

Final
Exam
Review

In-Class Final Exam Review Set A, Math 1554, Fall 2019

1. Indicate whether the statements are true or false.

true	false	
<input checked="" type="radio"/>	<input type="radio"/>	If a linear system has more unknowns than equations, then the system has either no solutions or infinitely many solutions.
<input type="radio"/>	<input checked="" type="radio"/>	A $n \times n$ matrix A and its echelon form E will always have the same eigenvalues.
<input checked="" type="radio"/>	<input type="radio"/>	$x^2 - 2xy + 4y^2 \geq 0$ for all real values of x and y .
<input checked="" type="radio"/>	<input type="radio"/>	If matrix A has linearly dependent columns, then $\dim(\text{Null}(A)) > 0$.
<input checked="" type="radio"/>	<input type="radio"/>	If λ is an eigenvalue of A , then $\dim(\text{Null}(A - \lambda I)) > 0$.
<input checked="" type="radio"/>	<input type="radio"/>	If A has QR decomposition $A = QR$, then $\text{Col}A = \text{Col}Q$.
<input checked="" type="radio"/>	<input type="radio"/>	If A has LU decomposition $A = LU$, then $\text{rank}(A) = \text{rank}(U)$.
<input checked="" type="radio"/>	<input type="radio"/>	If A has LU decomposition $A = LU$, then $\dim(\text{Null}(A)) = \dim(\text{Null}(U))$.

wide A
 $\left(\begin{array}{c} \text{---} \\ \text{---} \\ \text{---} \end{array} \right)$

$A = \begin{bmatrix} 1 & -1 \\ -1 & 4 \end{bmatrix}$ $Q(x) = x^T A x$

$P(x) = x^2 - 5x + 3$

$\lambda = \frac{5 \pm \sqrt{25 - 12}}{2} \geq 0$

yes $\sqrt{5 - \sqrt{13}} \geq 0$

yes $\sqrt{5 + \sqrt{13}} \geq 0$

yes $\sqrt{5} \geq \sqrt{13}$

2. Give an example of the following.

i) A 4×3 lower triangular matrix, A , such that $\text{Col}(A)^\perp$ is spanned by

the vector $\vec{v} = \begin{pmatrix} 1 \\ 2 \\ 3 \\ 1 \end{pmatrix}$. $A = \begin{pmatrix} & & \\ & & \\ & & \\ & & \end{pmatrix}$

ii) A 3×4 matrix A , that is in RREF, and satisfies $\dim(\text{Null}(A)) = 2$ and $\dim(\text{Col}(A)^\perp) = 2$

$A = \begin{pmatrix} NP \\ & \\ & \end{pmatrix}$

$\dim(\text{Col}(A)) = 1$

3 rows
4 cols

1 pivot
2 free

#pivot + #free = #cols

$\dim \text{Col}A + \dim \text{Null}A = n$

what about R ?

$A = QR$

$R = Q^T A$ ✓

R square $n \times n$ ✓

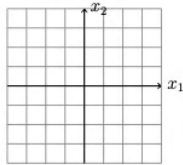
diagonal ✓
on the positive

$\|r_i\| = \|v_i\|$ ✓

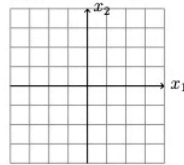
Col of R Col of A

3. (3 points) Suppose $A = \begin{pmatrix} 3 & 1 \\ 6 & 2 \end{pmatrix}$. On the grid below, sketch a) $\text{Col}(A)$, and b) the eigenspace corresponding to eigenvalue $\lambda = 5$.

(a) $\text{Col}(A)$



(b) $\lambda = 5$ eigenspace



4. Fill in the blanks.

(a) If $A \in \mathbb{R}^{M \times N}$, $M < N$, and $A\vec{x} = 0$ does not have a non-trivial solution, how many pivot columns does A have?

