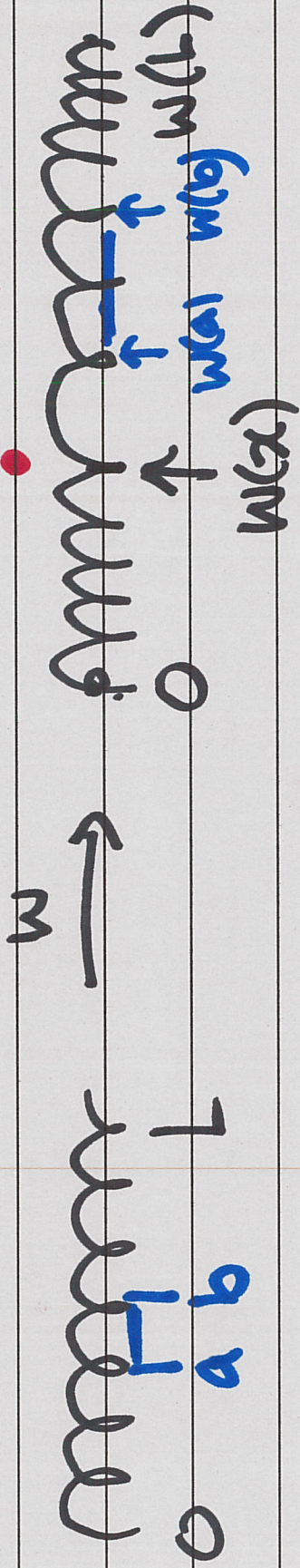
$$w(x) = \frac{x'}{l} x$$

What should be the tension force at each point of an inhomogeneous extension $w: [0, l] \rightarrow \mathbb{R}$?

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Inhomogeneous deformation

tension force
 (?)



hom: $F_{\text{hom}} = -\varepsilon \left(\frac{d'}{d} - 1 \right)$

$\left(\frac{d'}{d} - 1 \right)$ is the ratio of the change in length to the original length. $\left(\frac{d'}{d} - 1 \right)$ is the ratio of the change in length to the original length. $\left(\frac{d'}{d} - 1 \right)$ is the ratio of the change in length to the original length.

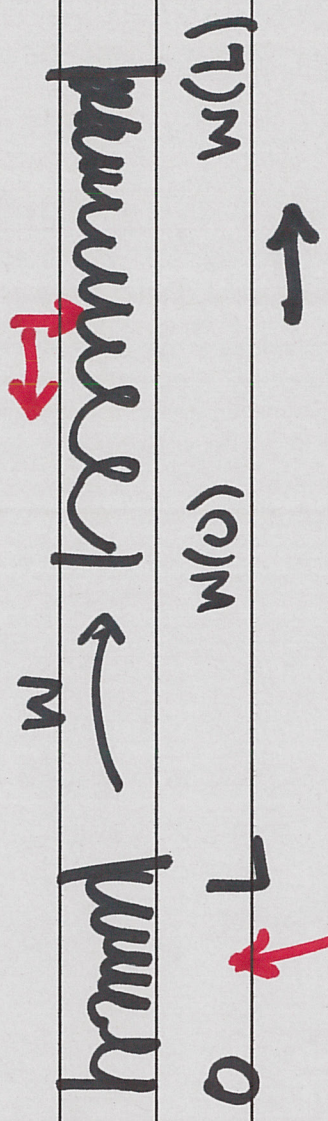
$w_{\text{hom}} = \frac{d'}{d} - 1$

$F = -\varepsilon (w'(x) - 1)$

$\lim_{a, b \rightarrow x} \frac{w(b) - w(a)}{b - a}$

$$\mathcal{N} = \{ w \in C^1[0, L] : w' \geq 0 \}$$

↳ admissible class. $F = -\epsilon(w' - 1)$



$$F \rightarrow \begin{cases} +\epsilon(w'(x) - 1) \\ = \rho(L - x)g \end{cases}$$

$\rho : [0, L] \rightarrow (0, L)$

$$+\epsilon(w'(x) - 1) = \rho(L - x)g$$

↑ constant? or $p = p(x)$

$$W' = \frac{p_0}{\epsilon} (L-x) + 1$$

\wedge W is quadratic!