(b) Consider the following linear transformation.

$$T(x_1, x_2) = (2x_1 - x_2, 4x_1 - 2x_2, x_2 - 2x_1).$$

The domain of T is . The image of $\vec{x} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ under $T(\vec{x})$ is $\begin{pmatrix} \\ \\ \end{pmatrix}$. The co-domain of T is . The range of T is:

5. Four points in \mathbb{R}^2 with coordinates (t, y) are $(0, 1)$, $(\frac{1}{4}, \frac{1}{2})$, $(\frac{1}{2}, -\frac{1}{2})$, and $(\frac{3}{4}, -\frac{1}{2})$. Determine the values of c_1 and c_2 for the curve $y = c_1 \cos(2\pi t) + c_2 \sin(2\pi t)$ that best fits the points. Write the values you obtain for c_1 and c_2 in the boxes below.

$$c_1 = \text{} \quad c_2 = \text{$$

In-Class Final Exam Review Set B, Math 1554, Fall 2019

1. Indicate whether the statements are true or false.

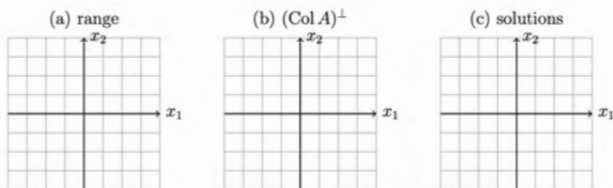
true false

- For any vector $\vec{y} \in \mathbb{R}^2$ and subspace W , the vector $\vec{v} = \vec{y} - \text{proj}_W \vec{y}$ is orthogonal to W .
- If A is $m \times n$ and has linearly dependent columns, then the columns of A cannot span \mathbb{R}^m .
- If a matrix is invertible it is also diagonalizable.
- If E is an echelon form of A , then $\text{Null } A = \text{Null } E$.
- If the SVD of $n \times n$ singular matrix A is $A = U\Sigma V^T$, then $\text{Col } A = \text{Col } U$.
- If the SVD of $n \times n$ matrix A is $A = U\Sigma V^T$, $r = \text{rank } A$, then the first r columns of V give a basis for $\text{Null } A$.
-

2. Give an example of:

- a) a vector $\vec{u} \in \mathbb{R}^3$ such that $\text{proj}_{\vec{p}} \vec{u} = \vec{p}$, where $\vec{u} \neq \vec{p}$, and $\vec{p} = \begin{pmatrix} 0 \\ 2 \\ 0 \end{pmatrix}$: $\vec{u} = \begin{pmatrix} \\ \\ \end{pmatrix}$
- b) an upper triangular 4×4 matrix A that is in RREF, 0 is its only eigenvalue, and its corresponding eigenspace is 1-dimensional. $A = \begin{pmatrix} & & & \\ & & & \\ & & & \\ & & & \end{pmatrix}$
- c) A 3×4 matrix, A , and $\text{Col}(A)^\perp$ is spanned by $\begin{pmatrix} 1 \\ -3 \\ -4 \end{pmatrix}$.
- d) A 2×2 matrix in RREF that is diagonalizable and not invertible.

3. Suppose $A = \begin{pmatrix} 2 & -1 \\ 4 & -2 \end{pmatrix}$. On the grid below, sketch a) the range of $x \rightarrow Ax$, b) $(\text{Col } A)^\perp$, (c) set of solutions to $A\vec{x} = \begin{pmatrix} 3 \\ 6 \end{pmatrix}$.



4. Matrix A is a 2×2 matrix whose eigenvalues are $\lambda_1 = \frac{1}{2}$ and $\lambda_2 = 1$, and whose corresponding eigenvectors are $\vec{v}_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$, $\vec{v}_2 = \begin{pmatrix} 4 \\ 1 \end{pmatrix}$. Calculate
1. $A(\vec{v}_1 + 4\vec{v}_2)$
 2. A^{10}
 3. $\lim_{k \rightarrow \infty} A^k(\vec{v}_1 + 4\vec{v}_2)$

In-Class Final Exam Review Set C, Math 1554, Fall 2019

1. Indicate whether the statements are possible or impossible.

possible impossible

- | | | |
|-----------------------|-----------------------|---|
| <input type="radio"/> | <input type="radio"/> | $Q(\vec{x}) = \vec{x}^T A \vec{x}$ is a positive definite quadratic form, and $Q(\vec{v}) = 0$, where \vec{v} is an eigenvector of A . |
| <input type="radio"/> | <input type="radio"/> | The maximum value of $Q(\vec{x}) = ax_1^2 + bx_2^2 + cx_3^2$, where $a > b > c$, for $\vec{x} \in \mathbb{R}^3$, subject to $\ \vec{x}\ = 1$, is not unique. |
| <input type="radio"/> | <input type="radio"/> | The location of the maximum value of $Q(\vec{x}) = ax_1^2 + bx_2^2 + cx_3^2$, where $a > b > c$, for $\vec{x} \in \mathbb{R}^3$, subject to $\ \vec{x}\ = 1$, is not unique. |
| <input type="radio"/> | <input type="radio"/> | A is 2×2 , the algebraic multiplicity of eigenvalue $\lambda = 0$ is 1, and $\dim(\text{Col}(A)^\perp)$ is equal to 0. |
| <input type="radio"/> | <input type="radio"/> | Stochastic matrix P has zero entries and is regular. |
| <input type="radio"/> | <input type="radio"/> | A is a square matrix that is not diagonalizable, but A^2 is diagonalizable. |
| <input type="radio"/> | <input type="radio"/> | The map $T_A(\vec{x}) = A\vec{x}$ is one-to-one but not onto, A is $m \times n$, and $m < n$. |
-

2. Transform $T_A = A\vec{x}$ reflects points in \mathbb{R}^2 through the line $y = 2 + x$. Construct a standard matrix for the transform using homogeneous coordinates. Leave your answer as a product of three matrices.

SKIP

3. Fill in the blanks.

- (a) $T_A = A\vec{x}$, where $A \in \mathbb{R}^{2 \times 2}$, is a linear transform that first rotates vectors in \mathbb{R}^2 clockwise by $\pi/2$ radians about the origin, then reflects them through the line $x_1 = x_2$. What is the value of $\det(A)$?
- (b) B and C are square matrices with $\det(BC) = -5$ and $\det(C) = 2$. What is the value of $\det(B) \det(C^4)$?
- (c) A is a 6×4 matrix in RREF, and $\text{rank}(A) = 4$. How many different matrices can you construct that meet these criteria?
- (d) $T_A = A\vec{x}$, where $A \in \mathbb{R}^{2 \times 2}$, projects points onto the line $x_1 = x_2$. What is an eigenvalue of A equal to?
- (e) If an eigenvalue of A is $\frac{1}{3}$, what is one eigenvalue of A^{-1} equal to?
- (f) If A is 30×12 and $A\vec{x} = \vec{b}$ has a unique least squares solution \hat{x} for every \vec{b} in \mathbb{R}^{30} , the dimension of $\text{Null}A$ is .

4. A is a 2×2 matrix whose nullspace is the line $x_1 = x_2$, and $C = \begin{pmatrix} 1 & 2 \\ 0 & 1 \end{pmatrix}$. Sketch the nullspace of $Y = AC$.

5. Construct an SVD of $A = \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}$. Use your SVD to calculate the condition number of A .

5. Construct an SVD of $A = \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}$. Use your SVD to calculate the condition number of A .

Final Exam Review Worksheet, Spring 2020

1. (12 points) Indicate whether the statements are true or false.