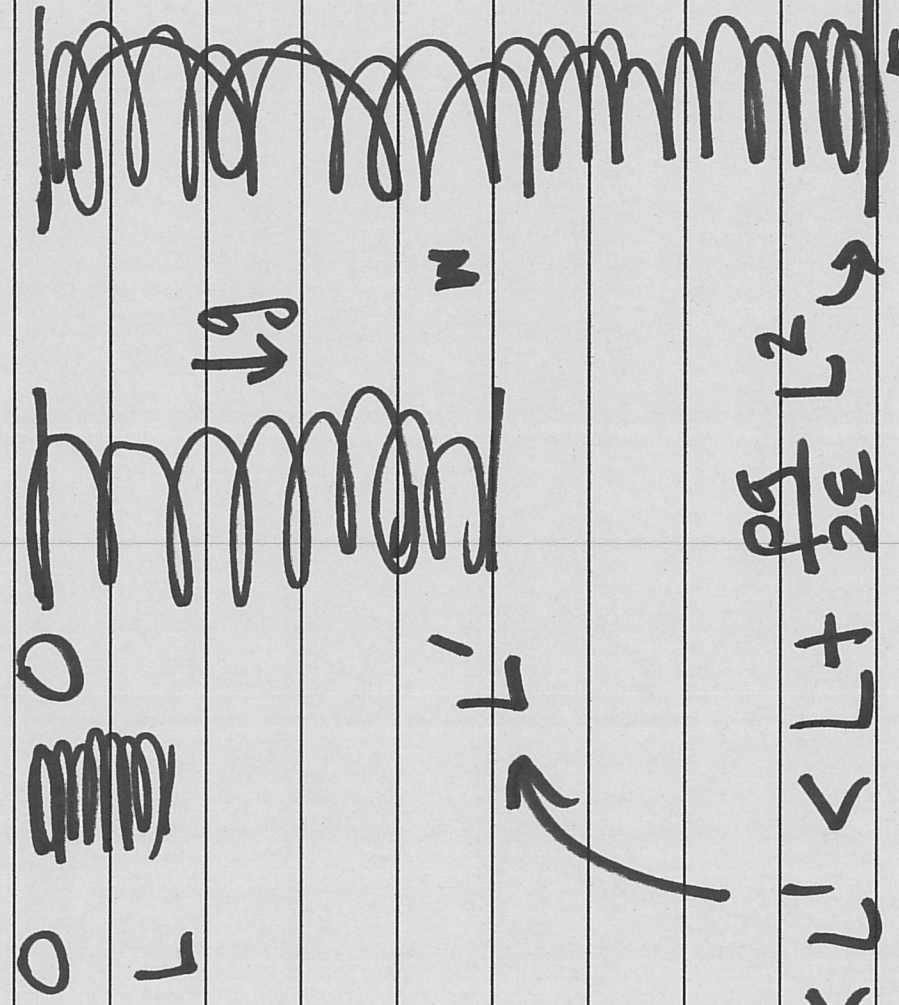
$$W(x) = -\frac{p_0}{2\epsilon} x^2 + \left(\frac{p_0}{\epsilon} L + 1\right) x$$

$$(W(0) = 0)$$

SLINKY MODELERS: THIS IS A LITTLE OFF.

Why? And how should the model be modified to be more exact.

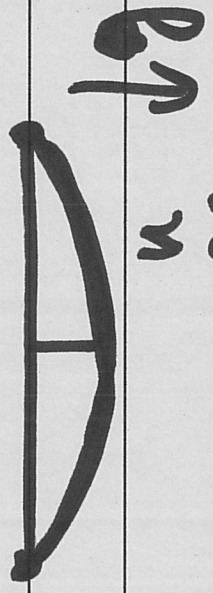
Fixed Ends Sagging



$$L < L' < L + \frac{\rho g}{2E} L^2 <$$

$$W'(L) = 1$$

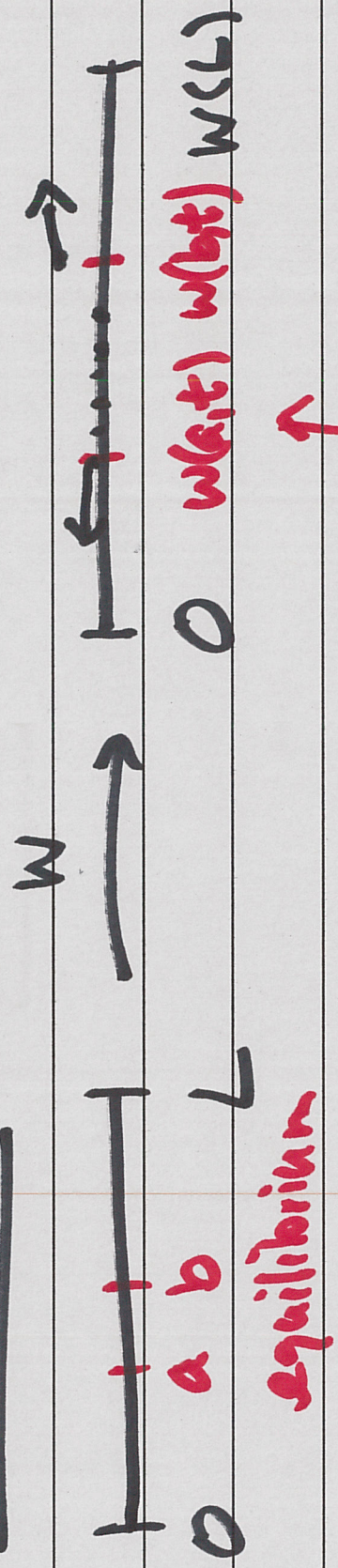
Habanman
sagging string



$$(u_E)_{xx} = \frac{\rho g}{E}$$

u_E'''' ← sagging.

Derivation of wave PDE - dynamics



mass $\rho(b-a)$

displacement $w(x,t)$

Newton:
$$F(b,t) - F(a,t) = -\epsilon(w_x(a,t) - 1) + \epsilon(w_x(b,t) - 1)$$

acceleration

$$\rho(b-a) w_{tt}(x^*, t) = \epsilon (w_x(b, t) - w_x(a, t))$$

↑
some/any $x^* \in (a, b)$.

$$\frac{w_x(b, t) - w_x(a, t)}{b-a}$$

$$\rho w_{tt}(x^*, t) = \epsilon$$

$$b, a \rightarrow x$$

$$\rho w_{tt} = \epsilon w_{xx}$$

WARNING: HERE ρ and ϵ are constant.