	true	false
i) If $A\vec{x} = \vec{b}$ has infinitely many solutions, then the RREF of A must have a row of zeros.	<input type="radio"/>	<input type="radio"/>
ii) If A is $n \times n$ and $A\vec{x} = \vec{b}$ is inconsistent, then the columns of A are linearly dependent.	<input type="radio"/>	<input type="radio"/>
iii) If A is a 3×3 matrix and $\det(A) = 2$, then $\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$ is a basis for $\text{Col}(A)$.	<input type="radio"/>	<input type="radio"/>
iv) A basis for a subspace must include the zero vector.	<input type="radio"/>	<input type="radio"/>
v) If the columns of an $n \times n$ matrix span \mathbb{R}^n , then the matrix must be invertible.	<input type="radio"/>	<input type="radio"/>
vi) A matrix, A , and any echelon form of A will have the same column space.	<input type="radio"/>	<input type="radio"/>
xii) An $n \times n$ diagonalizable matrix must have n distinct eigenvalues.	<input type="radio"/>	<input type="radio"/>
xiii) The geometric multiplicity of an eigenvalue is greater than or equal to the algebraic multiplicity of the same eigenvalue.	<input type="radio"/>	<input type="radio"/>
ix) If S is a subspace of \mathbb{R}^8 and $\dim(S) = 6$, then S^\perp is a two-dimensional subspace.	<input type="radio"/>	<input type="radio"/>
x) If two vectors \vec{u} and \vec{v} are orthogonal, then they are linearly independent.	<input type="radio"/>	<input type="radio"/>
xi) If A is symmetric, and $v_1 \neq v_2$ are two eigenvectors of A , then v_1 and v_2 are orthogonal.	<input type="radio"/>	<input type="radio"/>
xii) For a symmetric matrix A , the largest value of $\ Ax\ $ subject to the constraint that $\ x\ = 1$ is the largest singular value of A .	<input type="radio"/>	<input type="radio"/>

2. (10 points) Fill in the blanks.

(a) List all values of $k \in \mathbb{R}$ such that the vectors $\begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$, $\begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}$, $\begin{pmatrix} 3 \\ k \\ -1 \end{pmatrix}$ are linearly dependent.

(b) Suppose $\det(A^2B) = 4$, $\det(B) = \frac{1}{3}$, and A and B are $n \times n$ real matrices. List all possible values of $\det(A)$.

(c) List all values of k such that $A\vec{x} = \vec{b}$ is inconsistent where $\vec{b} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$ and

$$A = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 2k \\ 0 & 0 & k \end{pmatrix}. \quad k = \text{$$

(d) Consider the row operation that reduces matrix A to RREF.

$$A = \underbrace{\begin{pmatrix} 0 & 1 & 0 \\ 0 & -5 & 1 \end{pmatrix}}_A \sim \underbrace{\begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}}_{E_1A} = E_1A$$

By inspection, E_1 is the elementary matrix $E_1 = \begin{pmatrix} & & \\ & & \\ & & \end{pmatrix}$.

(e) If $S = \{\vec{x} \in \mathbb{R}^4 \mid x_1 = x_2\}$ then $\dim S = \text{$.

(f) If $A = \begin{pmatrix} 1 & 2 \\ 0 & 0 \\ 3 & 6 \end{pmatrix}$, then a non-zero vector in $\text{Null}A$ is $\begin{pmatrix} & \\ & \end{pmatrix}$.

(g) If the basis for the column space of an 11×15 matrix consists of exactly three vectors, how many pivot columns does the matrix have?

(h) If A is a 3×3 matrix with eigenvalues 5 and $1 - i$, then the third eigenvalue is .

(i) If \vec{v} is the steady-state vector for a regular stochastic matrix, then \vec{v} is an eigenvector of that matrix corresponding to the eigenvalue $\lambda = \text{$.

(j) List all values of k such that $A = \begin{pmatrix} 4 & k \\ 0 & 4 \end{pmatrix}$ is diagonalizable.

3. (6 points) Fill in the blanks.

(a) The distance between the vector $\vec{u} = \begin{pmatrix} 2 \\ 4 \end{pmatrix}$ and the line spanned by $\vec{w} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ is .

(b) If W is the plane spanned by the vectors $\vec{u} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$ and $\vec{v} = \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}$, a basis of W^\perp is given by $\vec{w} = \begin{pmatrix} \\ \\ \end{pmatrix}$.

(c) If A is a 3×3 matrix and $\dim(\text{Row}(A)) = 2$, then $\dim(\text{Null}(A^T)) = \text{}$.

(d) If \vec{u} and \vec{v} are two vectors in \mathbb{R}^2 satisfying $\|\vec{u}\| = 3$, $\|\vec{v}\| = 2$ and $\vec{u} \cdot \vec{v} = \frac{3}{2}$, then the length of the sum of the two vectors is $\|\vec{u} + \vec{v}\| = \text{}$.

(e) Let U be an $n \times n$ matrix with orthonormal columns. Then $U^t U = \text{}$.

(f) The maximum value of $Q(\vec{x}) = 10x_1^2 - 7x_2^2 - 4x_3^2$ subject to the constraints $\vec{x} \cdot \vec{x} = 1$ and $\vec{x} \cdot \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = 0$ is equal to .

4. (8 points) Indicate whether the statements are possible or impossible.

	possible	impossible
i) The linear transformation $T : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ is onto. $T = Ax$, and A has linearly independent columns.	<input type="radio"/>	<input type="radio"/>
ii) The columns of a matrix with N rows are linearly dependent and span \mathbb{R}^N .	<input type="radio"/>	<input type="radio"/>
iii) Matrix A is $n \times n$, $A\vec{x} = A\vec{y}$ for some $\vec{x} \neq \vec{y}$, and $\dim(\text{Null}A) = 0$.	<input type="radio"/>	<input type="radio"/>
iv) P is a stochastic matrix which has zero in the first entry of the first row, but is regular.	<input type="radio"/>	<input type="radio"/>
v) There is a 2×2 real matrix A and a vector $\vec{u} \neq \vec{0}$, such that $\vec{u} \in \text{Null}(A)$ and $\vec{u} \in \text{Row}(A)$.	<input type="radio"/>	<input type="radio"/>
vi) A is a non-singular matrix which is not diagonalizable.	<input type="radio"/>	<input type="radio"/>
vii) \vec{v}_1 and \vec{v}_2 are eigenvectors of matrix A that correspond to distinct eigenvalues, $A = A^T$, and $\vec{v}_1 \cdot \vec{v}_2 = 1$.	<input type="radio"/>	<input type="radio"/>
viii) \vec{y} is a non-zero vector in \mathbb{R}^5 . The projection of \vec{y} onto a subspace of \mathbb{R}^5 is the zero vector.	<input type="radio"/>	<input type="radio"/>

5. (2 points) Suppose A and B are $n \times n$ matrices and A is symmetric. Fill in the circles next to the expressions (if any) that are equal to

$$(B^T AB)^T$$

Leave the other circles empty.

- $BA^T B^T$
 $B^T AB$

6. (2 points) List the singular values of the matrix below. (No need to justify your answer.)

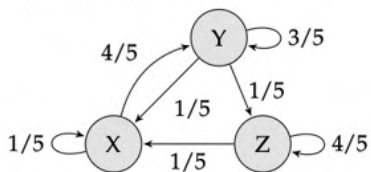
$$\begin{bmatrix} 0 & -2 \\ 0 & 1 \end{bmatrix}, \quad \sigma_1 = \underline{\hspace{2cm}}, \quad \sigma_2 = \underline{\hspace{2cm}},$$

7. (6 points) Let $A = \begin{pmatrix} -2 & -4 & 0 & 0 & 2 \\ -2 & -4 & 1 & 0 & 0 \\ -2 & -4 & 0 & 2 & 4 \\ -2 & -4 & 0 & 3 & 5 \end{pmatrix}$ and $\vec{b} = \begin{pmatrix} 5 \\ 0 \\ 7 \\ 8 \end{pmatrix}$.

(a) Solve the system $A\vec{x} = \vec{b}$ where A and \vec{b} are as above. Write your answer in parametric vector form for full credit.

(b) Write down a basis for $\text{Col}(A)$.

8. (4 points) Consider the following Markov chain.



(a) What is the transition matrix, P ?

$$P = \begin{pmatrix} & & \\ & & \\ & & \end{pmatrix}$$

(b) Use your transition matrix from part (a) to calculate the steady-state probability vector, \vec{q} . Show your work.

9. (3 points) Apply the Gram-Schmidt process to construct an orthogonal basis for $\text{Col}(A)$. Show your work.

$$A = \begin{pmatrix} 1 & 1 \\ 1 & 0 \\ 1 & 1 \end{pmatrix}$$

Do an LU-factorization.

10. (3 points) Construct the LU factorization of the matrix $A = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 2 & 2 & 3 & 0 \\ 4 & 4 & 5 & 0 \end{bmatrix}$. Clearly indicate matrices L and U .

Step 1: row reduce A to REF using only downwards row clearing operators (no row swaps!) (no row scaling!)

$$A = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 2 & 2 & 3 & 0 \\ 4 & 4 & 5 & 0 \end{bmatrix} \sim \begin{matrix} -2R_1 + R_2 \rightarrow \\ -4R_1 + R_3 \rightarrow \end{matrix} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 0 & 1 & -2 \\ 0 & 0 & 1 & -4 \end{bmatrix} \sim \begin{matrix} -1R_2 + R_3 \rightarrow \end{matrix} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 0 & 1 & -2 \\ 0 & 0 & 0 & -2 \end{bmatrix} = U$$

$$L = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 4 & 1 & 1 \end{bmatrix}$$

$$U = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 0 & 1 & -2 \\ 0 & 0 & 0 & -2 \end{bmatrix}$$

↑
switch the signs

when you row reduce A to U , get some E 's. this is.

$$E_3 E_2 E_1 A = U$$

$$A = (E_1^{-1} E_2^{-1} E_3^{-1}) U$$

11. (5 points) Compute Σ and V in the singular value decomposition of the matrix

$$A = \begin{bmatrix} 1 & 1 \\ 0 & -1 \\ 1 & 0 \end{bmatrix} = U \Sigma V^T$$

$$\Sigma = \begin{bmatrix} _ & 0 \\ 0 & _ \\ 0 & 0 \end{bmatrix} \quad V = \begin{bmatrix} _ & _ \\ _ & _ \end{bmatrix}$$

Next page!

11. (5 points) Compute Σ and V in the singular value decomposition of the matrix

Ⓢ!! and U .

$$A = \begin{bmatrix} 1 & 1 \\ 0 & -1 \\ 1 & 0 \end{bmatrix} = U\Sigma V^T$$

$$\Sigma = \begin{bmatrix} \sqrt{3} & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix} \quad V = \begin{bmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix}$$

bases for $\text{Col } A$ \downarrow \downarrow \downarrow
 basis $(\text{Col } A)^\perp$

$$U = \begin{bmatrix} \frac{2}{\sqrt{6}} & 0 & -\frac{1}{\sqrt{3}} \\ -\frac{1}{\sqrt{6}} & -\frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{6}} & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{3}} \end{bmatrix}$$

① Compute $A^T A$

$$\begin{bmatrix} 1 & 0 \\ 1 & -1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 0 & -1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$$

② Find $p(\lambda) = \det(A^T A - \lambda I)$

$$p(\lambda) = \lambda^2 - \text{tr}(A^T A)\lambda + \det(A^T A)$$

$$p(\lambda) = \lambda^2 - 4\lambda + 3 \\ = (\lambda - 3)(\lambda - 1) = 0$$

③ Find λ 's of $A^T A$

$$\lambda_1 = 3 \quad \sigma_1 = \sqrt{3} \\ \lambda_2 = 1 \quad \sigma_2 = 1$$

σ_i are the square roots of the eigenvalues of $A^T A$.

④ Get v_1, v_2 normalized orthogonal eigenvectors of $A^T A$.

$$A - \lambda I = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} - \begin{bmatrix} 3 & 0 \\ 0 & 3 \end{bmatrix} = \begin{bmatrix} -1 & 1 \\ 1 & -1 \end{bmatrix} \sim \begin{bmatrix} 1 & -1 \\ 0 & 0 \end{bmatrix} \quad \vec{x} = s \begin{bmatrix} 1 \\ 1 \end{bmatrix} \quad \Rightarrow v_1 = \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix}$$

\vec{v}_2 has to be orthogonal to \vec{v}_1
 \vec{v}_2 a unit vector.

or $v_2 = \begin{bmatrix} -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix}$
 also OK.

$$\textcircled{5} \quad u_1 = \frac{1}{\sigma_1} A v_1 = \frac{1}{\sqrt{3}} \begin{bmatrix} 1 & 1 \\ 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix} = \frac{1}{\sqrt{3}} \begin{bmatrix} \frac{2}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix} = \begin{bmatrix} \frac{2}{\sqrt{6}} \\ -\frac{1}{\sqrt{6}} \\ \frac{1}{\sqrt{6}} \end{bmatrix} = \vec{u}_1 \quad \checkmark$$

$$u_2 = \frac{1}{\sigma_2} A v_2 = \frac{1}{1} \begin{bmatrix} 1 & 1 \\ 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix} = \begin{bmatrix} 0 \\ -\frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \end{bmatrix} = \vec{u}_2 \quad \checkmark$$

to get \vec{u}_3 ?

$$\vec{x} = s \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix}$$

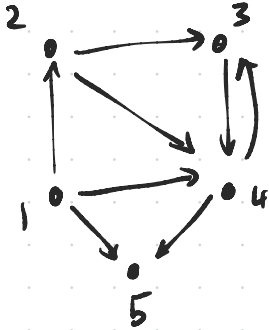
$$\sim \begin{bmatrix} 2 & 0 & 2 \\ 0 & 1 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}$$

Compute

$$\text{null of } \begin{bmatrix} u_1^T \\ u_2^T \end{bmatrix} = \begin{bmatrix} \frac{2}{\sqrt{6}} & -\frac{1}{\sqrt{6}} & \frac{1}{\sqrt{6}} \\ 0 & -\frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{bmatrix} \sim \begin{bmatrix} 2 & -1 & 1 \\ 0 & 1 & 1 \end{bmatrix}$$

Google matrix example

Step 1: Make P matrix



$$P = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ 1/3 & 0 & 0 & 0 & 0 \\ 0 & 1/2 & 0 & 1/2 & 0 \\ 1/3 & 1/2 & 1 & 0 & 0 \\ 1/3 & 0 & 0 & 1/2 & 1 \end{bmatrix}$$

Step 2: make the first adjustment

$$P^* = \begin{bmatrix} 0 & 0 & 0 & 0 & 1/5 \\ 1/3 & 0 & 0 & 0 & 1/5 \\ 0 & 1/2 & 0 & 1/2 & 1/5 \\ 1/3 & 1/2 & 1 & 0 & 1/5 \\ 1/3 & 0 & 0 & 1/2 & 1/5 \end{bmatrix}$$

Step 3: $G = 0.85 P^* + 0.15 K$ where $K = \begin{bmatrix} 1/5 & \dots & 1/5 \\ \vdots & & \vdots \\ 1/5 & \dots & 1/5 \end{bmatrix}$

ANS.

$$G = (0.85) \begin{bmatrix} 0 & 0 & 0 & 0 & 1/5 \\ 1/3 & 0 & 0 & 0 & 1/5 \\ 0 & 1/2 & 0 & 1/2 & 1/5 \\ 1/3 & 1/2 & 1 & 0 & 1/5 \\ 1/3 & 0 & 0 & 1/2 & 1/5 \end{bmatrix} + (0.15) \begin{bmatrix} 1/5 & 1/5 & 1/5 & 1/5 & 1/5 \\ 1/5 & 1/5 & 1/5 & 1/5 & 1/5 \\ 1/5 & 1/5 & 1/5 & 1/5 & 1/5 \\ 1/5 & 1/5 & 1/5 & 1/5 & 1/5 \\ 1/5 & 1/5 & 1/5 & 1/5 & 1/5 \end{bmatrix}$$

12. (5 points) Find matrices D and P to construct the orthogonal diagonalization of A . Show your work.

$$A = \begin{bmatrix} 4 & 3 \\ 3 & -4 \end{bmatrix} = PDP^T$$
$$D = \begin{bmatrix} _ & _ \\ _ & _ \end{bmatrix}, \quad P = \begin{bmatrix} _ & _ \\ _ & _ \end{bmatrix}$$